ABSTRACT

Title of Dissertation:	AFFINE PAVINGS OF HESSENBE IDEAL FIBERS					
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We define certain closed subvarieties of the flag variety, Hessenberg ideal fibers, and prove that they are paved by affines. Hessenberg ideal fibers are a natural generalization of Springer fibers. In type G_2 , we give explicit descriptions of all Hessenberg ideal fibers, study some of their geometric properties and use them to completely classify Tymoczko's dot actions of the Weyl group on the cohomology of regular semisimple Hessenberg varieties.

AFFINE PAVINGS OF HESSENBERG IDEAL FIBERS

by

Ke Xue

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Dedication

To my Lord and God Jesus Christ.

Acknowledgments

It is once said jokingly that graduate school is a lonely, disheartening existential purgatory, but that had been true for me in the literal sense. I entered it as a puffed-up scoundrel, and now am graduating as a normal human being capable of love. This thesis is a free gift from God, bestowed for the sake of all the people that made this transformation possible, and I am the least deserving of it among all.

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Chapter 1: Introduction

Let G be a connected reductive algebraic group over \mathbb{C} , B a Borel subgroup, Uthe unipotent radical of B, and let \mathfrak{g} , \mathfrak{b} and \mathfrak{u} denote their respective Lie algebras. A Hessenberg ideal is an $\mathrm{ad}(\mathfrak{b})$ -stable subspace I of \mathfrak{u} . Fix a nilpotent element $N \in \mathfrak{g}$ and a Hessenberg ideal I. The Hesseberg ideal fiber $\pi_I^{-1}(N)$ is defined to be the fiber over N of the following map,

$$\pi_I: G \times^B I \longrightarrow \mathfrak{g}$$
$$(g, X) \longmapsto g \cdot X$$

where $g \cdot X$ denotes the adjoint action $\operatorname{Ad}(g)(X)$. From this definition, it can be deduced that $\pi_I^{-1}(N)$ is a closed subvariety of the flag variety G/B when it is not empty, and that

$$\pi_I^{-1}(N) = \{ gB \mid g^{-1} \cdot N \in I \} \subset G/B.$$
(1.1)

When the Hessenberg ideal I is the biggest possible option \mathfrak{u} , by Equation 1.1, $\pi_{\mathfrak{u}}^{-1}(N) = \{ gB \mid g^{-1} \cdot N \in \mathfrak{u} \} = \{ \text{Borel subalgebras of } \mathfrak{g} \text{ that contain } N \}.$ In this case, our Hessenberg ideal fiber $\pi_{\mathfrak{u}}^{-1}(N)$ is exactly the Springer fiber \mathcal{B}_N as in De Concini et al. [1988]. In general, $\pi_I^{-1}(N)$ is a closed subvariety of \mathcal{B}_N .

The main theorem of this paper can be summarized as the following.

Theorem. Let G be a connected reductive algebraic group over \mathbb{C} whose Lie algebra has no simple component of type E_7 or E_8 . For any Hessenberg ideal $I \subset \mathfrak{u}$ and any nilpotent element $N \in \mathfrak{g}$, the Hessenberg ideal fiber $\pi_I^{-1}(N)$ is paved by affines whenever it is not empty. That is, we can decompose $\pi_I^{-1}(N)$ into a finite disjoint union of locally closed subvarieties each of which is an affine space.

In De Concini et al. [1988], de Concini, Lusztig and Procesi showed that Springer fibers for classical groups are paved by affines. The main theorem of this paper is a direct generalization of their result, and its proof is inspired by their arguments. Hessenberg ideal fibers (under different names) have already been considered by many authors (e.g. Fresse [2016], Ji & Precup [2019] and Sommers [2006]). Sommers [2006] pointed out that the image of π_I is the closure of a single nilpotent orbit, and the Hessenberg ideal fiber over an element of this orbit is a disjoint union of irreducible smooth varieties. Ji & Precup [2019] proved that Hessenberg ideal fibers for type A are paved by affines and gave a combinatorial formula for their cohomology groups. Most notably, Fresse [2016] generalized Springer fibers to certain closed subvarieties of any partial flag variety G/P and proved that they are paved by affines for the classical groups. In the case of the full flag variety G/B, Fresse [2016] [Theorem 1] implies that Hessenberg ideal fibers for the classical groups are paved by affines. Fresse's proof uses an explicit description of G/P as variety of partial flags and a type-by-type inspection for the classical groups. The proof of this paper is more conceptual and works for the exceptional types G_2 , F_4 and E_6 as well. In addition, it naturally leads to a way of computing the cell structures of

Hessenberg ideal fibers for low-rank G (see chapter 4).

The major motivation for studying Hessenberg ideal fibers is that knowledge of them can be used to classify Tymoczko's dot actions of the Weyl group W of G on the cohomology of regular semisimple Hessenberg varieties. Hessenberg ideal has a natural "dual" notion of Hessenberg subspace. A Hessenberg subspace is an $ad(\mathfrak{b})$ stable subspace M of \mathfrak{g} containing \mathfrak{b} . Let $y \in \mathfrak{g}$ be a regular semisimple element. The (regular semisimple) Hessenberg variety Hess(M, y) is defined to be the fiber over y of the following map

$$\pi_M: \ G \times^B M \longrightarrow \mathfrak{g}$$
$$(g, x) \longmapsto g \cdot x$$

where $g \cdot x$ denotes the adjoint action $\operatorname{Ad}(g)(x)$. The ordinary cohomology of Hess(M, y) with coefficient \mathbb{C} , $H^*(\operatorname{Hess}(M, y))$, is independent of the choice of the regular semisimple element y, and Tymoczko [2007] defined the dot action of Won $H^*(\operatorname{Hess}(M, y))$. The decomposition of $H^*(\operatorname{Hess}(M, y))$ into irreducible W representations is an interesting question in itself and a crucial ingredient of both the Shareshian-Wachs and the Stanley-Stembridge Conjectures. There is a very useful connection between the decomposition of $H^*(\operatorname{Hess}(M, y))$ and the knowledge of Hessenberg ideal fibers, which we briefly explain in the next paragraph. Readers are referred to chapter 5 for more details.

Firstly, there exists a natural one-one correspondence between Hessenberg subspaces and Hessenberg ideals (see chapter 5). Consider the maps $\pi_M : G \times^B M \longrightarrow \mathfrak{g}$ and $\pi_I: G \times^B I \longrightarrow \mathfrak{g}$ for a pair of Hessenberg subspace M and Hessenberg ideal I corresponding to each other. Let d and d^{\vee} denote the complex dimensions of $G \times^B M$ and $G \times^B I$ respectively and $\underline{\mathbb{C}}$ denote the constant sheaves on both spaces. We thus have two direct push-forward complexes $R\pi_{M*}\mathbb{C}[d]$ and $R\pi_{I*}\mathbb{C}[d^{\vee}]$. Let $G \times \mathbb{G}_m$ act on \mathfrak{g} with G acting via the adjoint action and \mathbb{G}_m acting by scaling. Then, by fixing a Killing form, we get an autoequivalence F (the Fourier-Sato transform) from the category $\operatorname{Perv}_{G \times \mathbb{G}_m}(\mathfrak{g})$ of $G \times \mathbb{G}_m$ -equivariant perverse sheaves on \mathfrak{g} to itself. We know that $F(R\pi_{M*}\underline{\mathbb{C}}[d]) = R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$ and that F maps simple summands of $R\pi_{M*}\mathbb{C}[d]$ to those of $R\pi_{I*}\mathbb{C}[d^{\vee}]$ bijectively. On the one hand, picking a regular semisimple element $y \in \mathfrak{g}$, we have $H^*(R\pi_{M*}\underline{\mathbb{C}}|_y) \cong H^*(\operatorname{Hess}(M, y))$ and that the decomposition of $R\pi_{M*}\mathbb{C}[d]$ into simple summands leads directly to the decomposition of $H^*(\text{Hess}(M, y))$ into irreducible W representations. On the other hand, picking any nilpotent element $N \in \mathfrak{g}$, we have $H^*(R\pi_{I*}\mathbb{C}|_N) \cong H^*(\pi_I^{-1}(N))$. Therefore, the knowledge of Hessenberg ideal fibers can help us determine the decomposition of $R\pi_{I*}\mathbb{C}[d^{\vee}]$ into simple summands, which in turn leads to the decompositions of $R\pi_{M*}\mathbb{C}[d]$ and of $H^*(\operatorname{Hess}(M, y))$. The detailed process for the ideas just outlined is carried out in chapter 5 where G is of type G_2 .

The remainder of the paper is organized as follows. Chapter 2 covers preliminary results used in the following chapter. In chapter 3 and 6, we prove the complete version of the main theorem stated above (Theorem 3.0.1). In chapter 4, we explicitly compute the cell structures of all Hessenberg ideal fibers for type G_2 and show that one of them has disconnected, un-equidimensional irreducible components (Theorem 4.4.1). In chapter 5, we use the results of chapter 4 to classify Tymoczko's dot actions on the cohomology of regular semisimple Hessenberg varieties for type G_2 (Theorem 5.3.2).

Chapter 2: Preliminaries

We state definitions and results that will be used later. In this chapter, except for Theorem 2.7.7, G is assumed to be a connected reductive algebraic group over \mathbb{C} , without any restriction on its Lie algebra. $B, U, \mathfrak{g}, \mathfrak{b}$ and \mathfrak{u} are the same as in the previous chapter.

2.1 Notation

Let B be the fixed Borel subgroup of G. Let $T \subset B$ be a fixed maximal torus with Lie algebra \mathfrak{t} and denote by W the Weyl group of G associated to T. Choose a representative $\dot{w} \in N_G(T)$ for each Weyl group element $w \in W = N_G(T)/T$. Let Φ^+ , Φ^- and Δ denote the positive, negative and simple roots associated to T and B. Let \mathfrak{g}_{α} denote the root space corresponding to $\alpha \in \Phi$. Write U for the unipotent radical of B, U^- for its opposite subgroup, \mathfrak{u} and \mathfrak{u}^- for their respective Lie algebras.

Given a standard parabolic subgroup P of G, we choose for it a specific Levi decomposition $P = LU_P$. U_P is the unipotent radical of P. The Levi factor L is determined in the following way. P corresponds to a unique subset $I \subset \Delta$ such that $P = BW_IB$, where W_I is the subgroup of W generated by the set of simple reflections $\{ s_{\alpha} \mid \alpha \in I \}$. Let $Z = (\bigcap_{\alpha \in I} \operatorname{Ker}(\alpha))^{\circ}$ and define $L = C_G(Z)$. The Lie algebra \mathfrak{l} of L has a root space decomposition $\mathfrak{l} = \mathfrak{t} \oplus (\bigoplus_{\alpha \in \Psi} \mathfrak{g}_{\alpha})$, in which Ψ is the subsystem of Φ spanned by I. The Weyl group W_L of L can be naturally identified with the subgroup W_I of W. We denote the Lie algebras of P and U_P by \mathfrak{p} and \mathfrak{u}_P respectively. $B \cap L$ is the Borel subgroup of L with Lie algebra $\mathfrak{b} \cap \mathfrak{l}$. Denote by $\Phi(\mathfrak{u}_P)$ and $\Phi(L)$ the subsets of roots so that

$$\mathfrak{u}_P = \bigoplus_{lpha \in \Phi(\mathfrak{u}_P)} \mathfrak{g}_{lpha} \quad ext{and} \quad \mathfrak{l} = \mathfrak{t} \oplus (\bigoplus_{lpha \in \Phi(L)} \mathfrak{g}_{lpha}).$$

In particular, \mathfrak{l} has triangular decomposition $\mathfrak{l} = \mathfrak{u}_L^- \oplus \mathfrak{t} \oplus \mathfrak{u}_L$ where

$$\mathfrak{u}_L = \bigoplus_{\alpha \in \Phi^+(L)} \mathfrak{g}_{\alpha} \quad \text{and} \quad \mathfrak{u}_L^- = \bigoplus_{\alpha \in \Phi^-(L)} \mathfrak{g}_{\alpha}$$

with $\Phi^{\pm}(L) = \Phi(L) \cap \Phi^{\pm}$. Let U_L denote the unipotent subgroup of G with Lie algebra \mathfrak{u}_L . Then, U_L is the unipotent radical of $B \cap L$, and $\mathfrak{u} = \mathfrak{u}_L \oplus \mathfrak{u}_P$.

Depending on context, we may use either G/B or \mathcal{B} to denote the flag variety. \mathcal{B} is viewed as the set of Borel subgroups of G (or equivalently, the set of Borel subalgebras of \mathfrak{g}). G/B is viewed as the set of left B-cosets. G acts naturally on the flag variety $\mathcal{B} = G/B$. The action on \mathcal{B} is conjugation on Borel subgroups (or adjoint action on Borel subalgebras), and the action on G/B is left multiplication on left B-cosets. They are different presentations of the same action. $g \cdot B \in \mathcal{B}$ stands for the Borel subgroup gBg^{-1} , $g \cdot \mathfrak{b} \in \mathcal{B}$ stands for the Borel subalgebra $\mathrm{Ad}(g)(\mathfrak{b})$, and $gB \in G/B$ stands for the left B-coset. They are the same point in the flag variety. These notational conventions are kept throughout the paper.

2.2 Hessenberg ideals

In what follows, we restate the definition of Hessenberg ideal and give a simple yet useful lemma about it.

Definition 2.2.1. A subspace $I \subset \mathfrak{u}$ is a Hessenberg ideal if it is stable under the adjoint action by \mathfrak{b} .

It follows easily from the definition that a Hessenberg ideal I is also stable under the adjoint action by B. We define two sets:

$$\begin{split} \mathscr{I} &= \{ \text{ subspaces } I \text{ of } \mathfrak{u} \mid I \text{ is } \operatorname{ad}(\mathfrak{b})\text{-stable } \}, \\ \mathscr{S} &= \{ \text{ subsets } S \subset \Phi^+ \mid \text{if } \beta \in S, \, \alpha \in \Phi^+ \text{ and } \beta + \alpha \in \Phi^+, \text{ then } \beta + \alpha \in S \}. \end{split}$$

Lemma 2.2.2. There is a one-to-one correspondence between \mathscr{I} and \mathscr{S} given by

$$I = \bigoplus_{\alpha \in S} \mathfrak{g}_{\alpha}$$

Proof. Straightforward.

If an ideal I corresponds to a set S as above, for any root $\alpha \in S$, we say that I has a root α and α is a root of I (or α belongs to I).

2.3 Affine pavings

Definition 2.3.1. A finite partition of a variety X into subsets is said to be a paving if the subsets in the partition can be indexed X_1, \ldots, X_n in such a way that $X_1 \amalg X_2 \amalg \cdots \amalg X_i$ is closed in X for $i = 1, \ldots, n$. A paving is affine if each X_i is

a finite disjoint union of affine spaces. In this case, we can alternatively say that X is paved by affines.

2.4 A brief roadmap

We sketch in this section a brief roadmap of the proof of the main theorem. For a Hessenberg ideal fiber $\pi_I^{-1}(N)$, we obtain a paving by intersecting it with a nice paving of the flag variety \mathcal{B} . For each piece in the paving of $\pi_I^{-1}(N)$, we consider its fixed-point subvariety by a certain one-dimensional torus. If the fixed-point subvariety is paved by affines, we are done. Otherwise we continue to decompose and take fixed-point sets until we reach something paved by affines. This process is accomplished by combining Lemma 2.4.1, Lemma 2.4.2 and Lemma 2.4.5.

Lemma 2.4.1. If a variety X has a paving $\{X_1, X_2, \ldots, X_n\}$ such that each X_i $(i = 1, 2, \ldots, n)$ is paved by affines, the same is true of X.

Proof. Straightforward.

Lemma 2.4.2. Let E be a connected smooth variety over \mathbb{C} with an algebraic \mathbb{C}^{\times} action. Assume that E can be covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes. Let $E^{\mathbb{C}^{\times}}$ denote the fixed-point subvariety and assume that it is nonempty, connected and smooth. Moreover, assume that $\lim_{t\to 0} t \cdot x \in E^{\mathbb{C}^{\times}}$ for every point $x \in E$, where $t \cdot x$ denotes the \mathbb{C}^{\times} -action. Let $Z \subset E$ be a \mathbb{C}^{\times} -stable smooth closed subvariety so that $Z^{\mathbb{C}^{\times}}$ is also smooth. Then if $Z^{\mathbb{C}^{\times}}$ is paved by affines, the same is true of Z.

The key to the proof of this lemma is Bass & Haboush [1985][Theorem 9.1], which is stated below for readers' convenience. **Theorem 2.4.3** (Bass & Haboush [1985], Theorem 9.1). Let G be a reductive group over \mathbb{C} acting on the affine scheme $X = \operatorname{Spec}(A)$. Let $X_0 = \operatorname{Spec}(A/I)$ be a closed subscheme of X. Assume:

- (1) X_0 is G-stable and contains all closed orbits.
- (2) There is a G-equivariant retraction $\pi: X \longrightarrow X_0$.
- (3) X_0 is a local complete intersection in X.

Then $\pi: X \longrightarrow X_0$ admits the structure of a *G*-vector bundle over X_0 .

The definition of local complete intersection can be found in Bass & Haboush [1985][section 8].

Fix an affine scheme $X = \operatorname{Spec}(A)$ and an ideal $I \subset A$. Define $A_0 = A/I$ and the closed subscheme $X_0 = \operatorname{Spec}(A_0)$ of X. Consider the A_0 -module $N = I/I^2$. Then the graded A_0 -algebra $\operatorname{gr}_I(A) = \bigoplus_{n \ge 0} I^n/I^{n+1}$ is generated by N in degree 1, and there is a canonical surjection of graded A_0 -algebras $\phi : \operatorname{Sym}_{A_0}(N) \longrightarrow \operatorname{gr}_I(A)$.

Definition 2.4.4. We say that X_0 is a local complete intersection in X if the following conditions are satisfied:

- (1) The A_0 -module $N = I/I^2$ is projective.
- (2) $\phi : \operatorname{Sym}_{A_0}(N) \longrightarrow \operatorname{gr}_I(A)$ is an isomorphism.

Now we can prove Lemma 2.4.2.

Proof. Since $\lim_{t\to 0} t \cdot x \in E^{\mathbb{C}^{\times}}$ for every $x \in E$, we can define a set-theoretic map $p: E \longrightarrow E^{\mathbb{C}^{\times}}$ by $p(x) = \lim_{t\to 0} t \cdot x$. It is clearly a \mathbb{C}^{\times} -equivariant retraction of

the inclusion $E^{\mathbb{C}^{\times}} \hookrightarrow E$. Since E is smooth and covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes, we can apply Białynicki-Birula [1973][Theorem 4.1] and deduce that $p: E \longrightarrow E^{\mathbb{C}^{\times}}$ is an affine fibration. Therefore, for every point $y \in E^{\mathbb{C}^{\times}}$, the fiber $p^{-1}(y)$ is an affine space with a \mathbb{C}^{\times} -action. y is the only fixed point within $p^{-1}(y)$ and every other point $x \in p^{-1}(y)$ is "flowed" to y by the \mathbb{C}^{\times} -action. Let $\pi: Z \longrightarrow Z^{\mathbb{C}^{\times}}$ denote the restriction of p to Z.

Assume $Z^{\mathbb{C}^{\times}}$ is paved by affines, we want to show the same is true of Z. Let $\{V_1, V_2, \ldots, V_m\}$ be an affine paving of $Z^{\mathbb{C}^{\times}}$. It suffices to show that $\{\pi^{-1}(V_1), \pi^{-1}(V_2), \ldots, \pi^{-1}(V_m)\}$ is an affine paving of Z. Let $W_i \cong \mathbb{A}^l$ be any affine piece lying in some V_j . Then it is enough to show that $Z_i \stackrel{\text{def}}{=} \pi^{-1}(W_i)$ is an affine space as well. For this purpose we apply Theorem 2.4.3 with $G = \mathbb{C}^{\times}$, $X = Z_i$ and $X_0 = W_i$. Next we show that all assumptions of Theorem 2.4.3 are satisfied.

Firstly, $G = \mathbb{C}^{\times}$ is reductive. $X_0 = W_i \cong \mathbb{A}^l$ is an affine space, hence certainly an affine scheme. Because Z is a \mathbb{C}^{\times} -stable closed subvariety of E, it is also covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes. Z is also smooth, so we can apply Białynicki-Birula [1973][Theorem 4.1] again and deduce that $\pi : Z \longrightarrow Z^{\mathbb{C}^{\times}}$ is an affine fibration. In particular, π is an affine morphism and so is its restriction $\pi|_{Z_i} : Z_i \longrightarrow W_i$. Now that $W_i \cong \mathbb{A}^l$ is an affine scheme, so is Z_i . Because Z_i is \mathbb{C}^{\times} -stable and $W_i = Z_i^{\mathbb{C}^{\times}}$, W_i is a closed subscheme of Z_i . Using the notation of Theorem 2.4.3, let $Z_i = \operatorname{Spec}(A)$ and $W_i = \operatorname{Spec}(A/I)$ for some affine \mathbb{C} -algebra A and ideal $I \subset A$.

Secondly, assumption (1) and (2) are clearly both satisfied.

Thirdly, for assumption (3), we need to show that both condition (1) and (2) of

Definition 2.4.4 are satisfied. Since π is an affine fibration, it is a smooth morphism and so is $\pi|_{Z_i} : Z_i \longrightarrow W_i$. Because $W_i \cong \mathbb{A}^l$ is a smooth variety, so is Z_i .

Now we know that $Z_i = \operatorname{Spec}(A)$ and $W_i = \operatorname{Spec}(A/I)$ are both smooth affine varieties and W_i is a closed subvariety of Z_i corresponding to the ideal I. By Hartshorne [1997][Chapter II, Theorem 8.17], $N = I/I^2$ is a locally free sheaf over $W_i = \operatorname{Spec}(A/I)$. Therefore $N = I/I^2$ is a projective A_0 -module ($A_0 = A/I$). Thus condition (1) of Definition 2.4.4 is satisfied.

For condition (2), we must show that $\phi : \operatorname{Sym}_{A_0}(N) \longrightarrow \operatorname{gr}_I(A)$ is an isomorphism. Because both sides of ϕ are graded A_0 -modules, it suffices to show that the localization $\phi_{\mathfrak{m}}$ is an isomorphism for each maximal ideal $\mathfrak{m} \supset I$. Without loss of generality, we may assume that (A, \mathfrak{m}) is a Noetherian local ring. Let d be the dimension of Z_i and k be the codimension of W_i in Z_i . Since Z_i and W_i are smooth varieties, both (A, \mathfrak{m}) and $(A/I, \mathfrak{m}/I)$ are regular local rings. By Matsumura [1980][p. 121, Theorem 36], there exists a regular system of parameters $\{a_1, a_2, \ldots, a_d\}$ of \mathfrak{m} so that a_1, a_2, \ldots, a_d is an A-regular sequence and $I = (a_1, a_2, \ldots, a_k)$. Therefore, the ideal I is generated by an A-regular sequence a_1, a_2, \ldots, a_k . By Matsumura [1980][p. 98, Theorem 27], a_1, a_2, \ldots, a_k is also an A-quasiregular sequence. By the definition of quasiregular sequence Matsumura [1980][p. 98], ϕ is an isomorphism.

Now that all assumptions of Theorem 2.4.3 are satisfied, we deduce that π_i : $Z_i \longrightarrow W_i$ admits the structure of a vector bundle. By the Quillen-Suslin theorem (that finitely generated projective modules over polynomial rings are free; see Lang [2002][p. 850, Theorem 3.7]), Z_i is an affine space and we have finished the proof. \Box The next paragraph is the outcome of several results by Białynicki-Birula and Iversen, stated in a way that fits the proof of the main theorem in chapter 3. Refer to Brosnan [2005][Theorem 3.2] for an alternative formulation and a short history of the results.

Let X be a smooth projective variety over \mathbb{C} with an algebraic \mathbb{C}^{\times} -action. The fixed-point set $X^{\mathbb{C}^{\times}}$ is smooth (Iversen [1972]). For each connected component Y of $X^{\mathbb{C}^{\times}}$, set $F_Y = \{ x \in X \mid \lim_{t \to 0} t \cdot x \in Y \}$ and define the map $\pi_Y : F_Y \longrightarrow Y$ by $\pi_Y(x) = \lim_{t \to 0} t \cdot x$. Then each F_Y is a locally closed \mathbb{C}^{\times} -stable smooth subvariety of X and $\pi_Y : F_Y \longrightarrow Y$ is a \mathbb{C}^{\times} -equivariant affine fibration (Białynicki-Birula [1973]). The partition of X into the subsets F_Y is a paving (Białynicki-Birula [1976]).

In addition, we have the following lemma about affine pavings.

Lemma 2.4.5. In the settings above, if Y is paved by affines, so is F_Y . As a consequence, if $X^{\mathbb{C}^{\times}}$ is paved by affines, the same is true of X.

Proof. When X is smooth projective with a \mathbb{C}^{\times} -action, it follows in particular that X is covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes (see Białynicki-Birula [1973][section 4]). Therefore, we can apply Białynicki-Birula [1973][Theorem 4.1] to X and deduce that $\pi_Y : F_Y \longrightarrow Y$ is a \mathbb{C}^{\times} -equivariant affine fibration. Now using Lemma 2.4.2 with $E = Z = F_Y$ and $E^{\mathbb{C}^{\times}} = Z^{\mathbb{C}^{\times}} = Y$, this lemma follows immediately.

2.5 A paving of the flag variety

As mentioned in the previous section, we can obtain a paving of any Hessenberg ideal fiber $\pi_I^{-1}(N)$ by intersecting it with a nice paving of the flag variety \mathcal{B} . Here we elaborate on this paving of \mathcal{B} and other related results.

Firstly, there is a well-known affine paving of the flag variety given by Schubert cells.

G has the Bruhat decomposition $G = \coprod_{w \in W} B\dot{w}B$. By abuse of notation, we also say that $G/B = \coprod_{w \in W} B\dot{w}B$. The latter equation is viewed as a partition of the flag variety G/B, in which $\dot{w}B$ is considered as a point in G/B and $B\dot{w}B$ the B-orbit of $\dot{w}B \in G/B$ (In the rest of this paper, a coset notation like $\dot{w}B$ always represents a point in G/B). The B-orbit $B\dot{w}B$ is a Schubert cell, and we denote it by X_w . In addition, we have the Schubert variety $\overline{X_w} = \coprod_{w' \leq w} X_{w'}$, where \leq denotes the (strong) Bruhat order on the Weyl group W (see Bernstein et al. [1973]).

For each $w \in W$, define $U^w = U \cap \dot{w}U^- \dot{w}^{-1}$. Its Lie algebra is $\mathfrak{u}^w = \bigoplus_{\alpha \in \Phi_w} \mathfrak{g}_\alpha$ where $\Phi_w = \{ \gamma \in \Phi^+ \mid w^{-1}(\gamma) \in \Phi^- \}$. \mathfrak{u}^w is naturally isomorphic to U^w by the *G*equivariant exponential map. By Humphreys [1981][section 28.4], X_w has a normal form $U^w \dot{w}B$. That is, U^w is isomorphic to X_w via the map $u \mapsto u\dot{w}B$. Therefore, we have natural isomorphisms $X_w \cong U^w \cong \mathfrak{u}^w$ and we know that $\dim X_w = \dim U^w =$ $\dim \mathfrak{u}^w = |\Phi_w| = l(w)$, where l(w) is the length of w in the Coxeter group W.

Secondly, let P be a standard parabolic of G. The finite set of P-orbits on G/B, after reordering, makes a paving of the flag variety. This is the paving with which we intersect the Hessenberg ideal fiber $\pi_I^{-1}(N)$. Next we elaborate on the

properties of these *P*-orbits.

Let $P = LU_P$ be the Levi decomposition. W_L denotes the Weyl group of L. Define $W^L = \{ v \in W \mid \Phi_v \subset \Phi(\mathfrak{u}_P) \}$. The elements of W^L form a set of minimal representatives for $W_L \setminus W$ in the following sense.

Lemma 2.5.1. Each $w \in W$ can be written uniquely as w = yv with $y \in W_L$ and $v \in W^L$ such that l(w) = l(y) + l(v).

Lemma 2.5.2. Let w = yv be the decomposition of $w \in W$ given above. Then $\Phi_w = y(\Phi_v) \amalg \Phi_y.$

The two lemmas above can be found in Precup [2013][section 3].

Let I be the unique subset of Δ corresponding to P. Note that there is a natural identification $W_L = W_I$, and that $P = BW_IB = BW_LB$. For any $y \in W_L$ and any $v \in W^L$, combining the equation l(yv) = l(y) + l(v) with Humphreys [1981][section 29.3, Lemma A] and arguing with a reduced word of y, it is not hard to show that $B\dot{y}B\dot{v}B = B\dot{y}\dot{v}B$. Equipped with this identity, we can give a better description of the P-orbits on G/B.

Lemma 2.5.3. There is a one-one correspondence between W^L and the set of Porbits on G/B. For each $v \in W^L$, the corresponding P-orbit is $P\dot{v}B$. Moreover, $P\dot{v}B$ is the disjoint union of certain Schubert cells:

$$P\dot{v}B = \prod_{y \in W_L} X_{yv} = \prod_{y \in W_L} U^{yv} \dot{y}\dot{v}B.$$

Proof. Since $P = BW_L B$, we have

$$P\dot{v}B = BW_LB\dot{v}B = \prod_{y\in W_L} B\dot{y}B\dot{v}B = \prod_{y\in W_L} B\dot{y}\dot{v}B = \prod_{y\in W_L} X_{yv} = \prod_{y\in W_L} U^{yv}\dot{y}\dot{v}B.$$

By Lemma 2.5.1, $W = W_L W^L = \{ yv \mid y \in W_L, v \in W^L \}$. Taking the disjoint union of $P\dot{v}B$ over all $v \in W^L$, we have

$$\prod_{v \in W^L} P\dot{v}B = \prod_{v \in W^L} \left(\prod_{y \in W_L} X_{yv} \right) = \prod_{w \in W} X_w = G/B.$$

Therefore, $v \mapsto P\dot{v}B$ is a one-one correspondence between W^L and the set of Porbits on G/B.

For simplicity of notation, we will use \mathcal{O}_v to denote PvB and \mathcal{O} an arbitrary P-orbit.

Next we investigate the fixed-point sets \mathcal{B}^Z and \mathcal{O}^Z where Z is the connected center of L.

From section 2.1, we know that $Z = (\bigcap_{\alpha \in I} \operatorname{Ker}(\alpha))^{\circ}$ is the connected center of L and $L = C_G(Z)$. There exists a one-parameter subgroup $\lambda : \mathbb{C}^{\times} \longrightarrow Z$ so that the λ -fixed-point set \mathcal{B}^{λ} and Z-fixed-point set \mathcal{B}^{Z} coincide. Every one-parameter subgroup in T is W-conjugate to a dominant one-parameter subgroup, so without loss of generality, we may assume

$$\langle \lambda, \alpha \rangle = 0 \ \forall \alpha \in \Phi(L) \text{ and } \langle \lambda, \gamma \rangle > 0 \ \forall \gamma \in \Phi(\mathfrak{u}_P),$$

where $\langle \lambda, \alpha \rangle$ is the natural pairing $Y(T) \times X(T) \longrightarrow \mathbb{Z}$ between the cocharacter and character group of T. Clearly $\mathcal{O}^Z = \mathcal{O}^{\lambda}$ for each P-orbit \mathcal{O} and $X_w^Z = X_w^{\lambda}$ for each Schubert cell X_w .

For each Schubert cell $X_w = U^w \dot{w} B$, λ acts on it by left multiplication. Hence, according to the natural isomorphisms $X_w \cong U^w \cong \mathfrak{u}^w$, λ acts on U^w by conjugation and on \mathfrak{u}^w by the adjoint action. Let w = yv be the decomposition as in Lemma 2.5.2, we have

$$\mathfrak{u}^w = igoplus_{lpha \in y(\Phi_v)} \mathfrak{g}_lpha \oplus igoplus_{lpha \in \Phi_y} \mathfrak{g}_lpha = \dot{y} \cdot \mathfrak{u}^v \oplus \mathfrak{u}^y.$$

Since $\dot{y} \cdot \mathfrak{u}^v \subset \mathfrak{u}_P$ and $\mathfrak{u}^y \subset \mathfrak{l}$, λ yields a \mathbb{C}^{\times} -action on \mathfrak{u}^w which has strictly positive weights on $\dot{y} \cdot \mathfrak{u}^v$ and fixes \mathfrak{u}^y . Therefore,

$$X_w^{\lambda} \cong (\mathfrak{u}^w)^{\lambda} = \mathfrak{u}^y \cong U^y.$$

Nowt

$$\mathcal{O}_{v}^{\lambda} = (\prod_{y \in W_{L}} X_{yv})^{\lambda} = \prod_{y \in W_{L}} (U^{yv} \dot{y} \dot{v} B)^{\lambda} = \prod_{y \in W_{L}} U^{y} \dot{y} \dot{v} B \cong \prod_{y \in W_{L}} U^{y} \dot{y} B_{L} = \mathcal{B}(L), \quad (2.1)$$

where $\mathcal{B}(L)$ is the flag variety of L and $B_L = L \cap \dot{v} \cdot B = L \cap \dot{v}B\dot{v}^{-1}$ is a Borel of L. Extrinsically, the isomorphism $\mathcal{O}_v^{\lambda} \cong \mathcal{B}(L)$ takes $u\dot{y}\dot{v}B$ to $u\dot{y}B_L$ $(u \in U^y)$; intrinsically, the isomorphism takes any Borel $B_0 \in \mathcal{O}_v^{\lambda}$ to $B_0 \cap L \in \mathcal{B}(L)$. If we assemble all these \mathcal{O}_v into \mathcal{B} , we get the following result. **Proposition 2.5.4.** Each connected component of $\mathcal{B}^Z = \mathcal{B}^\lambda$ takes the form of \mathcal{O}_v^λ for some $v \in W^L$. \mathcal{O}_v^λ is isomorphic to the flag variety $\mathcal{B}(L)$ of L and the isomorphism sends $B_0 \in \mathcal{B}^Z$ to $B_0 \cap L$ in $\mathcal{B}(L)$.

Moreover, we can show that each \mathcal{O}_v , considered as a variety with the \mathbb{C}^{\times} action from the left multiplication by λ , satisfies all the requirements for E as in
Lemma 2.4.2. To be precise:

Proposition 2.5.5. \mathcal{O}_v is a connected smooth variety with a \mathbb{C}^{\times} -action from the left multiplication by λ . \mathcal{O}_v can be covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes. Moreover, for every point $x \in \mathcal{O}_v$, $\lim_{t\to 0} \lambda(t) \cdot x \in \mathcal{O}_v^{\lambda}$, where $\lambda(t) \cdot x$ denotes the \mathbb{C}^{\times} -action via the left multiplication by λ .

Proof. Recall that \mathcal{O}_v is the *P*-orbit of $\dot{v}B$ in G/B, so it is a connected smooth variety. Since $\mathcal{O}_v = P\dot{v}B$ and $\lambda \subset P$, the left multiplication of λ on \mathcal{O}_v clearly stabilizes it.

Since $\mathcal{O}_v = \prod_{y \in W_L} X_{yv}$, each point $x \in \mathcal{O}_v$ lies in some Schubert cell X_{yv} . By the preceding analysis in this section, we know that $X_{yv} \cong \mathfrak{u}^{yv} = \dot{y} \cdot \mathfrak{u}^v \oplus \mathfrak{u}^y \cong$ $\dot{y} \cdot \mathfrak{u}^v \times X_{yv}^{\lambda}$. The projection onto the second factor $\operatorname{pr}_2 : X_{yv} \longrightarrow X_{yv}^{\lambda}$ gives a trivial vector bundle structure over X_{yv}^{λ} . Since $\dot{y} \cdot \mathfrak{u}^v \subset \mathfrak{u}_P$, the left multiplication by λ on X_{yv} yields a linear \mathbb{C}^{\times} -action on the fiber of pr_2 with strictly positive weights. Therefore, $\lim_{t\to 0} \lambda(t) \cdot x$ exists and lies in $X_{yv}^{\lambda} \subset \mathcal{O}_v^{\lambda}$.

Now it only remains to prove that \mathcal{O}_v can be covered by \mathbb{C}^{\times} -stable quasi-affine open subschemes. Each Schubert cell X_{yv} is clearly \mathbb{C}^{\times} -stable and affine, but they are not open subschemes except for the highest dimensional one. However, we can write down an explicit \mathbb{C}^{\times} -stable open affine cover of \mathcal{O}_v by using W_L -translates of the highest dimensional cell of \mathcal{O}_v . Next we elaborate on this claim.

Let $y_0 \in W_L$ be the unique element of maximal length. That is to say, $l(y_0) = \dim(L/L \cap B) = \dim \mathfrak{u}_L$. As a result, $\mathfrak{u}^{y_0} = \mathfrak{u}_L$ and $\dot{y}_0^{-1} \cdot \mathfrak{u}^{y_0} = \mathfrak{u}_L^-$. X_{y_0v} is the Schubert cell of the highest dimension in \mathcal{O}_v , hence an open affine subscheme. It is clearly \mathbb{C}^{\times} -stable. We claim that the set of W_L -translates of X_{y_0v} , $\{\dot{y}\dot{y}_0^{-1}X_{y_0v} \mid y \in W_L\}$, is a \mathbb{C}^{\times} -stable open affine cover of \mathcal{O}_v .

For \mathbb{C}^{\times} -stableness, consider the action of λ on $\dot{y}\dot{y}_{0}^{-1}X_{y_{0}v}$ by left multiplication. Since $yy_{0}^{-1} \in W_{L}$, for every $t \in \mathbb{C}^{\times}$, $\dot{y}_{0}\dot{y}^{-1}\lambda(t)\dot{y}\dot{y}_{0}^{-1} \in T$. Moreover, $X_{y_{0}v} = B\dot{y}_{0}\dot{v}B$ is clearly stable under left multiplication by T. Therefore, $\lambda(t)\dot{y}\dot{y}_{0}^{-1}X_{y_{0}v} = \dot{y}\dot{y}_{0}^{-1}(\dot{y}_{0}\dot{y}^{-1}\lambda(t)\dot{y}\dot{y}_{0}^{-1})X_{y_{0}v} = \dot{y}\dot{y}_{0}^{-1}X_{y_{0}v}$. Then $\dot{y}\dot{y}_{0}^{-1}X_{y_{0}v}$ is \mathbb{C}^{\times} -stable.

For the covering part, it suffices to show that $\dot{y}\dot{y}_0^{-1}X_{y_0v} \supset X_{yv}$ for every $y \in W_L$. Recall that $X_w = U^w \dot{w}B$, so we need to prove $\dot{y}\dot{y}_0^{-1}U^{y_0v}\dot{y}_0\dot{v}B \supset U^{yv}\dot{y}\dot{v}B$. The preceding inclusion relationship follows if we can show that $\dot{y}\dot{y}_0^{-1}U^{y_0v}\dot{y}_0 \supset U^{yv}\dot{y}$. Multiplying both sides by \dot{y}^{-1} , it remains to show the inclusion relationship of two unipotent subgroups of G: $\dot{y}_0^{-1}U^{y_0v}\dot{y}_0 \supset \dot{y}^{-1}U^{yv}\dot{y}$. As both are closed subgroups, the problem can be reduced to the level of Lie algebras: $\dot{y}_0^{-1} \cdot \mathfrak{u}^{yv} \supset \dot{y}^{-1} \cdot \mathfrak{u}^{yv}$.

Now recall that $\mathfrak{u}^{yv} = \dot{y} \cdot \mathfrak{u}^v \oplus \mathfrak{u}^y$ for every $y \in W_L$. Therefore, $\dot{y}_0^{-1} \cdot \mathfrak{u}^{y_0v} = \mathfrak{u}^v \oplus \dot{y}_0^{-1} \cdot \mathfrak{u}^{y_0}$ and $\dot{y}^{-1} \cdot \mathfrak{u}^{yv} = \mathfrak{u}^v \oplus \dot{y}^{-1} \cdot \mathfrak{u}^y$. Since $\dot{y}_0^{-1} \cdot \mathfrak{u}^{y_0} = \mathfrak{u}_L^- \supset \dot{y}^{-1} \cdot \mathfrak{u}^y$, the inclusion $\dot{y}_0^{-1} \cdot \mathfrak{u}^{y_0v} \supset \dot{y}^{-1} \cdot \mathfrak{u}^{yv}$ is clearly true and we have finished the proof. \Box

2.6 Associated parabolics

As stated in the previous section, we will intersect the Hessenberg ideal fiber $\pi_I^{-1}(N)$ with the *P*-orbit paving of G/B for some parabolic *P*. In fact, this *P* is always the associated parabolic of the nilpotent element *N*.

Let $N \in \mathfrak{g}$ be a nilpotent element. By the Jacobson-Morozov theorem, there exists a homomorphism of algebraic groups $\varphi : \operatorname{SL}_2(\mathbb{C}) \longrightarrow G$ such that $d\varphi \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} =$ N. Define a one-parameter subgroup $\lambda : \mathbb{C}^{\times} \longrightarrow G$ such that $\lambda(z) = \varphi \begin{pmatrix} z & 0 \\ 0 & z^{-1} \end{pmatrix}$ for all $z \in \mathbb{C}^{\times}$. λ decomposes \mathfrak{g} into a direct sum of weight spaces

$$\mathfrak{g}(i) = \{ X \in \mathfrak{g} \mid \lambda(z) \cdot X = z^i X \ \forall z \in \mathbb{C}^{\times} \}.$$

We know that $N \in \mathfrak{g}(2)$, and that $\mathfrak{g} = \bigoplus_{i \in \mathbb{Z}} \mathfrak{g}(i)$ where $[\mathfrak{g}(i), \mathfrak{g}(j)] \subset \mathfrak{g}(i+j)$ for all $i, j \in \mathbb{Z}$. Let L and P denote the connected algebraic subgroups of G whose Lie algebras are $\mathfrak{l} = \mathfrak{g}(0)$ and $\mathfrak{p} = \bigoplus_{i \geq 0} \mathfrak{g}(i)$. It is known that:

- (1) P is a parabolic subgroup depending only on N (not on the choice of φ).
- (2) $P = LU_P$ is a Levi decomposition, and its unipotent radical U_P has Lie algebra $\mathfrak{u}_P = \bigoplus_{i>0} \mathfrak{g}(i).$
- (3) The *P*-orbit of *N* in $\mathfrak{u}_P^{\geq 2} = \bigoplus_{i \geq 2} \mathfrak{g}(i)$ is dense.
- (4) The *L*-orbit of N in $\mathfrak{g}(2)$ is dense.
- (5) If N is distinguished, in the sense that it is not contained in any Levi subalgebra of a proper parabolic subalgebra of \mathfrak{g} , then $\mathfrak{g}(i) = 0$ for all odd i (see

Bala & Carter [1976]).

In the rest of this paper, for each nilpotent element N, the P and λ thus obtained are referred to as the associated parabolic of N and an associated oneparameter subgroup of N. The image of λ in G is usually denoted by D. Note that P as a subgroup of G is uniquely determined by N (see Carter [1985][p. 163, Proposition 5.7.1]) while λ depends of the choice of φ . Different choices of φ are conjugate by an element of $C_G(N)$, hence so are the λ 's.

It is worth pointing out that such an associated one-parameter subgroup λ is the same as the one mentioned in section 2.5, below Lemma 2.5.3. To be precise, we need to show that the λ associated to N via the Jacobson-Morozov theorem satisfies the following two requirements:

(1)
$$\langle \lambda, \alpha \rangle = 0 \ \forall \alpha \in \Phi(L) \text{ and } \langle \lambda, \gamma \rangle > 0 \ \forall \gamma \in \Phi(\mathfrak{u}_P).$$

(2) $\mathcal{B}^Z = \mathcal{B}^\lambda$ where Z is the connected center of L.

For (1), since λ decomposes \mathfrak{g} into weight spaces and $\mathfrak{l} = \mathfrak{g}(0), \mathfrak{u}_P = \bigoplus_{i>0} \mathfrak{g}(i)$, the requirement is clearly satisfied.

For (2), note that $L = C_G(Z) = C_G(\lambda)$. By Humphreys [1981][p. 141, section 22.4], both \mathcal{B}^Z and \mathcal{B}^{λ} are identical to the set $\{B_0 \in \mathcal{B} \mid L \cap B_0 \in \mathcal{B}(L)\}$. Hence the requirement is satisfied.

As a consequence, all the results of section 2.5 can be applied to the λ , L and P that are associated to N via the Jacobson-Morozov theorem.

2.7 Prehomogeneous vector spaces

Let M be a connected algebraic group over \mathbb{C} and V be a finite-dimensional vector space over \mathbb{C} with a rational M-action. V is said to be prehomogeneous if Vcontains a dense M-orbit V^0 . Pick an element $v \in V^0$.

Given a closed subgroup H in M and an H-stable vector subspace U of V, we construct a closed subvariety $X_U \subset M/H$ as follows: Set

$$M_U = \{ g \in M \mid g^{-1} \cdot v \in U \}.$$

Then M_U is stable under right multiplication by H and we set $X_U = M_U/H$. Clearly,

$$X_U = \{ gH \mid g \in M \text{ and } g^{-1} \cdot v \in U \}.$$

The following result can be found in De Concini et al. [1988] [Lemma 2.2].

Lemma 2.7.1.

- (1) When X_U is not empty, it is smooth and $\dim(X_U) = \dim(M/H) \dim(V/U)$.
- (2) The connected components of X_U are isomorphic, and M_v acts transitively on the set of them, where M_v is the stabilizer of v.

Remark 2.7.2. We use the quintuple notation (M, H, V, U, v) to denote all the information necessary to construct X_U . By abuse of notation, we also use the quintuple to denote the variety X_U itself. Equality such as $Y \cong (M, H, V, U, v)$ means the variety Y is isomorphic to the variety X_U constructed from the quintuple. Prehomogeneous vector space is the technical core of this paper. It is important for both the proof in chapter 3 and the explicit computation in chapter 4 and 6. In particular, we can use it to describe small pieces of the Hessenberg ideal fiber and their respective fixed-point subsets. Next we elaborate on this statement.

For a Hessenberg ideal I, let N and N' be conjugate nilpotent elements in the image of π_I . Then $\pi_I^{-1}(N)$ and $\pi_I^{-1}(N')$ are isomorphic while the associated parabolics P (of N) and P' (of N') are conjugate. Therefore, we may assume that the associated parabolic P of the nilpotent element N contains the pre-selected Borel subgroup B. This makes it very convenient to intersect $\pi_I^{-1}(N) = \{ gB \mid g^{-1} \cdot N \in I \}$ with various P-orbits on G/B.

Let L be the Levi factor of P and decompose the Weyl group $W = W_L W^L$. Let λ be an associated one-parameter subgroup of N. By Lemma 2.5.3, $\{\mathcal{O}_v \mid v \in W^L\}$ is the set of all P-orbits on G/B, and they can be ordered into a paving of the flag variety. Since $\pi_I^{-1}(N)$ is a closed subvariety of G/B, $\{\pi_I^{-1}(N) \cap \mathcal{O}_v \mid v \in W^L\}$ is a paving of $\pi_I^{-1}(N)$. In fact, each piece of the paving $\pi_I^{-1}(N) \cap \mathcal{O}_v$ is a variety constructed from some quintuple. So is its λ -fixed-point subset $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$.

Lemma 2.7.3. $\pi_I^{-1}(N) \cap \mathcal{O}_v = (P, P \cap \dot{v} \cdot B, \mathfrak{u}_P^{\geq 2}, \mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I, N).$

Proof. First we examine the validity of the quintuple. By section 2.6 (3), the *P*-orbit of N in $\mathfrak{u}_P^{\geq 2}$ is dense. Then all we need to check is that $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$ is $(P \cap \dot{v} \cdot B)$ -stable. Since the adjoint action of \dot{v} permutes the root spaces of \mathfrak{g} , $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$ still has a root space decomposition. To prove $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$ is $(P \cap \dot{v} \cdot B)$ -stable, it is enough to show the following: Let γ be a root of $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$ and δ be a root of $\mathfrak{p} \cap \dot{v} \cdot \mathfrak{b}$. If $\gamma + \delta$ is still a root, then it must be a root of $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$.

Now we prove the claim above. Let $\gamma = v(\alpha)$ so that α is a root of I and $v(\alpha)$ is a root of $\mathfrak{u}_P^{\geq 2}$. Let $\delta = v(\beta)$ so that β is a root of \mathfrak{b} and $v(\beta)$ is a root of \mathfrak{p} . If $\gamma + \delta = v(\alpha) + v(\beta) = v(\alpha + \beta)$ is a root, then so is $\alpha + \beta$. Since β is a root of \mathfrak{b} hence positive, and I is an ideal, $\alpha + \beta$ is a root of I as well. Recall that λ is the associated one-parameter subgroup of N which we have chosen to begin with. Then $\langle \lambda, \gamma + \delta \rangle = \langle \lambda, \gamma \rangle + \langle \lambda, \delta \rangle \geq 2$, because γ is a root of $\mathfrak{u}_P^{\geq 2}$ and δ is a root of \mathfrak{p} . Therefore $\gamma + \delta = v(\alpha + \beta)$ is a root of $\mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$.

Next we prove the equality. We know that $\mathcal{O}_v = P\dot{v}B$. The stabilizer of $\dot{v}B$ in P is $H \stackrel{\text{def}}{=} P \cap \dot{v} \cdot B$. For any $p \in P$, the whole coset pH, when acting on the point $\dot{v}B$, gives the same result $p\dot{v}B$. If $p\dot{v}B \in \pi_I^{-1}(N)$, by definition, $\dot{v}^{-1} \cdot p^{-1} \cdot N \in I \iff p^{-1} \cdot N \in \dot{v} \cdot I$. Since $p^{-1} \in P$ and $N \in \mathfrak{g}(2)$, we must have $p^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2}$. Therefore, $p^{-1} \cdot N \in \dot{v} \cdot I \iff p^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I$. In summary, $\pi_I^{-1}(N) \cap \mathcal{O}_v = \{ pH \mid p^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I \}$ and this is exactly $(P, P \cap \dot{v} \cdot B, \mathfrak{u}_P^{\geq 2}, \mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I, N)$.

Recall that λ acts on G/B by left multiplication. Since $N \in \mathfrak{g}(2)$, λ stabilizes $\pi_I^{-1}(N)$. Taking the λ -fixed-point subset of $\pi_I^{-1}(N) \cap \mathcal{O}_v$, we get $(\pi_I^{-1}(N) \cap \mathcal{O}_v)^{\lambda} = \pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$.

Lemma 2.7.4. $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} \cong (L, L \cap \dot{v} \cdot B, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N).$

Proof. Similar to the previous lemma, we begin by checking the validity of the quintuple. By section 2.6 (4), the *L*-orbit of N in $\mathfrak{g}(2)$ is dense. Then all we need

to check is that $\mathfrak{g}(2) \cap \dot{v} \cdot I$ is $(L \cap \dot{v} \cdot B)$ -stable. Still because of the root space decomposition of $\mathfrak{g}(2) \cap \dot{v} \cdot I$ and $\mathfrak{l} \cap \dot{v} \cdot \mathfrak{b}$, it is enough to show that:

Let γ be a root of $\mathfrak{g}(2) \cap \dot{v} \cdot I$ and β be a root of $\mathfrak{l} \cap \dot{v} \cdot \mathfrak{b}$. If $\gamma + \beta$ is still a root, it must be a root of $\mathfrak{g}(2) \cap \dot{v} \cdot I$.

The proof is almost verbatim the same as in the previous lemma.

Next we prove the equality. By Equation 2.1, we know that

$$\mathcal{O}_v^{\lambda} = \prod_{y \in W_L} U^y \dot{y} \dot{v} B \cong \prod_{y \in W_L} U^y \dot{y} (L \cap \dot{v} \cdot B) = \mathcal{B}(L) \cong L/L \cap \dot{v} \cdot B$$

and that the isomorphism in the middle takes $u\dot{y}\dot{v}B \in \mathcal{O}_v^{\lambda}$ to $u\dot{y}(L \cap \dot{v} \cdot B) \in \mathcal{B}(L)$ $(u \in U^y)$. If a point $u\dot{y}\dot{v}B \in \mathcal{O}_v^{\lambda}$ is also in $\pi_I^{-1}(N)$, by definition, $\dot{v}^{-1} \cdot \dot{y}^{-1} \cdot u^{-1} \cdot N \in I$ $I \iff \dot{y}^{-1} \cdot u^{-1} \cdot N \in \dot{v} \cdot I$. Since $\dot{y} \in W_L$ and $u \in U^y \subset L$ and $N \in \mathfrak{g}(2)$, we must have $\dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}(2)$. Therefore, $\dot{y}^{-1} \cdot u^{-1} \cdot N \in \dot{v} \cdot I \iff \dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}(2) \cap \dot{v} \cdot I$. In summary, $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} = \{ u\dot{y}\dot{v}B \mid \dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}(2) \cap \dot{v} \cdot I \}$. Mapped isomorphically into $\mathcal{B}(L)$, the previous set becomes $\{ u\dot{y}(L \cap \dot{v} \cdot B) \mid \dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}(2) \cap \dot{v} \cdot I \}$.

Combining the two lemmas above with Lemma 2.4.2, we can make an important step towards the proof of the main theorem. The following proposition is hinted at in the beginning of section 2.4.

Proposition 2.7.5. If $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ is paved by affines, so is $\pi_I^{-1}(N) \cap \mathcal{O}_v$.

Proof. By Proposition 2.5.5, \mathcal{O}_v satisfies all the requirements for E as in Lemma 2.4.2. By Lemma 2.7.1, Lemma 2.7.3 and Lemma 2.7.4, $\pi_I^{-1}(N) \cap \mathcal{O}_v$ satisfies all the requirements for Z as in Lemma 2.4.2. Now apply Lemma 2.4.2 with $E = \mathcal{O}_v$, $E^{\mathbb{C}^{\times}} = \mathcal{O}_v^{\lambda}, Z = \pi_I^{-1}(N) \cap \mathcal{O}_v$ and $Z^{\mathbb{C}^{\times}} = \pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$. We deduce that $\pi_I^{-1}(N) \cap \mathcal{O}_v$ is paved by affines if $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ is.

From the proof of Lemma 2.4.2, it is not hard to deduce the following corollary, which is useful in the computation in chapter 4.

Corollary 2.7.6. Let $q : \pi_I^{-1}(N) \cap \mathcal{O}_v \longrightarrow \pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ be the restriction of $p : \mathcal{O}_v \longrightarrow \mathcal{O}_v^{\lambda}$ and $r = \dim(\pi_I^{-1}(N) \cap \mathcal{O}_v) - \dim(\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda})$ be the relative dimension. We then have the following results:

(1) If $W \cong \mathbb{A}^l$ is an affine cell of $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$, then $q^{-1}(W)$ admits the structure of a rank r vector bundle over W. In particular, $q^{-1}(W) \cong \mathbb{A}^{l+r}$ and it is an affine cell of $\pi_I^{-1}(N) \cap \mathcal{O}_v$.

(2) If
$$r = 0$$
, $\pi_I^{-1}(N) \cap \mathcal{O}_v$ and $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ are the same subset of $\pi_I^{-1}(N)$.

The following is the fulcrum of the proof of the main theorem.

Theorem 2.7.7. Let G be a connected reductive algebraic group over \mathbb{C} whose Lie algebra has no simple component of type E_7 or E_8 . Let $N \in \mathfrak{g}$ be a distinguished nilpotent element and P be the associated parabolic of N. We may assume that Pcontains the pre-selected Borel subgroup B. Following the notation in section 2.6, let $P = LU_P$ be the Levi decomposition of P so that $\mathfrak{l} = \mathfrak{g}(0)$ and $\mathfrak{u}_P = \bigoplus_{i>0} \mathfrak{g}(i)$. $L \cap B$ is a Borel subgroup of L. Then for any $(L \cap B)$ -stable subspace $U \subset \mathfrak{g}(2)$, the variety $X_U = (L, L \cap B, \mathfrak{g}(2), U, N)$ is paved by affines whenever it is not empty. *Proof.* Note that $N \in \mathfrak{g}(2)$ and the *L*-orbit of *N* is dense in $\mathfrak{g}(2)$, so the *L*-module $\mathfrak{g}(2)$ is indeed prehomogeneous and the quintuple $(L, L \cap B, \mathfrak{g}(2), U, N)$ is valid.

Let D be the image in G of an associated one-parameter subgroup λ of N. By De Concini et al. [1988][section 3.7], since N is distinguished, there exists a P-orbit \mathcal{O} on \mathcal{B} such that $X_U \cong \mathcal{B}_{N,\mathcal{O}}^D$, where $\mathcal{B}_{N,\mathcal{O}}^D$ is the D-fixed-point set of the intersection $\mathcal{B}_N \cap \mathcal{O}$. Therefore, as long as we can prove that $\mathcal{B}_{N,\mathcal{O}}^D$ is paved by affines, we are done.

By De Concini et al. [1988][section 3.6], we know that $\mathcal{B}_N^D = \coprod_{\mathcal{O}} \mathcal{B}_{N,\mathcal{O}}^D$ and each piece is smooth projective and they do not meet each other. Therefore, if \mathcal{B}_N^D is paved by affines, so is each piece $\mathcal{B}_{N,\mathcal{O}}^D$.

Next we turn to look at \mathcal{B}_N^D . In this proof, for an arbitrary reductive Lie algebra \mathfrak{g}' , let $\mathcal{B}(\mathfrak{g}')$ denote the flag variety of a connected reductive group whose Lie algebra is \mathfrak{g}' . Let $\mathcal{B}_{N'}(\mathfrak{g}') = \{ \mathfrak{b}' \in \mathcal{B}(\mathfrak{g}') \mid N' \in \mathfrak{b}', \mathfrak{b}' \text{ is a Borel subalgebra of } \mathfrak{g}' \}$. Now come back to the group G and Lie algebra \mathfrak{g} we started with, and let $\mathfrak{g} \cong \mathfrak{z} \oplus (\bigoplus_{i=1}^m \mathfrak{g}_i)$ be the decomposition of \mathfrak{g} into a direct sum of its center \mathfrak{z} and simple components $\mathfrak{g}_1, \mathfrak{g}_2, \ldots, \mathfrak{g}_m$. Let N_i be the projection of N onto \mathfrak{g}_i for $i = 1, 2, \ldots, m$. Each N_i is a nilpotent element of \mathfrak{g}_i and N is distinguished in \mathfrak{g} if and only if each N_i is distinguished in \mathfrak{g}_i . It is not hard to show that $\mathcal{B}_N = \mathcal{B}_N(\mathfrak{g}) \cong \prod_{i=1}^m \mathcal{B}_{N_i}(\mathfrak{g}_i)$ (see Spaltenstein [2006][Chapter II, section 1.1]). Because each component \mathfrak{g}_i is an ideal of \mathfrak{g} , the adjoint action of D stabilizes \mathfrak{g}_i and induces an action on $\mathcal{B}(\mathfrak{g}_i)$. Since D stabilizes $\mathbb{C}N$, it also stabilizes each $\mathbb{C}N_i$. Then the adjoint action of D on \mathfrak{g} induces actions on $\mathcal{B}_N, \mathcal{B}_{N_1}(\mathfrak{g}_1), \mathcal{B}_{N_2}(\mathfrak{g}_2), \ldots, \mathcal{B}_{N_m}(\mathfrak{g}_m)$. Therefore, the isomorphism $\mathcal{B}_N \cong \prod_{i=1}^m \mathcal{B}_{N_i}(\mathfrak{g}_i)$ is *D*-equivariant and we have $\mathcal{B}_N^D \cong \prod_{i=1}^m \mathcal{B}_{N_i}^D(\mathfrak{g}_i)$.

Now it suffices to show that each $\mathcal{B}_{N_i}^D(\mathfrak{g}_i)$ is paved by affines. Since \mathfrak{g} is assumed to have no simple component of type E_7 or E_8 , each \mathfrak{g}_i is either classical or of type G_2 , F_4 or E_6 . In the classical case, let $s \in D$ be a semisimple element such that $\mathcal{B}_{N_i}^D(\mathfrak{g}_i) =$ $\mathcal{B}_{N_i}^s(\mathfrak{g}_i)$. By De Concini et al. [1988][Theorem 3.9], $\mathcal{B}_{N_i}^s(\mathfrak{g}_i)$ is paved by affines and so is $\mathcal{B}_{N_i}^D(\mathfrak{g}_i)$. In the other three cases, note that $\mathcal{B}_{N_i}^D(\mathfrak{g}_i) = \coprod_{\mathcal{O}}(\mathcal{B}_{N_i}^D(\mathfrak{g}_i) \cap \mathcal{O}),$ and for each P_i -orbit $\mathcal{O}, \mathcal{B}_{N_i}^D(\mathfrak{g}_i) \cap \mathcal{O}$ is constructed from some quintuple $(L_i, L_i \cap$ $B_i, \mathfrak{g}_i(2), U_i, N_i)$, where L_i is the Levi factor of the associated parabolic P_i of N_i (in \mathfrak{g}_i). Therefore, it suffices to prove that $(L_i, L_i \cap B_i, \mathfrak{g}_i(2), U_i, N_i)$ is paved by affines for a simple Lie algebra \mathfrak{g}_i of type G_2 , F_4 or E_6 . For type G_2 , the semisimple rank of L_i is at most 1 (see chapter 4), hence each nonempty $(L_i, L_i \cap B_i, \mathfrak{g}_i(2), U_i, N_i)$ is either a finite set of points or \mathbb{P}^1 , both of which are paved by affines. For type F_4 , only two of its four distinguished nilpotent orbits need to be carefully inspected. One of them has already been done in De Concini et al. [1988][section 4.2]. For the other orbit, a nonempty $(L_i, L_i \cap B_i, \mathfrak{g}_i(2), U_i, N_i)$ (with N_i from this nilpotent orbit) is one of the following: $\mathbb{P}^1 \times \mathbb{P}^1$, \mathbb{P}^1 (or disjoint union thereof), a finite set of points. For type E_6 , only one orbit needs inspection, for which a nonempty $(L_i, L_i \cap B_i, \mathfrak{g}_i(2), U_i, N_i)$ is one of: $\mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1$, a smooth rational surface, \mathbb{P}^1 (or disjoint union thereof), a finite set of points. Then knowledge of these very special varieties concludes the proof. The details for the F_4 and E_6 cases are given in chapter 6.
2.8 Undistinguished nilpotent elements

The proof of the main theorem when N is distinguished can be done by combining various results from section 2.7. When N is undistinguished, the classification of nilpotent orbits in Bala & Carter [1976] provides us a good way of reducing to the distinguished case. More specifically, we need the following result.

Proposition (Carter [1985][p. 172, Proposition 5.9.4]). There exists a minimal Levi subalgebra \mathfrak{m} of \mathfrak{g} containing N. N is a distinguished nilpotent element of \mathfrak{m} .

A Levi subalgebra \mathfrak{m} of \mathfrak{g} is the Lie algebra of the Levi factor of a parabolic subgroup of G. Miminal Levi subalgebra is minimal with respect to inclusion.

Next we describe how to find a minimal Levi subalgebra (and its corresponding Levi subgroup) that contains N. The following results are taken from Carter [1985][p. 156, Proposition 5.5.9; p. 172, Proposition 5.9.4].

For any nilpotent element N, let λ be an associated one-parameter subgroup (see section 2.6) and D be the image of λ in G. Let $F = C_G^{\circ}(N)$ be the connected centralizer of N. Let R be the unipotent radical of F and $C = C_F(D)$. We know that:

- (1) F = RC and $R \cap C = 1$.
- (2) C is a connected reductive group.

Let S be a maximal torus of C and let \mathfrak{s} be the Lie algebra of S. Set $\mathfrak{m} = C_{\mathfrak{g}}(\mathfrak{s})$ and $M = C_G(S)$. Then \mathfrak{m} is a minimal Levi subalgebra that contains N. M is the corresponding Levi subgroup of \mathfrak{m} and N is a distinguished nilpotent element of \mathfrak{m} . In particular, when N is distinguished, S is the connected center of G and the minimal Levi subalgebra that contains N is \mathfrak{g} itself.

Note that $S \subset C_F(D)$, so S and D commute with each other. D acts on N with weight 2 while S centralizes N. Therefore S and D have at most finite intersection. Choose a maximal torus T that contains both S and D and pick a Borel $B \supset T$ so that the associated parabolic P of N is standard. Since $B \supset T \supset S$, $M \cap B$ is a Borel subgroup of M (Humphreys [1981][section 22.4]). Let $P = LU_P$ be the Levi decomposition and let $\mu : \mathbb{C}^{\times} \longrightarrow S$ be a one-parameter subgroup so that the μ -fixed points and S-fixed points on \mathcal{B} coincide.

The groups λ , D, S, M, T, B, P, L and μ described above will be used in the proof of the main theorem when N is an undistinguished nilpotent element.

Chapter 3: Proof of the Main Theorem

In this chapter we prove the main theorem using various results from chapter 2.

Theorem 3.0.1. Let G be a connected reductive algebraic group over \mathbb{C} whose Lie algebra has no simple component of type E_7 or E_8 . For any Hessenberg ideal $I \subset \mathfrak{u}$ and any nilpotent element $N \in \mathfrak{g}$, the Hessenberg ideal fiber $\pi_I^{-1}(N)$ is paved by affines whenever it is not empty.

Proof. For any nilpotent element N, let P be the associated parabolic and λ be an associated one-parameter subgroup of N. $P = LU_P$ is the Levi decomposition and $W = W_L W^L$. Because { $\pi_I^{-1}(N) \cap \mathcal{O}_v \mid v \in W^L$ } is a paving of $\pi_I^{-1}(N)$, by Lemma 2.4.1, it is enough to show that each nonempty piece $\pi_I^{-1}(N) \cap \mathcal{O}_v$ is paved by affines. By Proposition 2.7.5, it suffices to show that each nonempty $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ is paved by affines. We accomplish this task in two different ways, depending on whether N is distinguished or undistinguished.

For any nilpotent N, by Lemma 2.7.4, $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} \cong (L, L \cap \dot{v} \cdot B, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N)$. Because $v \in W^L$, $L \cap \dot{v} \cdot B = L \cap B$ (see Lemma 4.2.1). Then $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} \cong (L, L \cap B, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N)$.

If N is distinguished, by Theorem 2.7.7, $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} \cong (L, L \cap B, \mathfrak{g}(2), \mathfrak{g}(2) \cap \mathcal{O}_v^{\lambda})$

 $\dot{v} \cdot I, N$ is paved by affines, and we are done.

If N is undistinguished, take all the groups λ , D, S, M, T, B, P, L and μ associated to N as in section 2.8. For simplicity of notation, we drop the subscript v and use \mathcal{O} to denote any P-orbit on G/B. Now we show that $\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda}$ is paved by affines by making use of the S-action on it.

Since S and D act on the flag variety G/B by left multiplication, the two actions commute with each other. Because $S \subset C_G^{\circ}(N)$, it stabilizes $\pi_I^{-1}(N)$; because S lies in T and commutes with D, it stabilizes \mathcal{O}^{λ} . Therefore, S stabilizes $\pi_I^{-1}(N) \cap$ \mathcal{O}^{λ} and $(\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda})^S = (\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda})^{\mu}$. Lemma 2.7.4 and Lemma 2.7.1 imply that $\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda}$ is smooth projective. Then we can apply the Lemma 2.4.5 to $\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda}$ with the μ -action. In particular, we deduce that:

The fixed-point set $(\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda})^{\mu}$ is the disjoint union of its connected components, each of which is smooth projective. Moreover, if every connected component of $(\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda})^{\mu}$ is paved by affines, the same is true of $\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda}$.

Let $\mathscr{P}(D,S)$ be the set of connected components of $(\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda})^{\mu}$ when \mathcal{O} ranges over all *P*-orbits on G/B. We want to show that every variety in $\mathscr{P}(D,S)$ is paved by affines. The key lies in viewing the set $\mathscr{P}(D,S)$ in a different way.

Consider the fixed-point variety $\pi_I^{-1}(N)^{D,S}$ by both D and S, and let \mathscr{R} be the set of connected components of $\pi_I^{-1}(N)^{D,S}$. For each $\pi_I^{-1}(N) \cap \mathcal{O}^{\lambda}$, it is a smooth projective closed subvariety of G/B. The intersection of two different pieces $(\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}) \bigcap (\pi_I^{-1}(N) \cap \mathcal{O}_u^{\lambda})$ is empty, because the two P-orbits \mathcal{O}_v and \mathcal{O}_u do not meet each other. Therefore, the elements of $\mathscr{P}(D,S)$ have to be exactly all connnect components of $\pi_I^{-1}(N)^{D,S}$. That is, $\mathscr{P}(D,S) = \mathscr{R}$. Now we consider $\pi_I^{-1}(N)^{D,S}$ in a different manner.

Let DS be the product group of D and S. It is a toral subgroup of T. Then $\pi_I^{-1}(N)^{D,S} = \pi_I^{-1}(N)^{DS}$. Since $L \cap M = C_G(D) \cap C_G(S) = C_G(DS)$, $L \cap M$ is a Levi subgroup of G. Let Q be the subgroup of G generated by $L \cap M$ and B, then Q is the standard parabolic of which $L \cap M$ is a Levi factor. On the other hand, $L \cap M = C_G(D) \cap M = C_M(D)$. Because $D \subset M$, $L \cap M$ is a Levi subgroup of M. By the definition $M = C_G(S)$ and Collingwood & McGovern [1993][Lemma 3.4.4], it is easy to show that the homomorphism $\varphi : \operatorname{SL}_2(\mathbb{C}) \longrightarrow G$ associated to N by the Jacobson-Morozov theorem factors through the subgroup M of G. Therefore, $L \cap M = C_M(D)$ is exactly the Levi subgroup of the unique parabolic subgroup of M associated to $N \in \mathfrak{m}$. Then we know that $\mathfrak{l} \cap \mathfrak{m} = \mathfrak{g}_M(0), N \in \mathfrak{g}_M(2)$ and that the $(L \cap M)$ -orbit of N in $\mathfrak{g}_M(2)$ is dense. Here $\mathfrak{m} = \bigoplus_{i \in \mathbb{Z}} \mathfrak{g}_M(i)$ is the weight space decomposition of \mathfrak{m} with respect to D.

Since $L \cap M$ is the Levi factor of the standard parabolic subgroup Q of G, we can decompose the Weyl group $W = W_{L \cap M} W^{L \cap M}$. For each $v \in W^{L \cap M}$, let \mathscr{O}_v be the corresponding Q-orbit on G/B. Then

$$\pi_{I}^{-1}(N) \cap \mathscr{O}_{v}^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{yv} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{y} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} \dot{v} B)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod_{y \in W_{L \cap M}} U^{y} \dot{v} b)^{DS} = \pi_{I}^{-1}(N) \cap (\prod$$

For any $u\dot{y}\dot{v}B \in U^y\dot{y}\dot{v}B$, it lies in $\pi_I^{-1}(N)$ whenever $\dot{v}^{-1} \cdot \dot{y}^{-1} \cdot u^{-1} \cdot N \in I \iff \dot{y}^{-1} \cdot u^{-1} \cdot N \in \dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}_M(2) \cap \dot{v} \cdot I$. The last equivalent condition is due to the fact that $u\dot{y} \in L \cap M = C_M(D)$ and $N \in \mathfrak{g}_M(2)$. Let $B_{L \cap M} = (L \cap M) \cap \dot{v} \cdot B$. It is a Borel subgroup of $L \cap M$. The natural isomorphism from $(\coprod_{y \in W_{L \cap M}} U^y \dot{y} \dot{v}B)$

to the flag variety $\mathcal{B}(L \cap M)$ takes $u\dot{y}\dot{v}B$ to $u\dot{y}B_{L\cap M}$. Under this isomorphism, $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS} \text{ can be identified with } \{ u\dot{y}B_{L\cap M} \mid \dot{y}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{g}_M(2) \cap \dot{v} \cdot I \}, \text{ which } i \in \mathfrak{g}_M(2) \cap \dot{v} \cdot I \}$ is exactly the quintuple $(L \cap M, B_{L \cap M}, \mathfrak{g}_M(2), \mathfrak{g}_M(2) \cap \dot{v} \cdot I, N)$. Because $v \in W^{L \cap M}$, we have $B_{L\cap M} = (L \cap M) \cap (M \cap B)$ (see Lemma 4.2.1). Because $M = C_G(S)$ is a Levi subgroup of G, its Dynkin diagram is obtained from that of G by removing certain nodes. Therefore, M is also a connected reductive algebraic group whose Lie algebra has no simple component of type E_7 or E_8 . Now apply Theorem 2.7.7 to the group M, its Borel subgroup $M \cap B$, the distinguished nilpotent element $N \in \mathfrak{m}$ and the quintuple $(L \cap M, B_{L \cap M}, \mathfrak{g}_M(2), \mathfrak{g}_M(2) \cap \dot{v} \cdot I, N)$, and we deduce that $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS} \cong (L \cap M, B_{L \cap M}, \mathfrak{g}_M(2), \mathfrak{g}_M(2) \cap \dot{v} \cdot I, N)$ is paved by affines. By Lemma 2.7.4 and Lemma 2.7.1, $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS}$ is smooth projective. Therefore it is a finite disjoint union of connected components from $\mathscr{R} = \mathscr{P}(D,S)$. Since $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS}$ is paved by affines, so is every one of its connected components. Because the collection of $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS}$ for different orbits \mathscr{O}_v cover $\pi_I^{-1}(N)^{DS}$, every connected component from $\mathscr{R} = \mathscr{P}(D,S)$ belongs to some $\pi_I^{-1}(N) \cap \mathscr{O}_v^{DS}$, hence has to be paved by affines as well. Then we have finished the proof.

Chapter 4: Type G_2

Throughout this chapter, let G be a connected algebraic group over \mathbb{C} of type G_2 . For every Hessenberg ideal fiber $\pi_I^{-1}(N)$, we explicitly describe each cell of $\pi_I^{-1}(N)$ as an affine subspace of some Schubert cell of G/B. Various geometric properties of Hessenberg ideal fibers can be deduced from these explicit cell structures. In particular, Theorem 4.4.1 shows that the irreducible components of $\pi_I^{-1}(N)$ are not always of the same dimension.

4.1 Some structures of G_2

First we collect some well-known results about G_2 that are relevent to our computation.

Fix a Borel subgroup B of G and choose a maximal torus $T \subset B$. Let α and β be the short and long simple roots respectively. The root system of G_2 is shown in Figure 4.1. The labeled arrows correspond to all the positive roots. We see that all the roots of G_2 have only two different lengths, and we call them short roots and long roots respectively.

There is a natural partial order on the set of positive roots: $\gamma \leq \delta$ if $\delta - \gamma$ is a linear combination of α and β with nonnegative coefficients.



Figure 4.1: Root system of G_2

Define $I_{\gamma} = \bigoplus_{\delta \geq \gamma} \mathfrak{g}_{\delta}$ for every $\gamma \in \Phi^+$, $I_{\alpha,\beta} = \mathfrak{u}$ and $I_{\emptyset} = (0)$. It is clear that these are all the Hessenberg ideals of G_2 . There is a natural partial order on the set of Hessenberg ideals by inclusion.

Let $E \cong \mathbb{R}^2$ be the real vector space that the root system of G_2 spans. We view E as the plane that contains all the arrows in Figure 4.1. Let $s = s_{\alpha}$ and $t = s_{\beta}$ be the reflections of E associated to the simple roots α and β respectively. Note that s is the reflection about the line through the arrow $2\beta + 3\alpha$ and t is the reflection about the line through the arrow $\beta + 2\alpha$. Let r = st and it is a rotation of E in the counterclockwise direction for 60 degrees. Let W be the Weyl group of G_2 and we have the following presentation of W:

$$W = \langle s, t | s^2 = t^2 = (st)^6 = e \rangle,$$

where e is the unit element of W. Clearly, $W \cong D_6$.

The rest of this section consists of several results that can be easily proved by knowledge of the Chevalley groups. They are true for all connected simple algebraic groups over \mathbb{C} .

For any root $\gamma \in \Phi$, let X_{γ} be the 1-dimensional unipotent subgroup of Gwhose Lie algebra is the root space \mathfrak{g}_{γ} . Let $x_{\gamma} : \mathbb{C} \longrightarrow X_{\gamma}$ be the group isomorphism defined via the exponential map and the choice of a Chevalley basis element in \mathfrak{g}_{γ} . For each positive root γ , choose a nonzero vector $E_{\gamma} \in \mathfrak{g}_{\gamma}$. Let $E_{-\gamma}$ be the unique vector in $\mathfrak{g}_{-\gamma}$ so that $\{E_{\gamma}, [E_{\gamma}, E_{-\gamma}], E_{-\gamma}\}$ is an \mathfrak{sl}_2 -triple. Let $H_{\gamma} = [E_{\gamma}, E_{-\gamma}]$.

Lemma 4.1.1. For any two roots γ and δ , there exist nonzero complex numbers c_1, c_2, \ldots, c_q depending only on γ, δ and G such that

$$x_{\gamma}(z) \cdot E_{\delta} = E_{\delta} + \sum_{n=1}^{q} c_n z^n E_{\delta+n\gamma}$$
 for any $z \in \mathbb{C}$.

 $x_{\gamma}(z) \cdot E_{\delta}$ is the adjoint action and $\delta + q\gamma$ is the last root in the γ -string that goes through δ .

Lemma 4.1.2. For any two roots γ and δ such that $\gamma + \delta$ is not in $\Phi \cup \{0\}$,

$$x_{\gamma}(z)x_{\delta}(z') = x_{\delta}(z')x_{\gamma}(z)$$
 for any $z, z' \in \mathbb{C}$.

That is, the two groups X_{γ} and X_{δ} commute with each other.

Lemma 4.1.3. For any $w \in W$ and $\gamma \in \Phi$, there exists a nonzero complex number c such that

$$\dot{w}x_{\gamma}(z)\dot{w}^{-1} = x_{w(\gamma)}(cz)$$
 for any $z \in \mathbb{C}$.

Lemma 4.1.4. For any $w \in W$, the following equality of sets is also an isomorphism

of algebraic varieties.

$$U^w = \prod_{\gamma \in \Phi_w} X_{\gamma},$$

in which factors on the right hand side are multiplied with respect to a fixed order of roots in Φ_w . Moreover, if $\gamma_1 + \gamma_2$ is not in $\Phi \cup \{0\}$ for any two roots $\gamma_1, \gamma_2 \in \Phi_w$, factors can be interchanged freely without changeing their product.

4.2 Outline of the algorithm

In this section, we outline the algorithm of the computation for the cell structures of all Hessenberg ideal fibers. The idea comes directly from the proof of Theorem 3.0.1. If N is the trivial nilpotent orbit $\{0\}$, then $\pi_I^{-1}(0) = G/B$, which is paved by the Schubert cells. We therefore ignore this case and only compute $\pi_I^{-1}(N)$ for N from a nontrivial nilpotent orbit.

Note that in the presentation of G_2 in section 4.1, we have chosen a Borel subgroup B and a maximal torus T to begin with. Therefore, for each nontrivial nilpotent orbit, we now have to first pick a representative N so that its associated parabolic P is standard. Let λ be an associated one-parameter subgroup of N, $P = LU_P$ the Levi decomposition, and $W = W_L W^L$ as in Lemma 2.5.1. For each $v \in W^L$, let \mathcal{O}_v be the P-orbit corresponding to v. For any Hessenberg ideal I, by Lemma 2.7.3 and Lemma 2.7.4, we have

$$\pi_I^{-1}(N) \cap \mathcal{O}_v = (P, P \cap \dot{v} \cdot B, \mathfrak{u}_P^{\geq 2}, \mathfrak{u}_P^{\geq 2} \cap \dot{v} \cdot I, N),$$

$$\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda} \cong (L, L \cap \dot{v} \cdot B, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N).$$

Clearly $\pi_I^{-1}(N) \cap \mathcal{O}_v$ and $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ are empty or nonempty at the same time. In the case of type G_2 , for every nontrivial nilpotent orbit, L has semisimple rank at most 1 and $\mathfrak{g}(2)$ is always of small dimension. Therefore it is easy to check whether $\pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$ is empty or not. To simplify notation, set $P(N, I, v) = \pi_I^{-1}(N) \cap \mathcal{O}_v$ and $L(N, I, v) = \pi_I^{-1}(N) \cap \mathcal{O}_v^{\lambda}$.

For any two Hessenberg ideals $J \subset I$, it is obvious from definition that $L(N, J, v) \subset L(N, I, v)$ and $P(N, J, v) \subset P(N, I, v)$. This simple observation is very useful in telling which L(N, I, v) is nonempty. In fact, in the case of type G_2 , when $\dim(I/J) = 1$, it happens quite often that the cells of P(N, J, v) are still cells of P(N, I, v) (there are exceptions).

According to Bala & Carter [1976][p. 6], G_2 has 4 nontrivial nilpotent orbits, denoted by A_1 , \tilde{A}_1 , $G_2(a_1)$ and G_2 . They are ordered in increasing dimensions. Our algorithm is the following:

- (1) Starting with the orbit A_1 , apply steps (2) to (5). Then repeat the same process for \tilde{A}_1 , $G_2(a_1)$ and G_2 in that order.
- (2) For each nontrivial nilpotent orbit, choose a representative N so that its associated parabolic P is standard.
- (3) Fixing the N, compute π_I⁻¹(N) for all nonzero Hessenberg ideals ranging from the smallest I_{2β+3α} to the biggest I_{α,β} by the next two steps.
- (4) For each Hessenberg ideal I, find all $v \in W^L$ so that $L(N, I, v) \neq \emptyset$.

(5) For each v obtained from step (4), compute the cell structure of P(N, I, v) explicitly.

Note that when I is the zero Hessenberg ideal I_{\emptyset} , $\pi_I^{-1}(0) \cong G/B$ is the only nonempty Hessenberg ideal fiber, so we omit it from the algorithm.

The following lemma will be useful in our computation. It is true for any connected reductive algebraic group over \mathbb{C} .

Lemma 4.2.1. Let P be a standard parabolic of G, and $P = LU_P$ be its Levi decomposition. $W = W_L W^L$. For any $v \in W^L$, we have the following:

- (1) $\mathfrak{p} \cap \dot{v} \cdot \mathfrak{b} = \mathfrak{t} \oplus (\bigoplus_{\gamma \in \Phi^+ \setminus \Phi_v} \mathfrak{g}_{\gamma}).$
- (2) $L \cap \dot{v} \cdot B = L \cap B$.
- (3) $\dim(P/P \cap \dot{v} \cdot B) = |\Phi^{-}(L)| + |\Phi_{v}|.$

Proof. Straightforward from the definition of W^L and Φ_v .

4.3 Computation

As mentioned in algorithm step (1), we split the computation into four cases, one for each nontrivial nilpotent orbit.

4.3.1 The case of A_1

First we choose a nice representative N that satisfies the requirement in step (2), and describe its associated parabolic P, associated one-parameter subgroup λ , the Levi subgroup L of P, $\mathfrak{g}(2)$, $\mathfrak{u}_{P}^{\geq 2}$ and the decomposition $W = W_{L}W^{L}$. According to Bala & Carter [1976], " A_1 " represents the undistinguished nilpotent orbit of G_2 every element of which lies in a minimal Levi subalgebra of type A_1 . For a suitable representative of the orbit A_1 , the root system of its minimal Levi subalgebra consists of a pair of opposite long roots of G_2 . $N = E_{2\beta+3\alpha}$ is a representative satisfying the requirement of step (2). We use N to denote $E_{2\beta+3\alpha}$ in this case for the sake of simplicity.

Next we justify the claim briefly. $N = E_{2\beta+3\alpha}$ is a regular nilpotent element of the Levi subalgebra $\mathfrak{m} = \mathfrak{t} \oplus \mathfrak{g}_{-2\beta-3\alpha} \oplus \mathfrak{g}_{2\beta+3\alpha}$, so it belongs to the orbit A_1 . The more subtle part is to show that the unique associated parabolic of N is standard. For this, it suffices to find an \mathfrak{sl}_2 -triple $\{N, H, Y\}$ so that $H \in \mathfrak{t}$ and $\alpha(H)$, $\beta(H) \geq 0$. Clearly, $\{E_{2\beta+3\alpha}, H_{2\beta+3\alpha}, E_{-2\beta-3\alpha}\}$ is such an \mathfrak{sl}_2 -triple. In this case, $\alpha(H_{2\beta+3\alpha}) = 0$ and $\beta(H_{2\beta+3\alpha}) = 1$ (these two numbers are always the same as the weights of α and β in the weighted Dynkin diagram of the nilpotent orbit).

Now we can easily see that:

- (1) $P = \langle B, X_{-\alpha} \rangle$ where $\langle B, X_{-\alpha} \rangle$ denotes the subgroup of G generated by B and $X_{-\alpha}$.
- (2) $\langle \lambda, \alpha \rangle = 0$ and $\langle \lambda, \beta \rangle = 1$.
- (3) $L = \langle X_{-\alpha}, T, X_{\alpha} \rangle.$
- (4) $\mathfrak{g}(2) = \mathfrak{u}_P^{\geq 2} = \mathbb{C}E_{2\beta+3\alpha}.$
- (5) $W_L = \{e, s\}$ and $W^L = \{e, t, ts, sr^2, sr^3, r^4\}$. (In this case, $v \in W^L \iff v^{-1}(\alpha) \in \Phi^+$.)

Next we enumerate the Hessenberg ideal I from the smallest $I_{2\beta+3\alpha}$ to the biggest $I_{\alpha,\beta}$, and compute $\pi_I^{-1}(N)$ by steps (4) and (5). N is understood to be $E_{2\beta+3\alpha}$ all the time. We know that

$$P(N, I, v) = (P, P \cap \dot{v} \cdot B, \mathbb{C}E_{2\beta+3\alpha}, \mathbb{C}E_{2\beta+3\alpha} \cap \dot{v} \cdot I, N),$$
$$L(N, I, v) \cong (L, L \cap B, \mathbb{C}E_{2\beta+3\alpha}, \mathbb{C}E_{2\beta+3\alpha} \cap \dot{v} \cdot I, N).$$

(Note that $L \cap \dot{v} \cdot B = L \cap B$ for any $v \in W^L$ by Lemma 4.2.1.) Since $\mathfrak{g}(2) = \mathbb{C}E_{2\beta+3\alpha}$, $L(N, I, v) \neq \emptyset \iff \mathbb{C}E_{2\beta+3\alpha} \cap \dot{v} \cdot I = \mathbb{C}E_{2\beta+3\alpha} \iff v$ sends some root of I to $2\beta + 3\alpha$. When this happens, $L(N, I, v) = \mathcal{O}_v^{\lambda}$ and $P(N, I, v) = \mathcal{O}_v = P\dot{v}B$. That is, both are equal to their biggest possibility.

•
$$I = I_{2\beta+3\alpha}$$

Since I has only one root $2\beta + 3\alpha$, for L(N, I, v) to be nonempty, v has to send $2\beta + 3\alpha$ to itself. Then the only possibility is v = e. Therefore, $\pi_I^{-1}(N) =$ $P(N, I, e) = P\dot{e}B = X_s \amalg X_e = \overline{X_s} \cong \mathbb{P}^1$. $\pi_I^{-1}(N)$ is the Schubert variety $\overline{X_s}$. It has one 0-cell and one 1-cell.

•
$$I = I_{\beta+3\alpha}$$

Now that I has one more long root $\beta + 3\alpha$ than the previous ideal $I_{2\beta+3\alpha}$, v has to send either of them to $2\beta + 3\alpha$. Then v = e or t. $P(N, I, e) = P\dot{e}B = \overline{X_s}$. $P(N, I, t) = P\dot{t}B = X_t \amalg X_{st}$. Then $\pi_I^{-1}(N) = \overline{X_s} \amalg X_t \amalg X_{st} = \overline{X_{st}}$. It is a Schubert variety of dimension 2.

• $I = I_{\beta+2\alpha}$

I has one more short root $\beta + 2\alpha$ than $I_{\beta+3\alpha}$, and the action of any $w \in W$

on Φ preserves the lengths of roots. Therefore, v can still only be e or t. Then $\pi_I^{-1}(N) = P(N, I, e) \amalg P(N, I, t) = P\dot{e}B \amalg P\dot{t}B = \overline{X_{st}}$. It is the same as the previous one.

• $I = I_{\beta+\alpha}$

I has one more short root $\beta + \alpha$ than $I_{\beta+2\alpha}$, by a similar argument as above, $\pi_I^{-1}(N)$ is still $\overline{X_{st}}$.

• $I = I_{\alpha}$

One more short root α , so $\pi_I^{-1}(N) = \overline{X_{st}}$.

• $I = I_{\beta}$

The previous ideal (by the partial order of inclusion) of I is $I_{\beta+\alpha}$. I has one more long root β and it leads to a new possibility for v. Now v = e, t or ts. $\pi_I^{-1}(N) = P(N, I, e) \amalg P(N, I, t) \amalg P(N, I, ts) = P\dot{e}B \amalg P\dot{t}B \amalg P\dot{t}\dot{s}B = \overline{X_{sts}}$. It is a Schubert variety of dimension 3.

• $I = I_{\alpha,\beta}$

I has one more short root α than I_{β} , so $\pi_I^{-1}(N) = \pi_{I_{\beta}}^{-1}(N) = \overline{X_{sts}}$. This one is a Springer fiber.

We have finished the case of A_1 .

4.3.2 The case of \tilde{A}_1

The notation " \tilde{A}_1 " represents the undistinguished nilpotent orbit of G_2 , every element of which lies in a minimal Levi subalgebra of type A_1 as well, but this time, for a suitable representative of \tilde{A}_1 , the root system of its minimal Levi subalgebra consists of a pair of opposite short roots of G_2 . $N = E_{\beta+2\alpha}$ is a representative satisfying the requirement of step (2). We use N to denote $E_{\beta+2\alpha}$ in this case.

First we justify the choice of $N = E_{\beta+2\alpha}$. N is a regular nilpotent element of the Levi subalgebra $\mathfrak{m} = \mathfrak{t} \oplus \mathfrak{g}_{-\beta-2\alpha} \oplus \mathfrak{g}_{\beta+2\alpha}$, hence belongs to \tilde{A}_1 . $\{N, H_{\beta+2\alpha}, E_{-\beta-2\alpha}\}$ is an \mathfrak{sl}_2 -triple such that $H_{\beta+2\alpha} \in \mathfrak{t}$, $\alpha(H_{\beta+2\alpha}) = 1$ and $\beta(H_{\beta+2\alpha}) = 0$. Then the associated parabolic of N is standard.

We know that:

- (1) $P = \langle B, X_{-\beta} \rangle.$
- (2) $\langle \lambda, \alpha \rangle = 1$ and $\langle \lambda, \beta \rangle = 0$.
- (3) $L = \langle X_{-\beta}, T, X_{\beta} \rangle.$

(4)
$$\mathfrak{g}(2) = \mathbb{C}E_{\beta+2\alpha}$$
 and $\mathfrak{u}_P^{\geq 2} = \operatorname{span}_{\mathbb{C}} \{ E_{\beta+2\alpha}, E_{\beta+3\alpha}, E_{2\beta+3\alpha} \}.$

(5) $W_L = \{e, t\}$ and $W^L = \{e, s, st, r^2, tr^3, tr^4\}$. (In this case, $v \in W^L \iff v^{-1}(\beta) \in \Phi^+$.)

Since $\mathfrak{g}(2) = \mathbb{C}E_{\beta+2\alpha}$ is still one dimensional, $L(N, I, v) \neq \emptyset \iff v$ sends some root of I to $\beta+2\alpha$. When this happens, $L(N, I, v) = \mathcal{O}_v^{\lambda}$, but P(N, I, v) could be strictly smaller that $\mathcal{O}_v = P\dot{v}B$. In this situation, it is usually helpful to compare P(N, I, v)with P(N, J, v) where J is the previous Hessenberg ideal (meaning a subspace of codimensin 1) of I. Quite often, they are equal to each other.

• $I = I_{2\beta+3\alpha}$ or $I_{\beta+3\alpha}$

Since these two ideals only have long roots, $\mathfrak{g}(2) \cap \dot{v} \cdot I = 0$ for any $v \in W^L$. Then $\pi_I^{-1}(N) = \emptyset$ for both ideals. • $I = I_{\beta+2\alpha}$

Since I has only one short root $\beta + 2\alpha$, v has to fix $\beta + 2\alpha$. Then it could only be e. Because $\mathfrak{u}_P^{\geq 2} \cap \dot{e} \cdot I = \mathfrak{u}_P^{\geq 2}$, $P(N, I, e) = P\dot{e}B = BW_LB = X_e \amalg X_t = \overline{X_t} \cong \mathbb{P}^1$. It is a Schubert variety of dimension 1.

• $I = I_{\beta+\alpha}$

I has one more short root $\beta + \alpha$ than $I_{\beta+2\alpha}$, so v = e or s. When v = e, since $\mathfrak{u}_P^{\geq 2} \cap \dot{e} \cdot I = \mathfrak{u}_P^{\geq 2} \cap \dot{e} \cdot I_{\beta+2\alpha}$, $P(N, I, e) = P(N, I_{\beta+2\alpha}, e) = \overline{X_t}$. As for v = s, $L(N, I, s) = \mathcal{O}_s^{\lambda} \cong L/L \cap B$. Because $\mathfrak{u}_P^{\geq 2} \cap \dot{s} \cdot I = \mathbb{C}E_{\beta+2\alpha} \oplus \mathbb{C}E_{2\beta+3\alpha}$, by Lemma 2.7.1 and Lemma 4.2.1,

$$\dim P(N, I, s) = |\Phi^{-}(L)| + |\Phi_s| - \dim(\mathfrak{u}_P^{\geq 2}/\mathfrak{u}_P^{\geq 2} \cap \dot{s} \cdot I) = 1 + 1 - 1 = \dim L(N, I, s).$$

By Corollary 2.7.6,

$$P(N,I,s) = L(N,I,s) = \mathcal{O}_s^{\lambda} = U^e \dot{s}B \amalg U^t \dot{t}\dot{s}B = \{\dot{s}B\} \amalg X_\beta \dot{t}\dot{s}B = \overline{X_\beta \dot{t}\dot{s}B} \cong \mathbb{P}^1$$

Then $\pi_I^{-1}(N) = \overline{X_t} \amalg \overline{X_\beta} \dot{t} \dot{s} B \cong \mathbb{P}^1 \amalg \mathbb{P}^1$. This is our first example which is not a Schubert variety.

•
$$I = I_{\beta}$$

I has one more long root β than $I_{\beta+\alpha}$, so v = e or s. $P(N, I, e) = P(N, I_{\beta+\alpha}, e) = \overline{X_t}$. Since $\mathfrak{u}_P^{\geq 2} \cap \dot{s} \cdot I = \mathfrak{u}_P^{\geq 2}$ this time, $P(N, I, s) = P\dot{s}B = X_{ts} \amalg X_s$. Then $\pi_I^{-1}(N) = \overline{X_t} \amalg X_{ts} \amalg X_s = \overline{X_{ts}}$. It is a Schubert variety of dimension 2. Note that $\pi_{I_{\beta+\alpha}}^{-1}(N)$ is naturally included in $\pi_{I_{\beta}}^{-1}(N)$, but the 1-cell $X_{\beta}\dot{t}\dot{s}B$ of the former is no

longer a cell of the latter.

•
$$I = I_{\alpha}$$

I has one more short root α than $I_{\beta+\alpha}$, so v has one more possibility and v = e, s or r. $P(N, I, e) = P(N, I_{\beta+\alpha}, e) = \overline{X_t}$ and $P(N, I, s) = P(N, I_{\beta+\alpha}, s) = \overline{X_\beta t \dot{s} B}$. As for $v = r, \mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I = \mathbb{C} E_{\beta+2\alpha} \oplus \mathbb{C} E_{2\beta+3\alpha}$. By Lemma 4.2.1 and Lemma 2.7.1, dim $P(N, I, r) = |\Phi^-(L)| + |\Phi_r| - \dim(\mathfrak{u}_P^{\geq 2}/\mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I) = 2$. By Corollary 2.7.6, P(N, I, r) has one 1-cell and one 2-cell, each being a respective rank 1 vector bundle over the 0-cell and 1-cell of $L(N, I, r) = \mathcal{O}_r^{\lambda} \cong \mathbb{P}^1$. Next we describe the cells of P(N, I, r) precisely.

Recall that $P(N, I, r) = \pi_I^{-1}(N) \cap \mathcal{O}_r$ and $\mathcal{O}_r = P\dot{r}B = U^r\dot{r}B \amalg U^{tr}\dot{t}\dot{r}B$. By Lemma 4.1.4, $U^r = X_{\alpha}X_{\beta+3\alpha}$ and $U^{tr} = X_{\beta+\alpha}X_{\beta}X_{2\beta+3\alpha}$. Now we are able to inspect $\pi_I^{-1}(N) \cap U^r\dot{r}B$ and $\pi_I^{-1}(N) \cap U^{tr}\dot{t}\dot{r}B$.

For $u\dot{r}B \in U^r\dot{r}B$ to be in $\pi_I^{-1}(N)$, we need $u^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I$. Here $u \in U^r$ takes the form $u = x_\alpha(z)x_{\beta+3\alpha}(z')$ for some $z, z' \in \mathbb{C}$. By Lemma 4.1.1, there exists a nonzero constant c such that

$$u^{-1} \cdot N = x_{\beta+3\alpha}(-z') \cdot x_{\alpha}(-z) \cdot E_{\beta+2\alpha} = E_{\beta+2\alpha} - cz E_{\beta+3\alpha}$$

for any $z, z' \in \mathbb{C}$. Then $E_{\beta+2\alpha} - cz E_{\beta+3\alpha} \in \mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I = \mathbb{C} E_{\beta+2\alpha} \oplus \mathbb{C} E_{2\beta+3\alpha}$ if and only if z = 0. Therefore, $\pi_I^{-1}(N) \cap U^r \dot{r} B = X_{\beta+3\alpha} \dot{r} B \subset X_r$.

For $u\dot{t}\dot{r}B \in U^{tr}\dot{t}\dot{r}B$ to be in $\pi_I^{-1}(N)$, we need $\dot{t}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I$. Here $u \in U^{tr}$ takes the form $u = x_{\beta+\alpha}(z)x_{\beta}(z')x_{2\beta+3\alpha}(z'')$ for some $z, z', z'' \in \mathbb{C}$. By

Lemma 4.1.1, there exists a nonzero constant c' such that

$$\dot{t}^{-1} \cdot u^{-1} \cdot N = \dot{t} \cdot x_{2\beta+3\alpha}(-z'') \cdot x_{\beta}(-z') \cdot x_{\beta+\alpha}(-z) \cdot E_{\beta+2\alpha} = \dot{t} \cdot E_{\beta+2\alpha} - c'z(\dot{t} \cdot E_{2\beta+3\alpha})$$

for any $z, z', z'' \in \mathbb{C}$. Then $\dot{t} \cdot E_{\beta+2\alpha} - c'z(\dot{t} \cdot E_{2\beta+3\alpha}) \in \mathfrak{u}_P^{\geq 2} \cap \dot{r} \cdot I$ if and only if z = 0. Therefore, $\pi_I^{-1}(N) \cap U^{tr}\dot{t}\dot{r}B = X_\beta X_{2\beta+3\alpha}\dot{t}\dot{r}B \subset X_{tr}$.

In addition, $L(N, I, r) = \mathcal{O}_r^{\lambda} = \{\dot{r}B\}$ II $X_{\beta}\dot{t}\dot{r}B$. Clearly, $X_{\beta+3\alpha}\dot{r}B$ contains and lies above $\{\dot{r}B\}$ as a rank 1 vector bundle. The same is true with $X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B$ and $X_{\beta}\dot{t}\dot{r}B$. This is compatible with Corollary 2.7.6.

In summary, $\pi_I^{-1}(N) = \overline{X_t} \amalg \overline{X_\beta} \dot{t} \dot{s} B \amalg X_{\beta+3\alpha} \dot{r} B \amalg X_\beta X_{2\beta+3\alpha} \dot{t} \dot{r} B$. It has two 0-cells, three 1-cells and one 2-cell. Further geometric properties of this $\pi_I^{-1}(N)$ will be discussed in later part of this chapter (Theorem 4.4.1).

•
$$I = I_{\alpha,\beta}$$

I has one more long root β than I_{α} , so v can still only be e, s or r. Since $\mathfrak{u}_{P}^{\geq 2} \cap \dot{e} \cdot I = \mathfrak{u}_{P}^{\geq 2} \cap \dot{s} \cdot I = \mathfrak{u}_{P}^{\geq 2}$, $P(N, I, e) = P\dot{e}B = \overline{X_{t}}$ and $P(N, I, s) = P\dot{s}B = X_{s} \amalg X_{ts}$. Moreover, $P(N, I, r) = P(N, I_{\alpha}, r) = X_{\beta+3\alpha}\dot{r}B \amalg X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B$. Therefore, $\pi_{I}^{-1}(N) = \overline{X_{ts}} \amalg X_{\beta+3\alpha}\dot{r}B \amalg X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B$. This is a Springer fiber of dimension 2. We have finished the case of $\tilde{A_{1}}$.

4.3.3 The case of $G_2(a_1)$

The notation " $G_2(a_1)$ " represents the distinguished nilpotent orbit of G_2 whose associated parabolic has semisimple rank 1. $N = E_{\beta+\alpha} + E_{\beta+3\alpha}$ is a representative that satisfies the requirement of step (2). We use N to denote $E_{\beta+\alpha} + E_{\beta+3\alpha}$ in this case.

Now we justify the choice of $N = E_{\beta+\alpha} + E_{\beta+3\alpha}$. Set $H = [E_{\beta+\alpha} + E_{\beta+3\alpha}, E_{-\beta-\alpha} + E_{-\beta-3\alpha}]$. Simple computation shows that $\{N, H, E_{-\beta-\alpha} + E_{-\beta-3\alpha}\}$ is an \mathfrak{sl}_2 -triple such that $H \in \mathfrak{t}$, $\alpha(H) = 0$ and $\beta(H) = 2$. Then the associated parabolic of N is standard. In fact, we know that $P = \langle B, X_{-\alpha} \rangle$ and $\dim \mathfrak{g}(0) = \dim \mathfrak{g}(2) = 4$, so N is a distinguished nilpotent element whose associated parabolic is not the Borel subgroup B. Therefore N has to be in $G_2(a_1)$.

We know that:

- (1) $P = \langle B, X_{-\alpha} \rangle.$
- (2) $\langle \lambda, \alpha \rangle = 0$ and $\langle \lambda, \beta \rangle = 2$.

(3)
$$L = \langle X_{-\alpha}, T, X_{\alpha} \rangle$$

- (4) $\mathfrak{g}(2) = \operatorname{span}_{\mathbb{C}} \{ E_{\beta}, E_{\beta+\alpha}, E_{\beta+2\alpha}, E_{\beta+3\alpha} \}$ and $\mathfrak{u}_{P}^{\geq 2} = \operatorname{span}_{\mathbb{C}} \{ E_{\beta}, E_{\beta+\alpha}, E_{\beta+2\alpha}, E_{\beta+3\alpha}, E_{2\beta+3\alpha} \}.$
- (5) $W_L = \{e, s\}$ and $W^L = \{e, t, ts, sr^2, sr^3, r^4\}.$

Now that $\mathfrak{g}(2)$ is of dimension 4, telling whether $L(N, I, v) \neq \emptyset$ is harder. We therefore propose the following lemma.

Lemma 4.3.1. For any $v \in W^L$, $L(N, I, v) \neq \emptyset$ if and only if $\mathfrak{g}(2) \cap \dot{v} \cdot I$ contains at least one of the three spaces below:

$$\mathbb{C}E_{\beta+\alpha} \oplus \mathbb{C}E_{\beta+3\alpha}, \mathbb{C}E_{\beta} \oplus \mathbb{C}E_{\beta+2\alpha} \text{ or } \mathbb{C}E_{\beta+\alpha} \oplus \mathbb{C}E_{\beta+2\alpha}.$$

Proof. Let B_L denote $L \cap B$ in this lemma. For any $v \in W^L$,

$$L(N, I, v) \cong (L, B_L, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N) \subset L/B_L.$$

Recall the definition of the quintuple

$$(L, B_L, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N) = \left\{ lB_L \in L/B_L \,|\, l^{-1} \cdot N \in \mathfrak{g}(2) \cap \dot{v} \cdot I \right\}.$$
(4.1)

By Lemma 4.1.1, there exist nonzero constants c and c' such that

$$x_{\alpha}(z) \cdot N = x_{\alpha}(z) \cdot (E_{\beta+\alpha} + E_{\beta+3\alpha}) = E_{\beta+\alpha} + czE_{\beta+2\alpha} + (1 + c'z^2)E_{\beta+3\alpha} \quad (4.2)$$

for any $z \in \mathbb{C}$. Let z_1 and z_2 be the two distinct solutions of $1 + c'z^2 = 0$. We partition L/B_L into four subsets:

$$L/B_L = \{\dot{e}B_L\} \amalg \{\dot{s}B_L\} \amalg \{x_{\alpha}(z_1)\dot{s}B_L, x_{\alpha}(z_2)\dot{s}B_L\} \amalg \{x_{\alpha}(z)\dot{s}B_L \mid z \neq 0, z_1, z_2\}.$$

By this partition and Equation 4.1, we can easily deduce the lemma. Further details are left out to mitigate distraction from the main course of computation. \Box

Next we give an algorithm (referred to as the "v-algorithm") to find all the v's so that $L(N, I, v) \neq \emptyset$.

Firstly, $W_L r^0, W_L r^1, \ldots, W_L r^5$ are all the six W_L -cosets of W, only that r^i may not be in W^L . We view the set of roots of I as a configuration of arrows. For each $i = 0, 1, \ldots, 5$, check if the aforementioned configuration, after a rotation by r^i , covers one of the three sets of arrows (roots):

$$\{\beta + \alpha, \beta + 3\alpha\}, \{\beta, \beta + 2\alpha\} \text{ and } \{\beta + \alpha, \beta + 2\alpha\}.$$

If so, both $\mathfrak{g}(2) \cap \dot{r}^i \cdot I$ and $\mathfrak{g}(2) \cap \dot{s}\dot{r}^i \cdot I$ satisfy the condition of Lemma 4.3.1. One of r^i and sr^i has to be in W^L and it serves as a v so that $L(N, I, v) \neq \emptyset$.

• $I = I_{2\beta+3\alpha}, I_{\beta+3\alpha}$ or $I_{\beta+2\alpha}$

Using the *v*-algorithm, we deduce that $\pi_I^{-1}(N) = \emptyset$ for all three ideals. The same fact can be more easily established by comparing the dimension of $G \times^B I$ with the dimension of the nilpotent orbit $G_2(a_1)$, but the algorithm is necessary when we work with bigger ideals.

• $I = I_{\beta+\alpha}$

Using the v-algorithm, we see that v = e is the only element so that $L(N, I, v) \neq \emptyset$. In this situation,

$$\mathfrak{g}(2) \cap \dot{e} \cdot I = \operatorname{span}_{\mathbb{C}} \left\{ E_{\beta+\alpha}, E_{\beta+2\alpha}, E_{\beta+3\alpha} \right\},$$
$$\mathfrak{u}_{P}^{\geq 2} \cap \dot{e} \cdot I = \operatorname{span}_{\mathbb{C}} \left\{ E_{\beta+\alpha}, E_{\beta+2\alpha}, E_{\beta+3\alpha}, E_{2\beta+3\alpha} \right\}$$

Then, by Lemma 2.7.1 and Lemma 4.2.1, dim $P(N, I, e) = \dim L(N, I, e) = 0$. By Corollary 2.7.6, P(N, I, e) and L(N, I, e) are the same finite set. Next we compute the set L(N, I, e).

To do this, we use the same setup as in the proof of Lemma 4.3.1. In particular, note that $L(N, I, e) \cong (L, B_L, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{e} \cdot I, N) \subset L/B_L$ and that L/B_L can be partitioned into the following four subsets.

$$L/B_L = \{\dot{e}B_L\} \amalg \{\dot{s}B_L\} \amalg \{x_{\alpha}(z_1)\dot{s}B_L, x_{\alpha}(z_2)\dot{s}B_L\} \amalg \{x_{\alpha}(z)\dot{s}B_L \mid z \neq 0, z_1, z_2\}.$$

We then find the intersection of each subset with L(N, I, e).

Clearly, $\dot{e}B_L \in L(N, I, e)$.

For the other three subsets, note that they all consist of points in the form $x_{\alpha}(z)\dot{s}B_L$ for some $z \in \mathbb{C}$. By definition, $x_{\alpha}(z)\dot{s}B_L \in L(N, I, e) \iff \dot{s}^{-1} \cdot x_{\alpha}(z)^{-1} \cdot N \in \mathfrak{g}(2) \cap \dot{e} \cdot I \iff x_{\alpha}(-z) \cdot N \in \dot{s} \cdot (\mathfrak{g}(2) \cap \dot{e} \cdot I) = \operatorname{span}_{\mathbb{C}} \{E_{\beta}, E_{\beta+\alpha}, E_{\beta+2\alpha}\}.$ By Equation 4.2,

$$x_{\alpha}(-z) \cdot N = E_{\beta+\alpha} - cz E_{\beta+2\alpha} + (1 + c'z^2) E_{\beta+3\alpha}.$$

Then $x_{\alpha}(-z) \cdot N \in \operatorname{span}_{\mathbb{C}} \{ E_{\beta}, E_{\beta+\alpha}, E_{\beta+2\alpha} \}$ if and only if $z = z_1$ or z_2 , the two solutions of $1 + c'z^2 = 0$.

In summary,

$$L(N, I, e) \cong (L, B_L, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{e} \cdot I, N) = \{ \dot{e}B_L, x_\alpha(z_1)\dot{s}B_L, x_\alpha(z_2)\dot{s}B_L \},\$$

hence

$$\pi_I^{-1}(N) = P(N, I, e) = L(N, I, e) = \{ \dot{e}B, x_\alpha(z_1)\dot{s}B, x_\alpha(z_2)\dot{s}B \}.$$

It is the variety of 3 distinct points.

• $I = I_{\beta}$

v = e is still the only possibility, but now $\mathfrak{g}(2) \cap \dot{e} \cdot I = \mathfrak{g}(2)$ and $\mathfrak{u}_P^{\geq 2} \cap \dot{e} \cdot I = \mathfrak{u}_P^{\geq 2}$. Therefore, $\pi_I^{-1}(N) = P(N, I, e) = P\dot{e}B = \overline{X_s}$. It is a Schubert variety. Note that the two 0-cells $\{x_{\alpha}(z_1)\dot{s}B\}$ and $\{x_{\alpha}(z_2)\dot{s}B\}$ of $\pi_{I_{\beta+\alpha}}^{-1}(N)$ are no longer cells of $\pi_I^{-1}(N)$. • $I = I_{\alpha}$

Using the v-algorithm, we now have v = e or t.

When v = e, $P(N, I, e) = P(N, I_{\beta+\alpha}, e) = \{\dot{e}B, x_{\alpha}(z_1)\dot{s}B, x_{\alpha}(z_2)\dot{s}B\}$. When v = t, $\mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I = \operatorname{span}_{\mathbb{C}} \{E_{\beta+\alpha}, E_{\beta+2\alpha}, E_{\beta+3\alpha}, E_{2\beta+3\alpha}\}$. By Lemma 2.7.1 and Lemma 4.2.1, dim P(N, I, t) = 1, so P(N, I, t) is strictly smaller than \mathcal{O}_t . Recall that $P(N, I, t) = \pi_I^{-1}(N) \cap \mathcal{O}_t$ and $\mathcal{O}_t = P\dot{t}B = U^t\dot{t}B$ II $U^{st}\dot{s}\dot{t}B$. By Lemma 4.1.4, $U^t = X_\beta$ and $U^{st} = X_\alpha X_{\beta+3\alpha}$. Next we inspect $\pi_I^{-1}(N) \cap U^t\dot{t}B$ and $\pi_I^{-1}(N) \cap U^{st}\dot{s}\dot{t}B$. For $u\dot{t}B \in U^t\dot{t}B$ to be in $\pi_I^{-1}(N)$, we need $u^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I$. Here $u \in U^t$

takes the form $u = x_{\beta}(z)$ for some $z \in \mathbb{C}$. By Lemma 4.1.1, there exists a nonzero constant c such that

$$u^{-1} \cdot N = x_{\beta}(-z) \cdot (E_{\beta+\alpha} + E_{\beta+3\alpha}) = E_{\beta+\alpha} + E_{\beta+3\alpha} - cz E_{2\beta+3\alpha}$$

for any $z \in \mathbb{C}$. Clearly, $E_{\beta+\alpha} + E_{\beta+3\alpha} - czE_{2\beta+3\alpha} \in \mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I$ for any $z \in \mathbb{C}$. Therefore, $\pi_I^{-1}(N) \cap U^t \dot{t}B = X_\beta \dot{t}B = X_t$.

For $u\dot{s}\dot{t}B \in U^{st}\dot{s}\dot{t}B$ to be in $\pi_I^{-1}(N)$, we need $\dot{s}^{-1} \cdot u^{-1} \cdot N \in \mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I$. Here $u \in U^{st}$ takes the form $u = x_\alpha(z)x_{\beta+3\alpha}(z')$ for some $z, z' \in \mathbb{C}$. The same nonzero

constants c and c' from Equation 4.2 guarantee that

$$\dot{s}^{-1} \cdot u^{-1} \cdot N = \dot{s} \cdot x_{\beta+3\alpha}(-z') \cdot x_{\alpha}(-z) \cdot (E_{\beta+\alpha} + E_{\beta+3\alpha})$$
$$= \dot{s} \cdot E_{\beta+\alpha} - cz(\dot{s} \cdot E_{\beta+2\alpha}) + (1 + c'z^2)(\dot{s} \cdot E_{\beta+3\alpha})$$

for any $z, z' \in \mathbb{C}$. Then $\dot{s} \cdot E_{\beta+\alpha} - cz(\dot{s} \cdot E_{\beta+2\alpha}) + (1 + c'z^2)(\dot{s} \cdot E_{\beta+3\alpha}) \in \mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I$ if and only if $1 + c'z^2 = 0$. That is, $z = z_1$ or z_2 , the two solutions of $1 + c'z^2 = 0$ and z' could be any complex number. Therefore, $\pi_I^{-1}(N) \cap U^{st}\dot{s}\dot{t}B = x_\alpha(z_1)X_{\beta+3\alpha}\dot{s}\dot{t}B \amalg$ $x_\alpha(z_2)X_{\beta+3\alpha}\dot{s}\dot{t}B \subset X_{st}$.

In summary,

$$\pi_I^{-1}(N) = \{ \dot{e}B, x_\alpha(z_1) \dot{s}B, x_\alpha(z_2) \dot{s}B \} \amalg X_\beta \dot{t}B \amalg x_\alpha(z_1) X_{\beta+3\alpha} \dot{s}\dot{t}B \amalg x_\alpha(z_2) X_{\beta+3\alpha} \dot{s}\dot{t}B$$

There is a simple description of $\pi_I^{-1}(N)$ as an algebraic variety. As will be shown in Lemma 4.4.3 and Lemma 4.4.5,

$$\lim_{z \to \infty} x_{\beta}(z)\dot{t}B = \dot{e}B,$$
$$\lim_{z \to \infty} x_{\alpha}(z_1)x_{\beta+3\alpha}(z)\dot{s}\dot{t}B = x_{\alpha}(z_1)\dot{s}B,$$
$$\lim_{z \to \infty} x_{\alpha}(z_2)x_{\beta+3\alpha}(z)\dot{s}\dot{t}B = x_{\alpha}(z_2)\dot{s}B,$$

where limits are taken in the flag variety G/B. Therefore,

$$\pi_I^{-1}(N) = \overline{X_\beta \dot{t}B} \amalg \overline{x_\alpha(z_1)} X_{\beta+3\alpha} \dot{s} \dot{t}B} \amalg \overline{x_\alpha(z_2)} X_{\beta+3\alpha} \dot{s} \dot{t}B \cong \mathbb{P}^1 \amalg \mathbb{P}^1 \amalg \mathbb{P}^1.$$

• $I = I_{\alpha,\beta}$

Still, v = e or t. When v = e, since $\mathfrak{u}_P^{\geq 2} \cap \dot{e} \cdot I = \mathfrak{u}_P^{\geq 2}$, $P(N, I, e) = P\dot{e}B = \overline{X_s}$. When v = t, since $\mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I = \mathfrak{u}_P^{\geq 2} \cap \dot{t} \cdot I_{\alpha}$,

$$P(N, I, t) = P(N, I_{\alpha}, t) = X_{\beta} \dot{t} B \amalg x_{\alpha}(z_1) X_{\beta+3\alpha} \dot{s} \dot{t} B \amalg x_{\alpha}(z_2) X_{\beta+3\alpha} \dot{s} \dot{t} B.$$

Putting these two parts together, we see that $\pi_I^{-1}(N)$ has 4 irreducible components, each isomorphic to \mathbb{P}^1 . $\pi_I^{-1}(N)$ is obtained by attaching 3 copies of \mathbb{P}^1 to the 3 distinct points $\{\dot{e}B, x_{\alpha}(z_1)\dot{s}B, x_{\alpha}(z_2)\dot{s}B\}$ of $\overline{X_s}$ at their respective points at infinity. Explicitly,

$$\pi_I^{-1}(N) = \overline{X_s} \amalg X_\beta \dot{t} B \amalg x_\alpha(z_1) X_{\beta+3\alpha} \dot{s} \dot{t} B \amalg x_\alpha(z_2) X_{\beta+3\alpha} \dot{s} \dot{t} B$$

We have finished the case of $G_2(a_1)$.

Remark 4.3.2. In Collingwood & McGovern [1993], $G_2(a_1)$ is called the subregular nilpotent orbit of G_2 . In general, the subregular nilpotent orbit is the unique nilpotent orbit of codimension 2 in the nilpotent cone $\mathcal{N} \subset \mathfrak{g}$. Let N be an element of the subregular orbit. It is known that the Springer fiber \mathcal{B}_N is a union of \mathbb{P}^1 's whose configuration we now describe. We can form the dual graph of \mathcal{B}_N so that its vertices are the irreducible components of \mathcal{B}_N and two vertices are joined by an edge if the two corresponding components intersect (they always intersect at a single point).

When G is of type G_2 and N is from the subregular orbit $G_2(a_1)$, the dual graph

of \mathcal{B}_N is the Dynkin diagram of D_4 (see Steinberg [1974][section 3.10]). This description of \mathcal{B}_N matches exactly our result for $\pi_{I_{\alpha,\beta}}^{-1}(G_2(a_1))$. Let $A(N) = C_G(N)/C_G^{\circ}(N)$. Since $C_G(N)$ acts naturally on $\pi_I^{-1}(N) \subset G/B$ by left multiplication, A(N) permutes the irreducible components of $\pi_I^{-1}(N)$. If G is in addition the adjoint form of G_2 , $A(N) \cong S_3$ (see Carter [1985][p. 427]). Then A(N) acts on $\pi_{I_{\alpha,\beta}}^{-1}(G_2(a_1))$ by naturally permuting three components and fixing the last one to which the other three are attached. Consequently, A(N) acts by the natural permutation action on $\pi_{I_{\alpha}}^{-1}(G_2(a_1)) \cong \mathbb{P}^1 \amalg \mathbb{P}^1 \amalg \mathbb{P}^1$ and $\pi_{I_{\beta+\alpha}}^{-1}(G_2(a_1)) \cong \{3 \text{ distinct points}\}$ and trivially on $\pi_{I_{\beta}}^{-1}(G_2(a_1)) \cong \mathbb{P}^1$. This action will be used in our computation of the dot actions for type G_2 in chapter 5.

4.3.4 The case of G_2

The notation " G_2 " represents the regular nilpotent orbit of the group G_2 . It is well-known that the Springer fiber \mathcal{B}_N is a single point when N is regular nilpotent. By comparing the dimension of $G \times^B I$ with that of the regular nilpotent orbit, it is easy to see that the Springer fiber \mathcal{B}_N is the only nonempty Hessenberg ideal fiber, so there is nothing to compute in this case. To show the scope of our algorithm, we give another proof of the two statements just made along the lines of this chapter.

Firstly, our representative of the regular nilpotent orbit is $N = E_{\alpha} + E_{\beta}$. Set $H = 6H_{\alpha} + 10H_{\beta}$. Simple computation shows that $\{N, H, 6E_{-\alpha} + 10E_{-\beta}\}$ is an \mathfrak{sl}_2 -triple such that $H \in \mathfrak{t}$, $\alpha(H) = 2$ and $\beta(H) = 2$. Therefore, the associated parabolic of N is the Borel subgroup B and we know the following:

- (1) P = B.
- (2) $\langle \lambda, \alpha \rangle = 2$ and $\langle \lambda, \beta \rangle = 2$.
- (3) L = T.
- (4) $\mathfrak{g}(2) = \mathbb{C}E_{\alpha} \oplus \mathbb{C}E_{\beta}$ and $\mathfrak{u}_{P}^{\geq 2} = \mathfrak{u}$.

(5)
$$W_L = \{e\}$$
 and $W^L = W_L$

For any $v \in W^L = W$ and any Hessenberg ideal $I, L(N, I, v) \cong (T, T, \mathfrak{g}(2), \mathfrak{g}(2) \cap \dot{v} \cdot I, N)$. Then $L(N, I, v) \neq \emptyset \iff N \in \mathfrak{g}(2) \cap \dot{v} \cdot I$. Because $N = E_{\alpha} + E_{\beta}$ and $\mathfrak{g}(2) \cap \dot{v} \cdot I$ is T-stable, $N \in \mathfrak{g}(2) \cap \dot{v} \cdot I \iff \mathfrak{g}(2) \subset \mathfrak{g}(2) \cap \dot{v} \cdot I \iff \mathfrak{g}(2) \subset \dot{v} \cdot I$. The last condition is possible only when v = e and $I = \mathfrak{u}$, so the Springer fiber \mathcal{B}_N is the only nonempty Hessenberg ideal fiber. In that case, $P(N, \mathfrak{u}, e) = (B, B, \mathfrak{u}, \mathfrak{u}, N)$ and it is a single point.

We have now finished the computation of all Hessenberg ideal fibers when G is of type G_2 . The results can be summarized by Table 4.1. Note that the ways in which $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$ and $\pi_{I_{\alpha,\beta}}^{-1}(\tilde{A}_1)$ are presented allude to the closure relationships of their cells. These relationships are proved in section 4.4.

4.4 An interesting Hessenberg ideal fiber

Now we study one of the Hessenberg ideal fibers computed in the last section— $\pi_I^{-1}(N)$ where $I = I_{\alpha}$ and $N = E_{\beta+2\alpha}$. Since N is a representative of \tilde{A}_1 , we denote this fiber by $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$ in the rest of this section.

				VI 2	
	{0}	A_1	$ ilde{A}_1$	$G_2(a_1)$	G_2
I_{\emptyset}	G/B				
$I_{2\beta+3\alpha}$	G/B	$\overline{X_s}$			
$I_{\beta+3\alpha}$	G/B	$\overline{X_{st}}$			
$I_{\beta+2\alpha}$	G/B	$\overline{X_{st}}$	$\overline{X_t}$		
$I_{\beta+\alpha}$	G/B	$\overline{X_{st}}$	$\mathbb{P}^1\amalg\mathbb{P}^1$	3 distinct points	
I_{α}	G/B	$\overline{X_{st}}$	$\overline{X_t} \amalg \overline{X_\beta X_{2\beta+3\alpha} \dot{t} \dot{r} B}$	$\mathbb{P}^1\amalg\mathbb{P}^1\amalg\mathbb{P}^1$	
I_{β}	G/B	$\overline{X_{sts}}$	$\overline{X_{ts}}$	$\overline{X_s}$	
$I_{\alpha,\beta}$	G/B	$\overline{X_{sts}}$	$\overline{X_{ts}} \cup \overline{X_{\beta}X_{2\beta+3\alpha}} \dot{t}\dot{r}B$	$\mathbb{P}^1 \cup \mathbb{P}^1 \cup \mathbb{P}^1 \cup \mathbb{P}^1$	1 point

Table 4.1: Hessenberg ideal fibers for type G_2

Spaltenstein [2006] proved that any Springer fiber \mathcal{B}_N of a reducitve linear algebraic group over \mathbb{C} is connected and that its irreducible components are of the same dimension. A natural question is whether the same is true of Hessenberg ideal fibers. The answer is no, because $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$ is a counterexample. In fact, we can prove the following.

Theorem 4.4.1. $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$ has two connected components, each of which is irreducible as well. They are of dimension 1 and 2 respectively.

To prove the theorem, we need to study the closure relationships between different cells of the Hessenberg ideal fiber $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$. These relationships can be deduced from the following 4 lemmas. It is well-known that, on algebraic varieties over \mathbb{C} , the closure of a locally closed subvariety in the Zariski topology is the same as in the ordinary (analytic) topology. Therefore, we mostly work with the ordinary topology in the rest of this section. All closures and limits are taken on the flag variety G/B, where G is assumed to be a connected algebraic group of type G_2 over From the last section we know that

$$\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1}) = \overline{X_{t}} \amalg \overline{X_{\beta} t \dot{s} B} \amalg X_{\beta+3\alpha} \dot{r} B \amalg X_{\beta} X_{2\beta+3\alpha} \dot{t} \dot{r} B$$
$$\pi_{I_{\alpha}\beta}^{-1}(\tilde{A}_{1}) = \overline{X_{ts}} \amalg X_{\beta+3\alpha} \dot{r} B \amalg X_{\beta} X_{2\beta+3\alpha} \dot{t} \dot{r} B.$$

Lemma 4.4.2. $\overline{X_{\beta+3\alpha}\dot{r}B} \subset \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}$.

Proof. $\pi_{I_{\alpha,\beta}}^{-1}(\tilde{A}_1)$ is a Springer fiber. By Spaltenstein's result, its irreducible components are of the same dimension. We know that

$$\pi_{I_{\alpha,\beta}}^{-1}(\tilde{A}_1) = \overline{\pi_{I_{\alpha,\beta}}^{-1}(\tilde{A}_1)} = \overline{X_{ts}} \cup \overline{X_{\beta+3\alpha}\dot{r}B} \cup \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}.$$

Since dim $\overline{X_{\beta+3\alpha}\dot{r}B} = 1$ and dim $\overline{X_{ts}} = \dim \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B} = 2$, the irreducible components of $\pi_{I_{\alpha,\beta}}^{-1}(\tilde{A}_1)$ have to be $\overline{X_{ts}}$ and $\overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}$. Because $\overline{X_{\beta+3\alpha}\dot{r}B} \cong \mathbb{P}^1$ hence irreducible, it has to lie in one of the irreducible components. Note that $X_{\beta+3\alpha}\dot{r}B$ lies in the Schubert cell $X_r = X_{st}$, so has no intersection with $\overline{X_{ts}}$. Therefore, $\overline{X_{\beta+3\alpha}\dot{r}B} \subset \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}$.

 $N = E_{\beta+2\alpha}$ is the representative of \tilde{A}_1 used in the computation of $\pi_{I_{\alpha}}^{-1}(\tilde{A}_1)$. Recall that the Levi subgroup of the associated parabolic of N is $L = \langle X_{-\beta}, T, X_{\beta} \rangle$, and that $W_L = \{e, t\}$ and $W = W_L W^L$. **Lemma 4.4.3.** For any $v \in W^L$,

$$\lim_{z \to \infty} x_{\beta}(z) \dot{t} \dot{v} B = \dot{v} B.$$

Proof. Let λ be an associated one-parameter subgroup of N. Recall that

$$\mathcal{O}_v^{\lambda} = U^e \dot{v} B \amalg U^t \dot{t} \dot{v} B = \{ \dot{v} B \} \amalg X_{\beta} \dot{t} \dot{v} B \cong \mathbb{P}^1.$$

 $X_{\beta}\dot{t}\dot{v}B$ is the 1-cell of \mathbb{P}^1 and $\dot{v}B$ is the point at infinity. Then the limit is clearly true.

Lemma 4.4.4. For any $z \in \mathbb{C}$,

$$\lim_{z' \to \infty} x_{\beta}(z) x_{2\beta+3\alpha}(z') \dot{t} \dot{r} B = x_{\beta}(z) \dot{t} \dot{s} B.$$

As a result, $\overline{X_{\beta}\dot{t}\dot{s}B} \subset \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}$.

Proof. Since tr = t(st) = (ts)t, we have

$$x_{\beta}(z)x_{2\beta+3\alpha}(z')\dot{t}\dot{r}B = x_{\beta}(z)\dot{t}\dot{s}(\dot{s}\dot{t}x_{2\beta+3\alpha}(z')\dot{t}\dot{s})\dot{t}B.$$

By Lemma 4.1.3, there exists a nonzero constant c such that $\dot{s}\dot{t}x_{2\beta+3\alpha}(z')\dot{t}\dot{s} = x_{\beta}(cz')$ for any $z' \in \mathbb{C}$. Since $e \in W^L$, by Lemma 4.4.3,

$$\lim_{z'\to\infty} x_\beta(cz')\dot{t}B = \dot{e}B.$$

Therefore, for any $z \in \mathbb{C}$,

$$\lim_{z'\to\infty} x_{\beta}(z) x_{2\beta+3\alpha}(z') \dot{t}\dot{r}B = x_{\beta}(z) \dot{t}\dot{s}(\lim_{z'\to\infty} x_{\beta}(cz')\dot{t}B) = x_{\beta}(z)\dot{t}\dot{s}B.$$

$$\overline{X_{\beta}\dot{t}\dot{s}B} \subset \overline{X_{\beta}X_{2\beta+3\alpha}\dot{t}\dot{r}B}$$
 follows easily from the limit above.

Lemma 4.4.5.

$$\lim_{z \to \infty} x_{\beta}(z) \dot{t} \dot{s} B = \lim_{z \to \infty} x_{\beta+3\alpha}(z) \dot{r} B = \dot{s} B.$$

Proof. Since $s \in W^L$, by Lemma 4.4.3,

$$\lim_{z \to \infty} x_{\beta}(z) \dot{t} \dot{s} B = \dot{s} B.$$

By Lemma 4.1.3, there exists a nonzero constant c such that for any $z \in \mathbb{C}$,

$$x_{\beta+3\alpha}(z)\dot{r}B = \dot{s}(\dot{s}x_{\beta+3\alpha}(z)\dot{s})\dot{t}B = \dot{s}(x_{\beta}(cz)\dot{t}B).$$

Therefore, by Lemma 4.4.3,

$$\lim_{z \to \infty} x_{\beta+3\alpha}(z)\dot{r}B = \dot{s}(\lim_{z \to \infty} x_{\beta}(cz)\dot{t}B) = \dot{s}B.$$

Now we can prove Theorem 4.4.1.

Proof. The explicit description

$$\pi_{L_{\alpha}}^{-1}(\tilde{A}_{1}) = \overline{X_{t}} \amalg \overline{X_{\beta} \dot{t} \dot{s} B} \amalg X_{\beta+3\alpha} \dot{r} B \amalg X_{\beta} X_{2\beta+3\alpha} \dot{t} \dot{r} B$$

shows that $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1})$ has two 0-cells, three 1-cells and one 2-cell. Since $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1})$ is projective, it is compact in the ordinary topology. Therefore the cell structure gives us the singular homology of $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1})$. In particular, $H_{0}(\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1});\mathbb{Z}) = \mathbb{Z} \oplus \mathbb{Z}$, which means $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1})$ has two connected components.

Lemma 4.4.2 and Lemma 4.4.4 imply that both $\overline{X_{\beta}tsB}$ and $\overline{X_{\beta+3\alpha}tB}$ lie in $\overline{X_{\beta}X_{2\beta+3\alpha}tB}$. Therefore, $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1}) = \overline{X_{t}} \cup \overline{X_{\beta}X_{2\beta+3\alpha}tB}$. Note that $\overline{X_{\beta}X_{2\beta+3\alpha}tB}$ is irreducible and connected in the Zariski topology, because it is the Zariski closure of a 2-cell. Therefore, it is also connected in the ordinary topology (Hartshorne [1997][Appendix B]). Then we must have $\overline{X_{t}} \cap \overline{X_{\beta}X_{2\beta+3\alpha}tB} = \emptyset$. Otherwise $\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1})$ is connected in the ordinary topology, contradictory to $H_{0}(\pi_{I_{\alpha}}^{-1}(\tilde{A}_{1});\mathbb{Z}) = \mathbb{Z} \oplus \mathbb{Z}$. In summary, $\overline{X_{t}}$ and $\overline{X_{\beta}X_{2\beta+3\alpha}tB}$ are both connected and irreducible and they are of dimension 1 and 2 respectively. We have now proved the theorem.

Chapter 5: Dot Actions for Type G_2

As an application of Hessenberg ideal fibers, we use the results from chapter 4 to classify Tymoczko's dot actions for type G_2 . This chapter is joint work with the author's advisor Dr. Patrick Brosnan.

5.1 Background and motivation

Let G be a connected reductive algebraic group over \mathbb{C} and B a Borel subgroup of G. Let \mathfrak{g} and \mathfrak{b} denote their respective Lie algebras. Recall that a Hessenberg subspace is an $\mathrm{ad}(\mathfrak{b})$ -stable subspace M of \mathfrak{g} containing \mathfrak{b} . Let $y \in \mathfrak{g}$ be a regular semisimple element. The Hessenberg variety $\mathrm{Hess}(M, y)$ is defined to be the fiber over y of the following map

$$\begin{aligned}
\pi_M : & G \times^B M \longrightarrow \mathfrak{g} \\
& (g, x) \longmapsto g \cdot x
\end{aligned} \tag{5.1}$$

where $g \cdot x$ denotes the adjoint action $\operatorname{Ad}(g)(x)$. According to De Mari et al. [1992], Hess(M, y) is nonsingular for any regular semisimple $y \in \mathfrak{g}$, and, if $T = C_G(y)$ denotes the maximal torus in G centralizing y, we have $\operatorname{Hess}(M, y)^T = (G/B)^T$. By Białynicki-Birula [1973], it follows that $\operatorname{Hess}(M, y)$ is cellular with cells in one-one correspondence with elements of the Weyl group W of G. Tymoczko [2007] used these facts to define the dot actions of W on both the T-equivariant and the ordinary cohomology groups with coefficient \mathbb{C} of the (regular semisimple) Hessenberg variety Hess(M, y). The point is that W does not act on the underlying Hessenberg variety in any interesting way.

The Shareshian-Wachs conjecture expresses Tymoczko's dot action in type A $(G = \mathbf{GL}_n)$ in terms of a symmetric function attached to colorings of a certain graph Γ_f . When $G = \mathbf{GL}_n$, the Hessenberg subspace M is uniquely determined by a non-decreasing function $f : \{1, \ldots, n\} \longrightarrow \{1, \ldots, n\}$ called a Hessenberg function (we require $f(i) \ge i$ for all i). Then Γ_f is the graph with vertex set $V = \{1, \ldots, n\}$ and edge set $E = \{\{i, j\} \subset V \mid i < j \le f(i)\}$. Let Λ denote the ring of symmetric functions, a subring of the power series ring in infinitely many variables $\mathbb{C} [[x_1, x_2, \ldots]]$. The ring $\Lambda = \bigoplus_{n\ge 0} \Lambda_n$ is graded in an obvious way and the Frobenius character ch : Rep $S_n \otimes_{\mathbb{Z}} \mathbb{C} \longrightarrow \Lambda_n$ is an isomorphism from the representation ring (viewed as an abelian group) Rep S_n to Λ_n . Modifying a construction of Stanley, Shareshian & Wachs [2016] defined a polynomial $X_{\Gamma_f}(t) \in \Lambda[t]$ given by

$$X_{\Gamma_f}(t) = \sum_{\kappa: V \to \mathbb{Z}_+} t^{\operatorname{asc}(\kappa)} x_{\kappa(1)} x_{\kappa(2)} \cdots x_{\kappa(n)}$$
(5.2)

where κ runs over all colorings of Γ_f and $\operatorname{asc}(\kappa) = |\{(i, j) \in E \mid i < j, \kappa(i) < \kappa(j)\}|$. The Shareshian-Wachs conjecture is then

$$\omega X_{\Gamma_f}(t) = \sum_{i \ge 0} \operatorname{ch}(S_n, H^{2i}(\operatorname{Hess}(M, y)))t^i$$
(5.3)

where ω is the involution on Λ corresponding to tensoring with the sign representation and $y \in \mathfrak{g}$ is regular semisimple.

This conjecture has already been proved by Brosnan & Chow [2018]. Therefore, Equation 5.3 gives us a formula for Tymoczko's dot action. Moreover, it implies that the Stanley-Stembridge conjecture, which states that $X_{\Gamma_f}(1)$ is a positive linear combination of elementary symmetric functions, has the following representation theoretic formulation: when $G = \mathbf{GL}_n$, the dot action of S_n on $H^*(\operatorname{Hess}(M, y))$ is a direct sum of representations of the form $\operatorname{Ind}_{S_{\lambda}}^{S_{n}} \mathbf{1}$, where $y \in \mathfrak{g}$ is regular semisimple and S_{λ} denotes the Young subgroup of S_n for the partition λ of n. The Stanley-Stembridge conjecture has not been proved yet, which means the dot action on $H^*(\text{Hess}(M, y))$ still needs to be further investigated. Naturally, if a representation theoretic proof of the Stanley-Stembridge conjecture is desired, we should find for it a representation theoretic formulation in all types via the dot action. As one step in the attempt to generalize the Shareshian-Wachs and the Stanley-Stembridge conjectures, Brosnan and the author classified all the dot actions for type G_2 . In particular, Theorem 5.3.2 Table 5.4 shows that not every $H^*(\text{Hess}(M, y))$ is a direct sum of induced representations of the form $\operatorname{Ind}_{W_J}^W \mathbf{1}$, where W_J is the Weyl group of a Levi subalgebra of g. Therefore, at least the "naive" generalization of the Stanley-Stembridge conjecture for type A is not true for type G_2 .
5.2 Computational techniques

In this section, we present the main ideas of the computation and gather all the relevant techniques.

Let G denote a connected reductive algebraic group over \mathbb{C} of any type. For a Hessenberg subspace M, consider the map $\pi_M : G \times^B M \longrightarrow \mathfrak{g}$ again. Let \mathfrak{g}^{rs} denote the Zariski open dense subset of \mathfrak{g} consisting of regular semisimple elements and $\underline{\mathbb{C}}$ denote the constant sheaf over $G \times^B M$. Results from De Mari et al. [1992] show that the direct push-forward complex $R\pi_{M*}\mathbb{C}|_{\mathfrak{g}^{rs}}$, considered as an object of the constructible bounded derived category $D_c^b(\mathfrak{g}^{rs})$, is equivalent to a local system over \mathfrak{g}^{rs} . The local system corresponds to a monodromy action of $\pi_1(\mathfrak{g}^{rs}, y)$ on $H^*(\operatorname{Hess}(M, y))$ after picking a base-point $y \in \mathfrak{g}^{rs}$. The following theorem was first stated and proved for type A in Brosnan & Chow [2018][Theorem 73], and generalized to all other types in Bălibanu & Crooks [2020][Corollary 1.14].

Theorem 5.2.1. The monodromy action of $\pi_1(\mathfrak{g}^{rs}, y)$ on $H^*(\operatorname{Hess}(M, y))$ factors through the Weyl group W and coincides with Tymoczko's dot action.

From now on, we will not distinguish between the monodromy action above and Tymoczko's original definition via moment graph, and will refer to both of them simply as the dot action of W on $H^*(\text{Hess}(M, y))$. In particular, the theorem above implies that the dot action on $H^*(\text{Hess}(M, y))$ does not depend on the choice of the regular semisimple element y.

Let d denote the complex dimension of $G \times^B M$. Since $G \times^B M$ is a vector

bundle over G/B, it is nonsingular and we can therefore apply the decomposition theorem of Beilinson, Bernstein and Deligne to $R\pi_{M*}\mathbb{C}[d]$. Brosnan has the following conjecture.

Conjecture 5.2.2 (Brosnan). $R\pi_{M*}\mathbb{C}[d]$ is a direct sum of shifted intermediate extensions of irreducible local systems on \mathfrak{g}^{rs} . That is, we have the following decomposition,

$$R\pi_{M*}\underline{\mathbb{C}}[d] = \bigoplus \operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \mathcal{V}_i)[a_i]$$
(5.4)

where each \mathcal{V}_i is an irreducible local system on \mathfrak{g}^{rs} and $\mathrm{IC}(\overline{\mathfrak{g}^{rs}}, \mathcal{V}_i)$ is the intermediate extension of $\mathcal{V}_i[\dim\mathfrak{g}]$ from \mathfrak{g}^{rs} to $\mathfrak{g} = \overline{\mathfrak{g}^{rs}}$. Moreover, for any $y \in \mathfrak{g}^{rs}$, the monodromy action of $\pi_1(\mathfrak{g}^{rs}, y)$ on the stalk $\mathcal{V}_{i,y}$ factors through the Weyl group W.

We are going to prove the conjecture independently for type G_2 later in this section, which will be sufficient for our computation of dot actions.

When the conjecture above is true, taking cohomology of both sides of Equation 5.4 at $y \in \mathfrak{g}^{rs}$ and ignoring shifting, we get the decomposition of the dot action of W on $H^*(\operatorname{Hess}(M, y))$ as a direct sum of irreducible W representations: $H^*(\operatorname{Hess}(M, y)) \cong \bigoplus \mathcal{V}_{i,y}$. Therefore, Tymoczko's dot action is determined by the decomposition of the complex $R\pi_{M*}\mathbb{C}[d]$.

On the other hand, Hessenberg subspace is the natural "dual" notion of Hessenberg ideal. Recall that a Hessenberg ideal is an $\operatorname{ad}(\mathfrak{b})$ -stable subspace I of \mathfrak{u} , where \mathfrak{u} is the Lie algebra of the unipotent radical U of B. There is a one-one correspondence between Hessenberg subspaces and Hessenberg ideals denoted by $M \mapsto I = M^{\perp}$. To understand the correspondence, choose a maximal torus T in B. Let Φ denote the set of roots and \mathfrak{g}_{α} denote the root space corresponding to $\alpha \in \Phi$ as before. It is easy to see that M and I have root space decompositions for certain subsets $\Phi(M)$ and $\Phi(I)$ of Φ :

$$M \cong \mathfrak{t} \oplus \bigoplus_{\alpha \in \Phi(M)} \mathfrak{g}_{\alpha} \text{ and } I \cong \bigoplus_{\alpha \in \Phi(I)} \mathfrak{g}_{\alpha},$$

where \mathfrak{t} is the Lie algebra of the maximal torus T. Then $I = M^{\perp}$ if and only if $\Phi(I) = -(\Phi \setminus \Phi(M))$. In the rest of this chapter, unless otherwise specified, M and I are always assumed to satisfy the relation $I = M^{\perp}$ as explained above.

Recall the following map defined in the very beginning of chapter 1.

$$\pi_I: \ G \times^B I \longrightarrow \mathfrak{g}$$
$$(g, x) \longmapsto g \cdot x$$

Let $N \in \mathcal{N}$ be an element in the image of π_I . The fiber of π_I over N, $\pi_I^{-1}(N)$, is a Hessenberg ideal fiber. Let $G \times \mathbb{G}_m$ act on \mathfrak{g} with G acting via the adjoint action and \mathbb{G}_m acting by scaling. By fixing a Killing form, we get an autoequivalence F, the Fourier-Sato transform, from the category $\operatorname{Perv}_{G \times \mathbb{G}_m}(\mathfrak{g})$ of $G \times \mathbb{G}_m$ -equivariant perverse sheaves on \mathfrak{g} to itself. Let d^{\vee} denote the complex dimension of $G \times^B I$. We know that $F(R\pi_{M*}\mathbb{C}[d]) = R\pi_{I*}\mathbb{C}[d^{\vee}]$ and F maps a simple summand of $R\pi_{M*}\mathbb{C}[d]$ to a simple summand of $R\pi_{I*}\mathbb{C}[d^{\vee}]$ (see Bălibanu & Crooks [2020][section 2.2]). $R\pi_{I*}\mathbb{C}[d^{\vee}]$ is supported on the nilpotent cone $\mathcal{N} \subset \mathfrak{g}$, and the $G \times \mathbb{G}_m$ -orbits in \mathcal{N} and the equivariant perverse sheaves on these nilpotent orbits are very wellunderstood (as they are the main subject of Springer theory). Since $G \times^B I$ is nonsingular, we can apply the decomposition theorem to $R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$ and get

$$R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}] = \bigoplus_{(N,\mathcal{L})} \operatorname{IC}(\overline{C(N)}, \mathcal{L})[b_{N,\mathcal{L}}]$$
(5.5)

where $N \in \mathcal{N}$ is a nilpotent element, C(N) is the conjugacy class (nilpotent orbit) of N, \mathcal{L} is an irreducible G-equivariant local system on C(N), $\mathrm{IC}(\overline{C(N)}, \mathcal{L})$ is the intermediate extension of $\mathcal{L}[\dim C(N)]$ from C(N) to $\overline{C(N)}$ and $b_{N,\mathcal{L}}$ is an integer for shifting. The pairs (N, \mathcal{L}) appearing in the sum are determined by \mathfrak{g} and I. Applying the Fourier-Sato transform F (which is an autoequivalence) to both sides of Equation 5.5 and comparing it to Equation 5.4, we see that for each summand $\mathrm{IC}(\overline{C(N)}, \mathcal{L})$ of $R\pi_{I*}\mathbb{C}[d^{\vee}]$, $F(\mathrm{IC}(\overline{C(N)}, \mathcal{L})) = \mathrm{IC}(\overline{\mathfrak{g}^{rs}}, \mathcal{V}_i)$, where the right hand side is a certain summand of $R\pi_{M*}\mathbb{C}[d]$. Moreover, the correspondence

$$\mathcal{V}_{i,y} \mapsto \mathrm{IC}(\overline{C(N)}, \mathcal{L})$$
 such that $F(\mathrm{IC}(\overline{C(N)}, \mathcal{L})) = \mathrm{IC}(\overline{\mathfrak{g}^{rs}}, \mathcal{V}_i)$

is exactly the Springer correspondence that sends the trivial representation of W to $IC(\{0\}, \underline{\mathbb{C}})$. Now we have reduced the problem of computing the dot action of W on $H^*(Hess(M, y))$ to the decomposition of $R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$ into simple summands. That is, if we know the decomposition of $R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$, applying the Springer correspondence (whose G_2 case will be explicitly given shortly), we get the decomposition of the dot action on $H^*(Hess(M, y))$ as a direct sum of irreducible W representations. Note that if a nilpotent element $N \in \mathcal{N}$ is in the image of π_I , $H^*(R\pi_{I*}\underline{\mathbb{C}}|_N) =$ $H^*(\pi_I^{-1}(N))$. This is where the knowledge of Hessenberg ideal fibers, in particular the results from chapter 4, enters the computation of dot actions.

We briefly recall the theory of Springer correspondence. For simplicity, assume that G is a connected simple algebraic group over \mathbb{C} of the adjoint form. Since both Hessenberg varieties and Hessenberg ideal fibers are subvarieties of G/B defined via subspaces of the Lie algebra \mathfrak{g} , different choices of the group G does not affect them as long as G is of the same type. The theory of Springer correspondence states that:

Theorem (Borho & MacPherson [1983], p. 48, section 2.2). Let W be the Weyl group of G, Irr(W) be the set of isomorphic classes of irreducible W representations and $\{(N, \psi)\}/G$ be the G-conjugacy classes of pairs (N, ψ) where N is a nilpotent element and ψ is an irreducible character of $A(N) = C_G(N)/C_G^{\circ}(N)$. Then there is a meaningful injection $Irr(W) \longrightarrow \{(N, \psi)\}/G$.

Since Springer's original paper Springer [1976], several different constructions of the Springer correspondence have arisen. They result in two different versions of the map $\operatorname{Irr}(W) \longrightarrow \{(N, \psi)\}/G$, which differ from each other by tensoring with the sign representation of W. The one constructed via the Fourier-Sato transform, which is used here, is characterized by sending the trivial representation of W to the pair $(0, \mathbf{1})$, where $0 \in \mathfrak{g}$ is the nilpotent element and $\mathbf{1}$ is the trivial representation of the trivial group. For any nilpotent element N, the set of irreducible G-equivariant local systems over the conjugacy class C(N) is classified by the set of irreducible characters of A(N). Therefore, there is a bijection between the set $\{(N, \psi)\}/G$ and the following set of simple $G \times \mathbb{G}_m$ -equivariant IC-sheaves supported over the nilpotent cone \mathcal{N} :

$${\rm IC}(\overline{C(N)},\mathcal{L}) \mid \mathcal{L}$$
 is a *G*-equivariant irreducible local system over $C(N)$.

In particular, the pair (0, 1) corresponds to $IC(\{0\}, \underline{\mathbb{C}})$ under this bijection.

Next we explicitly describe the Springer correspondence for type G_2 . In the rest of this chapter, let G denote the adjoint form of type G_2 . We assume the same presentation of G as in section 4.1. The character table of the Weyl group W of G_2 is given in Table 5.1, which is taken from Carter [1985][p. 412] with new character names added in the first column. The nilpotent orbits and their respective dimensions are recalled in Table 5.2. Their closure relationship is simple: the closure of any nilpotent orbit is the union of itself and all the other lower dimensional orbits. The Springer correspondence for type G_2 is given in Table 5.3, which is obtained from Carter [1985][p. 427] after tensoring with the sign representation ϵ and adding two additional columns for the IC-sheaves. The original table from Carter [1985][p. 427] gives the version of Springer correspondence that sends the sign representation ϵ of W to the pair (0, 1), and that is why we tensor its last column with the sign representation in order to get Table 5.3.

	1	s	t	st	$(st)^2$	$(st)^3$
$1 = \phi_{1,0}$	1	1	1	1	1	1
$\epsilon_1 = \phi'_{1,3}$	1	1	-1	-1	1	-1
$\epsilon_2 = \phi_{1,3}''$	1	-1	1	-1	1	-1
$\epsilon = \phi_{1,6}$	1	-1	-1	1	1	1
$\chi_1 = \phi_{2,1}$	2	0	0	1	-1	-2
$\chi_2 = \phi_{2,2}$	2	0	0	-1	-1	2

Table 5.1: Character table of $W(G_2)$

Table 5.2: Nilpotent orbits for type G_2					
orbit	{0}	A_1	\tilde{A}_1	$G_2(a_1)$	G_2
dimension	0	6	8	10	12

Table 5.3: Springer correspondence for type G_2

nilpotent	$\Lambda(N)$	character character		IC-sheaf	IC-sheaf
orbit	A(N)	of $A(N)$	of W	over \mathcal{N}	over \mathfrak{g}
{0}	1	1	1	$\operatorname{IC}(\{0\},\underline{\mathbb{C}})$	$\operatorname{IC}(\overline{\mathfrak{g}^{rs}},1)$
A_1	1	1	ϵ_1	$\operatorname{IC}(A_1, \underline{\mathbb{C}})$	$\operatorname{IC}(\overline{\mathfrak{g}^{rs}},\epsilon_1)$
$ ilde{A}_1$	1	1	χ_2	$\mathrm{IC}(\tilde{A}_1,\underline{\mathbb{C}})$	$\operatorname{IC}(\overline{\mathfrak{g}^{rs}},\chi_2)$
$G_2(a_1)$ S_3		ψ_3	χ_1	$\operatorname{IC}(G_2(a_1),\psi_3)$	$\operatorname{IC}(\overline{\mathfrak{g}^{rs}},\chi_1)$
	S_3	ψ_{21}	ϵ_2	$\mathrm{IC}(G_2(a_1),\psi_{21})$	$\operatorname{IC}(\overline{\mathfrak{g}^{rs}},\epsilon_2)$
		ψ_{111}		$\mathrm{IC}(G_2(a_1),\psi_{111})$	
G_2	1	1	ϵ	$\mathrm{IC}(G_2,\underline{\mathbb{C}})$	$\operatorname{IC}(\overline{\mathfrak{g}}^{rs},\epsilon)$

A few words on the reading of Table 5.3. From every row of the table, we get a pair (N, ψ) from the 1st and 3rd column. The character χ of the irreducible W representation corresponding to the pair is in the 4th column. The IC-sheaf supported over \mathcal{N} in the 5th column corresponds to the pair (N, ψ) as previously explained. The IC-sheaf supported over $\mathfrak{g} = \overline{\mathfrak{g}^{rs}}$ in the 6th column corresponds to χ after picking a base point (see Conjecture 5.2.2). In particular, the Fourier-Sato transform F always takes the 5th column to the 6th column and vice versa. A(N) is the trivial group except for the orbit $G_2(a_1)$, for which the irreducible characters ψ_3 , ψ_{21} and ψ_{111} are respectively indexed by the partions (3), (2, 1) and (1, 1, 1) of 3. ψ_3 is the trivial representation, ψ_{111} is the sign representation and $\psi_3 + \psi_{21}$ is the natural 3-dimensional permutation representation of S_3 . By abuse of notation, we also use ψ_3 , ψ_{21} and ψ_{111} to denote their corresponding G-equivariant irreducible

local systems over the nilpotent orbit $G_2(a_1)$ in the 5th column. The two blank boxes in the table means that the pair $(G_2(a_1), \psi_{111})$ does not correspond to any irreducible W representation under the Springer correspondence, and that $F(\text{IC}(G_2(a_1), \psi_{111}))$ is an IC-sheaf supported on a proper closed subset of \mathfrak{g} , that is to say, it is not the intermediate extension of an irreducible local system on \mathfrak{g}^{rs} .

Besides the techniques of Fourier-Sato transform and Springer correspondence summarized above, we need the following results for our computation. Except for Lemma 5.2.4, they are true for connected reductive algebraic group G in general.

Lemma 5.2.3. Let I be a Hessenberg ideal and N be an element from the maximal nilpotent orbit contained in the image of $\pi_I : G \times^B I \longrightarrow \mathfrak{g}$. Restricting both sides of Equation 5.5 to the point N, taking cohomology of both sides and ignoring the shiftings, we get the isomorphism $H^*(\pi_I^{-1}(N)) \cong \bigoplus \mathcal{L}_N$, where the direct sum is taken over those \mathcal{L} 's supported on the very orbit of C(N) (not on a smaller orbit than C(N)). Then the isomorphism is A(N)-equivariant with respect to the natural A(N) actions on both sides.

Proof. If shiftings are ignored, the isomorphism of vector spaces $H^*(\pi_I^{-1}(N)) \cong \bigoplus \mathcal{L}_N$ follows directly from the isomorphism of complexes in Equation 5.5. By the definition of $\pi_I^{-1}(N)$ in Equation 1.1, it is clear that $C_G(N)$ acts on $\pi_I^{-1}(N) \subset G/B$ by left multiplication. The actions of $A(N) = C_G(N)/C_G^{\circ}(N)$ on both sides of the isomorphism $H^*(\pi_I^{-1}(N)) \cong \bigoplus \mathcal{L}_N$ are induced by actions of $C_G(N)$ on the underlying varieties $\pi_I^{-1}(N)$ and C(N), hence they respect the isomorphism. In addition, in the case of type G_2 , the only nontrivial case is when N comes from the

orbit $G_2(a_1)$, where the actions of $A(N) \cong S_3$ on the $H^*(\pi_I^{-1}(N))$'s are explicitly described in Remark 4.3.2.

Lemma 5.2.4 (Xue). Conjecture 5.2.2 is true when G is the adjoint form of type G_2 .

Proof. Since $F(R\pi_{M*}\mathbb{C}[d]) = R\pi_{I*}\mathbb{C}[d^{\vee}]$, Conjecture 5.2.2 is equivalent to the claim that every summand $\operatorname{IC}(\overline{C(N)}, \mathcal{L})$ in $R\pi_{I*}\mathbb{C}[d^{\vee}] = \bigoplus \operatorname{IC}(\overline{C(N)}, \mathcal{L})[b_{N,\mathcal{L}}]$ comes from some irreducible W representation via the Springer correspondence (shiftings ignored). In the case of type G_2 , according to Table 5.3, it means that $\operatorname{IC}(G_2(a_1), \psi_{111})$ is not a summand of any $R\pi_{I*}\mathbb{C}[d^{\vee}]$.

For IC($G_2(a_1), \psi_{111}$) to be a summand of $R\pi_{I*}\mathbb{C}[d^{\vee}]$ at all, the image of π_I has to contain the orbit $G_2(a_1)$ in the first place. According to Table 4.1, such an I can only be $I_{\beta+\alpha}, I_{\beta}, I_{\alpha}$ or $I_{\alpha,\beta}$.

When $I = I_{\alpha,\beta} = \mathfrak{u}, \pi_I : G \times^B I \longrightarrow \mathcal{N}$ is the Springer resolution of the nilpotent cone \mathcal{N} , and the decomposition of $R\pi_{I*}\mathbb{C}[d^{\vee}]$ is well-known: every summand of it does come from some irreducible W representation via the Springer correspondence. In fact, Borho and MacPherson constructed Springer correspondence via this decomposition (see Borho & MacPherson [1983]).

When $I = I_{\beta+\alpha}$, I_{β} or I_{α} , $G_2(a_1)$ is the maximal nilpotent orbit contained in the image of π_I . Let N be an element of $G_2(a_1)$. From Remark 4.3.2, we deduce that the actions of $A(N) \cong S_3$ on the $H^i(\pi_I^{-1}(N))$'s (i = 0, 2) are either the trivial representation or the 3-dimensional permutation representation. In the light of Lemma 5.2.3, $IC(G_2(a_1), \psi_{111})$ can never be a summand of $R\pi_{I*}\mathbb{C}[d^{\vee}]$, because ψ_{111} , being the sign representation, can never be a subrepresentation of either the trivial or the permutation representation.

We have now finished the proof of the lemma.

Proposition 5.2.5 (Brosnan).

- (1) Let M be a Hessenberg subspace, $y \in \mathfrak{g}^{rs}$ a regular semisimple element, $n = \dim_{\mathbb{C}} \operatorname{Hess}(M, y)$ and $\eta \in H^2(G/B)$ be the first Chern class of a hyperplane line bundle over G/B that is invariant under the dot action by W. Then the cup product map $\eta \wedge : H^i(\operatorname{Hess}(M, y)) \longrightarrow H^{i+2}(\operatorname{Hess}(M, y))$ respects the dot action. As a result, $\eta^i \wedge : H^{n-i}(\operatorname{Hess}(M, y)) \longrightarrow H^{n+i}(\operatorname{Hess}(M, y))$ is an isomorphism of dot actions. In short, the dot action is compatible with the Hard Lefschetz theorem.
- (2) The action of W on H⁰(Hess(M, y)) is a permutation representation for any Hessenberg subspace M and regular semisimple element y. As a result, if dim_ℂ H⁰(Hess(M, y)) = 1, it is the trivial representation.
- (3) Let N and M be two Hessenberg subspaces with $N \subset M$. If $\operatorname{Hess}(N, y)$ is connected, the restriction map $H^2(\operatorname{Hess}(M, y)) \longrightarrow H^2(\operatorname{Hess}(N, y))$ is injective and respects the dot action.

Proof. Let η_0 be the first Chern class of an arbitrary hyperplane line bundle over G/B. Since the Weyl group W is finite, we can define $\eta = \sum_{\sigma \in W} \sigma \cdot \eta_0$, which is clearly a W-invariant first Chern class. From Tymoczko's definition of the dot action in terms of moment graphs and equivariant cohomology (see Tymoczko [2007]), it

is clear that the dot action respects cup product. Therefore, claim (1) follows from the usual Hard Lefschetz theorem.

Claim (2) and (3) also follow easily from Tymoczko's definition. \Box

Theorem 5.2.6 (Brosnan & Chow [2018], Theorem 76). Let G be a connected reductive algebraic group over \mathbb{C} and $x_J \in \mathfrak{g}$ be a regular element. Take the Jordan decomposition $x_J = s_J + n_J$ where s_J is semisimple and n_J is nilpotent. Then the centralizer $C_{\mathfrak{g}}(s_J)$ is a Levi subalgebra of \mathfrak{g} and n_J is a regular nilpotent element of $C_{\mathfrak{g}}(s_J)$. Let W_J denote the Weyl group of $C_{\mathfrak{g}}(s_J)$. Let M be a Hessenberg subspace of \mathfrak{g} and $y \in \mathfrak{g}$ be a regular semisimple element. We have

$$\dim_{\mathbb{C}} H^{i}(\operatorname{Hess}(M, x_{J})) = \dim_{\mathbb{C}} H^{i}(\operatorname{Hess}(M, y))^{W_{J}}$$

for all i.

Theorem 5.2.6 is proved in Brosnan & Chow [2018] only for type A, but it can be generalized to other types without difficulty. Note that $\operatorname{Hess}(M, x_J)$ is the Hessenberg variety associated to a regular element x_J , so it is different from our main object of study—regular semisimple Hessenberg variety $\operatorname{Hess}(M, y)$. In general, $\operatorname{Hess}(M, x_J)$ is not smooth, but Precup [2013] shows that it is still paved by affines and gives formula for $H^*(\operatorname{Hess}(M, x_J))$.

5.3 Computation

In this section, we fix G to be the adjoint form of type G_2 and compute the dot action of W on $H^*(\text{Hess}(M, y))$ for any Hessenberg subspace M. To be specific, we decompose the character of each $H^{2i}(\text{Hess}(M, y))$ as a direct sum of irreducible characters of W (listed in Table 5.1). Note that $H^*(\text{Hess}(M, y))$ are supported on the even degrees because it is paved by affines. Besides the same setups for G_2 as in section 4.1, we introduce the following notational conventions.

Let $M \subset \mathfrak{g}$ denote a Hessenberg subspace in general and $I \subset \mathfrak{u}$ denote the Hessenberg ideal "dual" to M. That is, $I = M^{\perp}$ and $M \cong \mathfrak{t} \oplus \bigoplus_{\alpha \in \Phi(M)} \mathfrak{g}_{\alpha}$, $I \cong \bigoplus_{\alpha \in \Phi(I)} \mathfrak{g}_{\alpha}$, where $\Phi(I) = -(\Phi \setminus \Phi(M))$. Let $y \in \mathfrak{g}$ be a regular semisimple element. We define the Poincaré polynomial of $\operatorname{Hess}(M, y)$ to be

$$P_M(q) = \sum_{i=0}^n \chi_{H^{2i}(\text{Hess}(M,y))} q^i, \ \deg(q) = 2,$$

where $n = \dim_{\mathbb{C}} \operatorname{Hess}(M, y)$ and the coefficient $\chi_{H^{2i}(\operatorname{Hess}(M, y))}$ is the character of $H^{2i}(\operatorname{Hess}(M, y))$ as a W representation.

We can easily enumerate all the Hessenberg ideals. Using the same notation as in section 4.1, they are I_{\emptyset} , $I_{2\beta+3\alpha}$, $I_{\beta+3\alpha}$, $I_{\beta+2\alpha}$, $I_{\beta+\alpha}$, I_{α} , I_{β} and $I_{\alpha,\beta}$.

To state the plan for computation in more details, we need the following simple lemma.

Lemma 5.3.1. Let G be the adjoint form of type G_2 .

(1) $\dim_{\mathbb{C}} \mathfrak{g} = 14$, $\dim_{\mathbb{C}} \mathfrak{b} = 8$ and $\dim_{\mathbb{C}} \mathfrak{u} = 6$.

- (2) $d^{\vee} = \dim_{\mathbb{C}}(G \times^B I) = 6 + |\Phi(I)|$ and $d = \dim_{\mathbb{C}}(G \times^B M) = 20 |\Phi(I)|$, where $|\Phi(I)|$ is the order of $\Phi(I)$.
- (3) $n = \dim_{\mathbb{C}} \operatorname{Hess}(M, y) = 6 |\Phi(I)|.$
- (4) Let χ be an irreducible character of W. If $\operatorname{IC}(\overline{C(N)}, \mathcal{L}) = F(\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi))$ and $\operatorname{IC}(\overline{C(N)}, \mathcal{L})[b]$ is a direct summand of $R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$, then $\chi q^{(d-b-14)/2}$ is a summand of $P_M(q)$.
- (5) $\sum_{i=0}^{n} \dim_{\mathbb{C}} H^{2i}(\text{Hess}(M, y)) = 12.$
- *Proof.* (1) and (2) are straightforward.

For (3), by De Mari et al. [1992][Theorem 6], $\dim_{\mathbb{C}} \operatorname{Hess}(M, y) = \dim_{\mathbb{C}} M/\mathfrak{b} = \dim_{\mathbb{C}} \mathfrak{g} - \dim_{\mathbb{C}} I - \dim_{\mathbb{C}} \mathfrak{b} = 14 - |\Phi(I)| - 8 = 6 - |\Phi(I)|.$

For (4), since $R\pi_{M*}\underline{\mathbb{C}}[d] = F(R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}])$, if $\operatorname{IC}(\overline{C(N)}, \mathcal{L})[b]$ is a direct summand of $R\pi_{I*}\underline{\mathbb{C}}[d^{\vee}]$, $\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)[b] = F(\operatorname{IC}(\overline{C(N)}, \mathcal{L})[b])$ is a direct summand of $R\pi_{M*}\underline{\mathbb{C}}[d]$. Hence $\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)[b - d]$ is a direct summand of $R\pi_{M*}\underline{\mathbb{C}}$. Restricting both to the point y and taking cohomology, we deduce that $H^{2i+b-d}(\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)|_y)$ is a W subrepresentation of $H^{2i}(\operatorname{Hess}(M, y))$ for any $i \in \mathbb{Z}$. By the definition of IC-sheaves, $\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)|_{\mathfrak{g}^{rs}} \cong \chi[\dim_{\mathbb{C}} \mathfrak{g}] = \chi[14]$, so $H^{2i+b-d}(\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)|_y)$ is nonzero only when 2i + b - d = -14. In this case, i = (d - b - 14)/2 and $\chi \cong H^{-14}(\operatorname{IC}(\overline{\mathfrak{g}^{rs}}, \chi)|_y)$ is a subrepresentation of $H^{2i}(\operatorname{Hess}(M, y))$. Therefore $\chi q^i = \chi q^{(d-b-14)/2}$ is a summand of $P_M(q)$. By abuse of notation, we also used χ to denote its corresponding irreducible local system over \mathfrak{g}^{rs} and irreducible W representation.

For (5), according to De Mari et al. [1992], $\operatorname{Hess}(M, y)$ is paved by affines with the set of cells in bijection with W. Hence $\sum_{i=0}^{n} \dim_{\mathbb{C}} H^{2i}(\operatorname{Hess}(M, y)) = |W| =$ Our plan for computation is the following:

- (1) Start from the smallest Hessenberg ideal $I = I_{\emptyset}$ and compute $P_M(q)$ in the increasing order of dim_C I.
- (2) The previous results, combined with Proposition 5.2.5, provide certain summands of the new $P_M(q)$ immediately.
- (3) Let N be an element from the maximal nilpotent orbit contained in the image of $\pi_I : G \times^B I \longrightarrow \mathfrak{g}$. In the light of Lemma 5.2.3 and Lemma 5.3.1 (4), we obtain some new summands of $P_M(q)$ by inspecting $H^*(\pi_I^{-1}(N))$.
- (4) If the total dimension of the summands above is already 12, according to Lemma 5.3.1 (5), we have the complete $P_M(q)$. Otherwise we bring in Theorem 5.2.6 to figure out the rest of the summands.
- $I = I_{\emptyset}$

In this case, $M = \mathfrak{g}$ and the map $\pi_M : G \times^B M \longrightarrow \mathfrak{g}$ is isomorphic to the projection $\operatorname{pr}_2 : G/B \times \mathfrak{g} \longrightarrow \mathfrak{g}$. Then $\operatorname{Hess}(M, y) \cong G/B$ and $R\pi_{M*}\mathbb{C}[d]|_{\mathfrak{g}^{rs}}$ is a constant sheaf with fibers isomorphic to $H^*(G/B)$. Therefore, every $H^{2i}(\operatorname{Hess}(M, y))$ is the trivial representation of W and we can figure out $P_M(q)$ from the cell structure of G/B. In fact, $P_M(q) = \mathbf{1} + \mathbf{2}q + \mathbf{2}q^2 + \mathbf{2}q^3 + \mathbf{2}q^4 + \mathbf{2}q^5 + \mathbf{1}q^6$, where $\mathbf{1}$ denotes the trivial representation of W and $\mathbf{2}$ denotes $\mathbf{1} \oplus \mathbf{1}$.

•
$$I = I_{2\beta+3\alpha}$$

In this case, $|\Phi(I)| = 1$. By Lemma 5.3.1, d = 19, $d^{\vee} = 7$, $n = \dim_{\mathbb{C}} \operatorname{Hess}(M, y) =$ 5. From De Mari et al. [1992][Corollary 9], it follows easily that $\operatorname{Hess}(M, y)$ is connected. (In fact, $\operatorname{Hess}(M, y)$ is connected for $I = I_{\emptyset}$, $I_{2\beta+3\alpha}$, $I_{\beta+3\alpha}$, $I_{\beta+2\alpha}$, $I_{\beta+\alpha}$). By Proposition 5.2.5 (2), $H^0(\operatorname{Hess}(M, y)) \cong \mathbf{1}$. Using the H^2 term of the previous case (when $I = I_{\emptyset}$), we deduce by Proposition 5.2.5 (3) that $H^2(\operatorname{Hess}(M, y))$ has **2** as a subrepresentation. Now Proposition 5.2.5 (1) implies that $P_M(q)$ must have $\mathbf{1} + \mathbf{2}q + \mathbf{2}q^2 + \mathbf{2}q^3 + \mathbf{2}q^4 + \mathbf{1}q^5$ as summands. By Lemma 5.3.1 (5), there are only 2 additional dimensions that remain to be figured out.

We know from Table 4.1 that A_1 is the maximal nilpotent orbit contained in the image of $\pi_I : G \times^B I \longrightarrow \mathfrak{g}$. Let N be an element from A_1 . Then $\pi_I^{-1}(N) = \overline{X_s} \cong \mathbb{P}^1$. Hence we have $H^*(\pi_I^{-1}(N)) = \mathbb{C}[0] \oplus \mathbb{C}[-2]$ and $H^*(R\pi_{I*}\mathbb{C}[7]|_N) = \mathbb{C}[7] \oplus \mathbb{C}[5]$. Since A_1 is the maximal orbit contained in the image of π_I , $R\pi_{I*}\mathbb{C}[7]$ is the direct sum of shifted copies of IC($\{0\}, \mathbb{C}$) and IC(A_1, \mathbb{C}). We know that IC(A_1, \mathbb{C}) $|_N \cong \mathbb{C}[6]$ and IC($\{0\}, \mathbb{C}$) $|_N \cong 0$. Because the decomposition of $R\pi_{I*}\mathbb{C}[7]$ satisfies the Hard Lefschetz theorem (see Deligne et al. [1982][Théorème 6.2.10]), IC(A_1, \mathbb{C})[1] and IC(A_1, \mathbb{C})[-1] must be the only summands of $R\pi_{I*}\mathbb{C}[7]$ supported on A_1 . All the other summands are shifted copies of IC($\{0\}, \mathbb{C}$). By Lemma 5.3.1 (4) and Table 5.3, IC(A_1, \mathbb{C})[1] and IC(A_1, \mathbb{C})[-1] correspond to the summands $\epsilon_1 q^2 + \epsilon_1 q^3$ of $P_M(q)$, which are the 2 additional dimensions expected from the previous paragraph. As a result, $P_M(q) = \mathbf{1} + \mathbf{2}q + (\mathbf{2} + \epsilon_1)q^2 + (\mathbf{2} + \epsilon_1)q^3 + \mathbf{2}q^4 + \mathbf{1}q^5$.

• $I = I_{\beta+3\alpha}$

In this case, $|\Phi(I)| = 2$, d = 18, $d^{\vee} = 8$, n = 4. Hess(M, y) is still connected. Arguing with Proposition 5.2.5 in the same manner as the previous case, we deduce that $P_M(q)$ must have summands $\mathbf{1} + \mathbf{2}q + \mathbf{2}q^2 + \mathbf{2}q^3 + \mathbf{1}q^4$. There are 4 additional dimensions to be figured out.

According to Table 4.1, A_1 is still the maximal nilpotent orbit contained in the image of π_I . Let N be an element from A_1 . Then $\pi_I^{-1}(N) = \overline{X_{st}}$. Hence we have $H^*(\pi_I^{-1}(N)) = \mathbb{C}[0] \oplus \mathbb{C}^2[-2] \oplus \mathbb{C}[-4]$ and $H^*(R\pi_{I*}\mathbb{C}[8]|_N) = \mathbb{C}[8] \oplus \mathbb{C}^2[6] \oplus \mathbb{C}[4]$. $R\pi_{I*}\mathbb{C}[8]$ is still the direct sum of shifted copies of IC (A_1, \mathbb{C}) and IC $(\{0\}, \mathbb{C})$, and IC $(A_1, \mathbb{C})|_N \cong \mathbb{C}[6]$, IC $(\{0\}, \mathbb{C})|_N \cong 0$. By the same Hard Lefschetz argument, $R\pi_{I*}\mathbb{C}[8]$ must have summands IC $(A_1, \mathbb{C})[2]$, IC $(A_1, \mathbb{C})[-2]$ and IC $(A_1, \mathbb{C})^{\oplus 2}$. By Lemma 5.3.1 (4) and Table 5.3, they correspond to the summands $\epsilon_1q + \epsilon_1q^3 + 2\epsilon_1q^2$, which are exactly the 4 additional dimensions. Hence $P_M(q) = \mathbf{1} + (\mathbf{2} + \epsilon_1)q + (\mathbf{2} + 2\epsilon_1)q^2 + (\mathbf{2} + \epsilon_1)q^3 + \mathbf{1}q^4$, where $2\epsilon_1$ means $\epsilon_1 \oplus \epsilon_1$.

• $I = I_{\beta+2\alpha}$

In this case, $|\Phi(I)| = 3$, d = 17, $d^{\vee} = 9$, n = 3. Hess(M, y) is connected. Similarly, $P_M(q)$ must have summands $\mathbf{1} + (\mathbf{2} + \epsilon_1)q + (\mathbf{2} + \epsilon_1)q^2 + \mathbf{1}q^3$. There are 4 additional dimensions to be figured out.

Now \tilde{A}_1 is the maximal orbit contained in the image of π_I . Let N be an element from \tilde{A}_1 . $\pi_I^{-1}(N) = \overline{X}_t \cong \mathbb{P}^1$. Hence we have $H^*(\pi_I^{-1}(N)) = \mathbb{C}[0] \oplus$ $\mathbb{C}[-2]$ and $H^*(R\pi_{I*}\mathbb{C}[9]|_N) = \mathbb{C}[9] \oplus \mathbb{C}[7]$. $R\pi_{I*}\mathbb{C}[9]$ is the direct sum of shifted copies of IC(\tilde{A}_1, \mathbb{C}), IC(A_1, \mathbb{C}) and IC($\{0\}, \mathbb{C}$), and IC(\tilde{A}_1, \mathbb{C})|_N $\cong \mathbb{C}[8]$. Therefore, IC(\tilde{A}_1, \mathbb{C})[1] and IC(\tilde{A}_1, \mathbb{C})[-1] are the only summands of $R\pi_{I*}\mathbb{C}[9]$ supported on \tilde{A}_1 . They correspond to the summands $\chi_2 q + \chi_2 q^2$, the 4 additional dimensions. Then $P_M(q) = \mathbf{1} + (\mathbf{2} + \epsilon_1 + \chi_2)q + (\mathbf{2} + \epsilon_1 + \chi_2)q^2 + \mathbf{1}q^3$.

• $I = I_{\beta+\alpha}$

In this case, $|\Phi(I)| = 4$, d = 16, $d^{\vee} = 10$, n = 2. Hess(M, y) is connected. $P_M(q)$ must have summands $\mathbf{1} + (\mathbf{2} + \epsilon_1 + \chi_2)q + \mathbf{1}q^2$. There are 5 additional dimensions.

 $G_2(a_1)$ is the maximal orbit contained in the image of π_I . Let N be an element from $G_2(a_1)$. $\pi_I^{-1}(N) = \{3 \text{ distinct points}\}$ and $A(N) \cong S_3$ acts on $\pi_I^{-1}(N)$ by the natural permutation action (see Remark 4.3.2). Hence $H^*(\pi_I^{-1}(N)) = \mathbb{C}^3[0]$ and $H^*(R\pi_{I*}\mathbb{C}[10]|_N) = \mathbb{C}^3[10]$. A(N) acts on $H^*(R\pi_{I*}\mathbb{C}[10]|_N) = \mathbb{C}^3[10]$ by the permutation action (see Lemma 5.2.3). We know that $\mathrm{IC}(G_2(a_1), \psi_3)|_N \cong \mathbb{C}[10]$, $\mathrm{IC}(G_2(a_1), \psi_{21})|_N \cong \mathbb{C}^2[10]$ and that $\psi_3 + \psi_{21}$ is the 3-dimensional permutation representation of A(N). Therefore, $\mathrm{IC}(G_2(a_1), \psi_3)$ and $\mathrm{IC}(G_2(a_1), \psi_{21})$ must be the only summands of $R\pi_{I*}\mathbb{C}[10]$ supported on $G_2(a_1)$. They correspond to summands $(\chi_1 + \epsilon_2)q$. Up to now, $P_M(q)$ have summands $\mathbf{1} + (\mathbf{2} + \epsilon_1 + \chi_2 + \chi_1 + \epsilon_2)q + \mathbf{1}q^2$. There remains a 2-dimensional subrepresentation of $H^2(\mathrm{Hess}(M, y))$ to be figured out, which we denote by χ . Then $P_M(q) = \mathbf{1} + (\mathbf{2} + \epsilon_1 + \chi_2 + \chi_1 + \epsilon_2 + \chi)q + \mathbf{1}q^2$.

Since χ comes from IC-sheaves supported on nilpotent orbits strictly smaller than $G_2(a_1)$, it can be written as an integral combination $\chi = a\mathbf{1} + b\epsilon_1 + c\chi_2$. We will make a linear system of equations to solve for a, b and c.

Let J be any subset of the set of simple roots $\Delta = \{\alpha, \beta\}$ of G_2 . There always exists a semisimple element $s_J \in \mathfrak{g}$ such that $C_{\mathfrak{g}}(s_J)$ is a Levi subalgebra of \mathfrak{g} whose Weyl group is W_J . Let $n_J \in C_{\mathfrak{g}}(s_J)$ be a regular nilpotent element and define $x_J = s_J + n_J$. Then x_J is a regular element of \mathfrak{g} . According to Theorem 5.2.6, $\dim_{\mathbb{C}} H^2(\operatorname{Hess}(M, x_J)) = \dim_{\mathbb{C}} H^2(\operatorname{Hess}(M, y))^{W_J}$. Precup [2013][Corollary 5.8] tells us how to compute $\dim_{\mathbb{C}} H^*(\operatorname{Hess}(M, x_J))$ by inspecting the intersection of $\text{Hess}(M, x_J)$ with every Schubert cell of G/B, and the inspections are carried out in Appendix A. By Table A.1 and Table A.2, we have the following.

$$J = \{\alpha, \beta\}, \ W_J = W \quad J = \{\beta\}, \ W_J = \langle t \rangle$$
$$\dim_{\mathbb{C}} H^2(\text{Hess}(M, x_J)) \qquad 2 \qquad 6$$

On the other hand, $\dim_{\mathbb{C}} H^2(\operatorname{Hess}(M, y))^{W_J} = \langle \chi_{H^2(\operatorname{Hess}(M, y))}, \operatorname{Ind}_{W_J}^W \mathbf{1} \rangle$, where $\chi_{H^2(\operatorname{Hess}(M, y))}$ is the character of $H^2(\operatorname{Hess}(M, y))$ as a W representation and \langle , \rangle is the inner product of characters. So far we have the following information,

$$\begin{cases} \chi_{H^{2}(\text{Hess}(M,y))} = \mathbf{2} + \epsilon_{1} + \chi_{2} + \chi_{1} + \epsilon_{2} + \chi \\ \text{Ind}_{W}^{W} \mathbf{1} = \mathbf{1} \\ \text{Ind}_{\langle t \rangle}^{W} \mathbf{1} = \mathbf{1} + \epsilon_{2} + \chi_{1} + \chi_{2} \\ \langle \chi_{H^{2}(\text{Hess}(M,y))}, \text{Ind}_{W}^{W} \mathbf{1} \rangle = 2 \\ \langle \chi_{H^{2}(\text{Hess}(M,y))}, \text{Ind}_{\langle t \rangle}^{W} \mathbf{1} \rangle = 6 \\ \chi = a\mathbf{1} + b\epsilon_{1} + c\chi_{2} \\ \text{dim}_{\mathbb{C}} \chi = 2 \end{cases}$$

which can be turned into the following linear system of equations.

$$\begin{cases} a+2=2\\ a+2+1+1+1+c=6\\ a+b+2c=2 \end{cases}$$

We get a = 0, b = 0, c = 1. Therefore, $P_M(q) = \mathbf{1} + (\mathbf{2} + \epsilon_1 + 2\chi_2 + \chi_1 + \epsilon_2)q + \mathbf{1}q^2$.

• $I = I_{\alpha}$

In this case, $|\Phi(I)| = 5$, d = 15, $d^{\vee} = 11$, n = 1. Hess(M, y) is no longer connected, so Proposition 5.2.5 (3) does not apply. However, Proposition 5.2.5 (1) implies that $H^0(\text{Hess}(M, y))$ and $H^2(\text{Hess}(M, y))$ are isomorphic as W representations, hence $P_M(q)$ is divisible by (1 + q).

 $G_2(a_1)$ is the maximal orbit contained in the image of π_I . Let N be an element from $G_2(a_1)$. $\pi_I^{-1}(N) \cong \mathbb{P}^1 \amalg \mathbb{P}^1 \amalg \mathbb{P}^1$ and $A(N) \cong S_3$ acts on the set of irreducible components of $\pi_I^{-1}(N)$ by the natural permutation action (see Remark 4.3.2). Hence $H^*(\pi_I^{-1}(N)) = \mathbb{C}^3[0] \oplus \mathbb{C}^3[-2]$ and $H^*(R\pi_{I*}\mathbb{C}[11]|_N) = \mathbb{C}^3[11] \oplus \mathbb{C}^3[9]$, where A(N)acts on both $\mathbb{C}^3[11]$ and $\mathbb{C}^3[9]$ by the permutation action. Since $\operatorname{IC}(G_2(a_1), \psi_3)|_N \cong$ $\mathbb{C}[10]$, $\operatorname{IC}(G_2(a_1), \psi_{21})|_N \cong \mathbb{C}^2[10]$ and $\psi_3 + \psi_{21}$ is the 3-dimensional permutation representation of A(N), $\operatorname{IC}(G_2(a_1), \psi_3)[1]$, $\operatorname{IC}(G_2(a_1), \psi_{21})[1]$, $\operatorname{IC}(G_2(a_1), \psi_3)[-1]$ and $\operatorname{IC}(G_2(a_1), \psi_{21})[-1]$ are the only summands of $R\pi_{I*}\mathbb{C}[11]$ supported on $G_2(a_1)$. They corresponds to summands $(\chi_1 + \epsilon_2)(1 + q)$. Then $P_M(q) = (\chi_1 + \epsilon_2 + \chi)(1 + q)$, where χ is a 3-dimensional subrepresentation of $H^2(\operatorname{Hess}(M, y))$ still to be figured out. Because χ comes from IC-sheaves supported on nilpotent orbits strictly smaller than $G_2(a_1)$, we write $\chi = a\mathbf{1} + b\epsilon_1 + c\chi_2$ and solve for a, b and c.

Now we use Theorem 5.2.6 for $J = \{\alpha\}$ and $J = \{\beta\}$. By Table A.3 and Table A.4, we have

$$J = \{\alpha\}, W_J = \langle s \rangle \quad J = \{\beta\}, W_J = \langle t \rangle$$
$$\dim_{\mathbb{C}} H^2(\operatorname{Hess}(M, x_J)) \quad 3 \quad 4$$

Combining the information,

$$\begin{split} \chi_{H^{2}(\mathrm{Hess}(M,y))} &= \chi_{1} + \epsilon_{2} + \chi \\ \mathrm{Ind}_{\langle s \rangle}^{W} \mathbf{1} &= \mathbf{1} + \epsilon_{1} + \chi_{1} + \chi_{2} \\ \mathrm{Ind}_{\langle t \rangle}^{W} \mathbf{1} &= \mathbf{1} + \epsilon_{2} + \chi_{1} + \chi_{2} \\ \langle \chi_{H^{2}(\mathrm{Hess}(M,y))}, \mathrm{Ind}_{\langle s \rangle}^{W} \mathbf{1} \rangle &= 3 \\ \langle \chi_{H^{2}(\mathrm{Hess}(M,y))}, \mathrm{Ind}_{\langle t \rangle}^{W} \mathbf{1} \rangle &= 4 \\ \chi &= a\mathbf{1} + b\epsilon_{1} + c\chi_{2} \\ \mathrm{dim}_{\mathbb{C}} \chi &= 3 \end{split}$$

we get the following system.

$$\begin{cases} 1+a+b+c = 3\\ 1+1+a+c = 4\\ a+b+2c = 3 \end{cases}$$

Then a = 1, b = 0 and c = 1. As a result, $P_M(q) = (1 + \chi_2 + \chi_1 + \epsilon_2)(1 + q)$.

•
$$I = I_{\beta}$$

Still, $|\Phi(I)| = 5$, d = 15, $d^{\vee} = 11$, n = 1. By an argument similar to the previous case, $P_M(q)$ is divisible by (1+q).

 $G_2(a_1)$ is the maximal orbit contained in the image of π_I . Let N be an element from $G_2(a_1)$. $\pi_I^{-1}(N) = \overline{X_s} \cong \mathbb{P}^1$ and $A(N) \cong S_3$ fixes the unique irreducible component of $\pi_I^{-1}(N)$ (see Remark 4.3.2). Therefore, $H^*(\pi_I^{-1}(N)) = \mathbb{C}[0] \oplus \mathbb{C}[-2]$ and $H^*(R\pi_{I*}\mathbb{C}[11]|_N) = \mathbb{C}[11] \oplus \mathbb{C}[9]$, where A(N) acts on both $\mathbb{C}[11]$ and $\mathbb{C}[9]$ trivially. Hence IC($G_2(a_1), \psi_3$)[1] and IC($G_2(a_1), \psi_3$)[-1] are the only summands of $R\pi_{I*}\mathbb{C}[11]$ supported on $G_2(a_1)$. They correspond to the summands $\chi_1(1+q)$ and $P_M(q) = (\chi_1 + \chi)(1+q)$ where $\chi = a\mathbf{1} + b\epsilon_1 + c\chi_2$ is a 4-dimensional subrepresentation of $H^2(\text{Hess}(M, y))$ to be figured out.

Use Theorem 5.2.6 for $J = \{\alpha\}$ and $J = \{\beta\}$ again. By Table A.5 and Table A.6, we have

$$\frac{J = \{\alpha\}, W_J = \langle s \rangle}{\dim_{\mathbb{C}} H^2(\operatorname{Hess}(M, x_J))} \frac{4}{4}$$

Combining the information,

$$\chi_{H^{2}(\text{Hess}(M,y))} = \chi_{1} + \chi$$
$$\text{Ind}_{\langle s \rangle}^{W} \mathbf{1} = \mathbf{1} + \epsilon_{1} + \chi_{1} + \chi_{2}$$
$$\text{Ind}_{\langle t \rangle}^{W} \mathbf{1} = \mathbf{1} + \epsilon_{2} + \chi_{1} + \chi_{2}$$
$$\langle \chi_{H^{2}(\text{Hess}(M,y))}, \text{Ind}_{\langle s \rangle}^{W} \mathbf{1} \rangle = 4$$
$$\langle \chi_{H^{2}(\text{Hess}(M,y))}, \text{Ind}_{\langle t \rangle}^{W} \mathbf{1} \rangle = 3$$
$$\chi = a\mathbf{1} + b\epsilon_{1} + c\chi_{2}$$
$$\text{dim}_{\mathbb{C}} \chi = 4$$

we get the following system.

$$\begin{cases} a+b+c+1 = 4\\ a+c+1 = 3\\ a+b+2c = 4 \end{cases}$$

Then a = b = c = 1 and $P_M(q) = (\mathbf{1} + \epsilon_1 + \chi_2 + \chi_1)(1+q)$.

• $I = I_{\alpha,\beta}$

In this case, $I = \mathfrak{u}$, $M = \mathfrak{b}$, and the map $\pi_M : G \times^B M \longrightarrow \mathfrak{g}$ is isomorphic to the Grothendieck simultaneous resolution. Let $\tilde{\mathfrak{g}}^{rs} = \pi_M^{-1}(\mathfrak{g}^{rs})$. Then the restriction $\pi_M : \tilde{\mathfrak{g}}^{rs} \longrightarrow \mathfrak{g}^{rs}$ is a W-torsor. Therefore, $H^*(\operatorname{Hess}(M, y))$ is the regular representation of W and $P_M(q) = \mathbf{1} + \epsilon_1 + 2\chi_2 + 2\chi_1 + \epsilon_2$.

Now we have finished the classification of all dot actions for type G_2 .

In summary, we have the following theorem.

Theorem 5.3.2 (Brosnan, Xue). Table 5.4 gives the complete list of Tymoczko's dot actions on the cohomology of regular semisimple Hessenberg varieties when G is of type G_2 .

I	$P_M(q)$
I_{\emptyset}	$1 + 2q + 2q^2 + 2q^3 + 2q^4 + 2q^5 + 1q^6$
$I_{2\beta+3\alpha}$	$1 + 2q + (2 + \epsilon_1)q^2 + (2 + \epsilon_1)q^3 + 2q^4 + 1q^5$
$I_{\beta+3\alpha}$	$1 + (2 + \epsilon_1)q + (2 + 2\epsilon_1)q^2 + (2 + \epsilon_1)q^3 + 1q^4$
$I_{\beta+2\alpha}$	$1 + (2 + \epsilon_1 + \chi_2)q + (2 + \epsilon_1 + \chi_2)q^2 + 1q^3$
$I_{\beta+\alpha}$	$1 + (2 + \epsilon_1 + 2\chi_2 + \chi_1 + \epsilon_2)q + 1q^2$
I_{α}	$(1 + \chi_2 + \chi_1 + \epsilon_2)(1+q)$
I_{β}	$(1 + \epsilon_1 + \chi_2 + \chi_1)(1+q)$
$I_{\alpha,\beta}$	$1 + \epsilon_1 + 2\chi_2 + 2\chi_1 + \epsilon_2$

Table 5.4: Dot actions for type G_2

Chapter 6: Type F_4 and E_6

In this chapter we complete the proof of Theorem 2.7.7. To be more specific, all that remains is the following proposition.

Proposition 6.0.1. Let G be a connected simple algebraic group over \mathbb{C} of type F_4 or E_6 . Let B be a Borel subgroup of G and $N \in \mathfrak{g}$ be a distinguished nilpotent element whose associated parabolic P contains B. Following the notation in section 2.6, let $P = LU_P$ be the Levi decomposition of P so that $\mathfrak{l} = \mathfrak{g}(0)$ and $\mathfrak{u}_P = \bigoplus_{i>0} \mathfrak{g}(i)$. $L \cap B$ is a Borel subgroup of L. Then for any $(L \cap B)$ -stable subspace $U \subset \mathfrak{g}(2)$, the variety $X_U = (L, L \cap B, \mathfrak{g}(2), U, N)$ is paved by affines whenever it is not empty.

We prove the statement above by giving sufficiently concrete descriptions of all the nonempty $(L, L \cap B, \mathfrak{g}(2), U, N)$'s for every distinguished nilpotent orbit of F_4 and E_6 . The proposition should be evident towards the end of this chapter.

6.1 Computational setups

Let G denote a connected simple algebraic group over \mathbb{C} of type F_4 or E_6 . Fix a Borel subgroup B of G and choose a maximal torus $T \subset B$. Let Φ denote the set of roots with respect to T and B and Δ denote the set of simple roots. By abuse of notation, Φ also denotes the Dynkin diagram of \mathfrak{g} .

For any root $\gamma \in \Phi$, let X_{γ} be the 1-dimensional unipotent subgroup of Gwhose Lie algebra is the root space \mathfrak{g}_{γ} . Let $x_{\gamma} : \mathbb{C} \longrightarrow X_{\gamma}$ be the group isomorphism defined via the exponential map and the choice of a Chevalley basis element in \mathfrak{g}_{γ} . For each positive root γ , choose a nonzero vector $E_{\gamma} \in \mathfrak{g}_{\gamma}$. Let $E_{-\gamma}$ be the unique vector in $\mathfrak{g}_{-\gamma}$ so that $\{E_{\gamma}, [E_{\gamma}, E_{-\gamma}], E_{-\gamma}\}$ is an \mathfrak{sl}_2 -triple. Let $H_{\gamma} = [E_{\gamma}, E_{-\gamma}]$. The four lemmas from Lemma 4.1.1 to Lemma 4.1.4 are still true for type F_4 and E_6 .

In our presentation of G above, we have chosen a Borel subgroup B and a maximal torus $T \subset B$ to begin with. Therefore, for each distinguished nilpotent orbit, we need to pick a representative N so that its associated parabolic P contains the preselected B. To facilitate the choice, we recall some information regarding the classification of nilpotent orbits of a simple Lie algebra.

There are at least three different ways of classifying nilpotent orbits: weighted Dynkin diagrams, the Bala-Carter theory and pseudo-Levi subalgebras.

• weighted Dynkin diagrams

By the Jacobson-Morozov theorem, every nilpotent element $N \in \mathfrak{g}$ can be embedded in a \mathfrak{sl}_2 -triple. By considering \mathfrak{g} as an \mathfrak{sl}_2 -representation, we thereby obtain the weighted Dynkin diagram associated to N, which is the Dynkin diagram of \mathfrak{g} with every node labeled by a number from $\{0, 1, 2\}$. It is known that the weighted Dynkin diagram is uniquely determined by the conjugacy class of N, and that the diagram is even (labeled only by 0 and 2) if N is distinguished. The main drawback of this method is that not all of the 3^l weighted Dynkin diagrams of an algebra \mathfrak{g} of rank l correspond to nilpotent orbits, and there is no simple algorithm to determine which diagram does. For type F_4 and E_6 , the weighted Dynkin diagrams of all their distinguished nilpotent orbits are listed in Bala & Carter [1976][p. 416].

• Bala-Carter theory

Bala & Carter [1976][Theorem 6.1] states that there is a bijection between the set of conjugacy classes of nilpotent elements of \mathfrak{g} and G-conjugacy classes of pairs (R, P_R) , where R is a semisimple subgroup of parabolic type in G and P_R is a distinguished parabolic subgroup of R. As a consequence, (as we have recalled in section 2.8) for every nilpotent element $N \in \mathfrak{g}$, there exists a minimal Levi subalgebra \mathfrak{m} of \mathfrak{g} containing N so that N is distinguished in \mathfrak{m} . Under this scheme, the distinguished nilpotent orbits of type F_4 and E_6 are denoted by symbols $X_i(a_j)$, where X_i is either F_4 or E_6 (meaning the minimal Levi subalgebra is \mathfrak{g} itself) and j is the semisimple rank of the associated distinguished parabolic subgroup. According to Bala & Carter [1976][p. 416], F_4 has 4 distinguished nilpotent orbits: F_4 (the regular orbit), $F_4(a_1)$, $F_4(a_2)$ and $F_4(a_3)$. E_6 has 3 distinguished orbits: E_6 , $E_6(a_1)$ and $E_6(a_3)$.

• pseudo-Levi subalgebras

Definition 6.1.1. A pseudo-Levi subalgebra of \mathfrak{g} is a subalgebra that is *G*-conjugacy to a subalgebra of the form

$$\mathfrak{g}' = \mathfrak{t} \oplus \bigoplus_{\alpha \in \Psi} \mathfrak{g}_{lpha},$$

where Ψ is an additively closed subrootsystem of Φ .

Pseudo-Levi subalgebras turn out to be rather tractable.

In the first place, we have the following result.

Proposition 6.1.2 (Sommers [1998], Proposition 2). Pseudo-Levi subalgebras are the subalgebras of \mathfrak{g} of the form $C_{\mathfrak{g}}(t)$ where t is a semisimple element of G.

In the second place, the Dynkin diagrams of all the additively closed subrootsystems Ψ can be obtained from the extended Dynkin diagram $\tilde{\Phi}$ of \mathfrak{g} by the Borel-de Siebenthal theory: start with $\tilde{\Phi}$, remove certain nodes, and possibly repeat the same process on the connected components of the resulting diagram. In particular, the Dynkin diagrams of the pseudo-Levi subalgebras of the same rank as \mathfrak{g} are those obtained from $\tilde{\Phi}$ by removing exactly one node.

In the third place, for type A_n , C_n , G_2 , F_4 and E_6 , the *G*-conjugacy class of the pseudo-Levi subalgebra \mathfrak{g}' is determined by the isomorphism type of its root system Ψ and the lengths of the simple roots of Ψ .

These facts, together with the following theorem, can help us find a representative for each distinguished nilpotent orbit of type F_4 and E_6 .

Theorem 6.1.3 (Sommers [1998], Theorem 13). When G is of the adjoint type, there is a bijection between: G-conjugacy classes of pairs (\mathfrak{l}, N) , where \mathfrak{l} is a pseudo-Levi subalgebra of \mathfrak{g} and N is a distinguished nilpotent element in \mathfrak{l} ; and G-conjugacy classes of pairs (N, C), where N is a nilpotent element of \mathfrak{g} and C is a conjugacy class in the component group $A(N) = C_G(N)/C_G^{\circ}(N)$.

Furthermore, to make sure that the associated parabolic subgroup of the chosen representative does contain the preselected Borel subgroup B, we need the following lemma. **Lemma 6.1.4.** Let \mathfrak{g} be a reductive Lie algebra over \mathbb{C} of semisimple rank l with a decomposition

$$\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{lpha \in \Phi} \mathfrak{g}_{lpha},$$

where \mathfrak{h} is a Cartan subalgebra and Φ is the root system of \mathfrak{g} . Choose a set of simple roots $\Delta = \{\alpha_1, \alpha_2, \ldots, \alpha_l\}$. For each positive root $\gamma \in \Phi$, choose a nonzero vector $E_{\gamma} \in \mathfrak{g}_{\gamma}$. Let $E_{-\gamma}$ be the unique vector in $\mathfrak{g}_{-\gamma}$ so that $\{E_{\gamma}, [E_{\gamma}, E_{-\gamma}], E_{-\gamma}\}$ is an \mathfrak{sl}_2 -triple. Let $H_{\gamma} = [E_{\gamma}, E_{-\gamma}]$. Then $N = \sum_{i=1}^{l} E_{\alpha_i}$ is a regular nilpotent element of \mathfrak{g} and there exist a semisimple element $H \in \mathfrak{h}$ and a nilpotent element $Y \in \mathfrak{g}$ so that $\{N, H, Y\}$ forms an \mathfrak{sl}_2 -triple.

Proof. By the Jacobson-Morozov theorem, we can always embed N in an \mathfrak{sl}_2 -triple. The point of the lemma is to show that there exists such an \mathfrak{sl}_2 -triple so that the semisimple element H lies in the preselected Cartan subalgebra \mathfrak{h} .

Let $A = [A_{ij}]_{l \times l}$ be the Cartan matrix of Φ , where $A_{ij} = \langle \alpha_j, \alpha_i \rangle = \alpha_j(H_{\alpha_i})$. Define the $1 \times l$ row vector $[x_1, x_2, \dots, x_l] = [2, 2, \dots, 2]A^{-1}$. Set $H = \sum_{i=1}^l x_i H_{\alpha_i}$ and $Y = \sum_{i=1}^l x_i E_{-\alpha_i}$.

For every $j \in \{1, 2, ..., l\}$, $\alpha_j(H) = \sum_{i=1}^l x_i \alpha_j(H_{\alpha_i}) = \sum_{i=1}^l x_i A_{ij} = 2$. Therefore, $[H, N] = \sum_{i=1}^l [H, E_{\alpha_i}] = \sum_{i=1}^l \alpha_i(H) E_{\alpha_i} = 2N$. Similarly, [H, Y] = -2Y. For distinct simple roots α_i and α_j , $\alpha_i - \alpha_j$ is not a root. Hence $[N, Y] = \sum_{i=1}^l x_i [E_{\alpha_i}, E_{-\alpha_i}] = \sum_{i=1}^l x_i H_{\alpha_i} = H$. Therefore, $\{N, H, Y\}$ is an \mathfrak{sl}_2 -triple. This also means that the weighted Dynkin diagram associated to N has every node labeled by 2, so N must be a regular nilpotent element.

As will become clear later, the following lemma is the last piece of the puzzle

to prove Proposition 6.0.1.

Lemma 6.1.5. For every smooth projective rational surface over \mathbb{C} with finitely many marked points, there exists an affine paving of it whose unique 2-cell contains all the marked points. In particular, every smooth projective rational surface is paved by affines.

Proof. It is well-known that any smooth projective rational surface S can be obtained from successive blowups of a minimal rational surface. To be precise, there exists a chain of morphisms $\pi_k : S_k \longrightarrow S_{k-1}$ (k = 1, 2, ..., n) so that: each S_k is a smooth projective rational surface, $S_n \cong S$ and S_0 is a minimal rational surface; each π_k is the blowup of S_{k-1} at a single point. We prove the lemma by induction on the number of blowups in the chain.

When the number of blowups is 0, the surface S itself is a minimal rational surface. That is, S is either \mathbb{P}^2 or a Hirzebruch surface. Then the lemma is clear from the explicit descriptions of these two types of minimal surfaces.

Assume the lemma is true when the number of blowups is less than or equal to n-1. For any surface S obtained by n blowups, consider the last morphism $\pi_n : S \longrightarrow S_{n-1}$. Let $\{q_1, q_2, \ldots, q_m\}$ be the set of marked points on S and let $p \in S_{n-1}$ be the blown-up point. Consider S_{n-1} with a set of marked points $\{\pi_n(q_1), \pi_n(q_2), \ldots, \pi_n(q_m)\} \cup \{p\}$. By the inductive hypothesis, there exists an affine paving of S_{n-1} whose unique 2-cell \mathbb{A}^2 contains $\{\pi_n(q_1), \pi_n(q_2), \ldots, \pi_n(q_m)\} \cup \{p\}$. Then the blowup $\operatorname{Bl}_p \mathbb{A}^2$, as an open subset of S, contains all the points q_1, q_2, \ldots, q_m . The classic definition of the blowup of \mathbb{C}^2 at the origin is $\operatorname{Bl}_{(0,0)} \mathbb{C}^2 = \{((x, y), [u :$ $v]) \in \mathbb{C}^2 \times \mathbb{P}^1 \mid xv - yu = 0\}$. Hence $\operatorname{Bl}_p \mathbb{A}^2$ is a line bundle over the exceptional divisor \mathbb{P}^1 , and we use $\operatorname{pr}_2 : \operatorname{Bl}_p \mathbb{A}^2 \longrightarrow \mathbb{P}^1$ to denote the projection. Picking $x \in \mathbb{P}^1$ which is not equal to any $\operatorname{pr}_2(q_i)$ $(i = 1, 2, \ldots, m)$, we can decompose $\operatorname{Bl}_p \mathbb{A}^2$ into a 1-cell $\operatorname{pr}_2^{-1}(x) \cong \mathbb{A}^1$ and a 2-cell $\operatorname{pr}_2^{-1}(\mathbb{P}^1 \setminus \{x\}) \cong \mathbb{A}^2$. It is clear that $\operatorname{pr}_2^{-1}(\mathbb{P}^1 \setminus \{x\})$, $\operatorname{pr}_2^{-1}(x)$ and the inverse images under π_n of the 1-cells and 0-cells of S_{n-1} form an affine paving of S, and that q_1, q_2, \ldots, q_m all lie in the unique 2-cell $\operatorname{pr}_2^{-1}(\mathbb{P}^1 \setminus \{x\}) \cong \mathbb{A}^2$. The induction step is now complete and we have finished the proof.

6.2 The case of F_4

We now prove Proposition 6.0.1 when the group G is of type F_4 . We use the presentation of G outlined in the beginning of section 6.1. That is, we fix a Borel subgroup B and a maximal torus $T \subset B$, by which we obtain the decomposition

$$\mathfrak{g} = \mathfrak{t} \oplus \bigoplus_{\alpha \in \Phi} \mathfrak{g}_{\alpha},$$

a 1-dimensional unipotent subgroup X_{γ} for each root $\gamma \in \Phi$, and an \mathfrak{sl}_2 -triple $\{E_{\gamma}, H_{\gamma}, E_{-\gamma}\}$ for each positive root $\gamma \in \Phi^+$.

As mentioned earlier, F_4 has 4 distinguished nilpotent orbits: F_4 , $F_4(a_1)$, $F_4(a_2)$ and $F_4(a_3)$. Note that $(L, L \cap B, \mathfrak{g}(2), U, N)$ is a closed subvariety of the flag variety $L/L \cap B$. For the regular nilpotent orbit F_4 , $L/L \cap B$ is a single point, so the proposition is automatically true. For $F_4(a_1)$, since the semisimple rank of the associated parabolic subgroup of a representative is 1, $L/L \cap B$ is \mathbb{P}^1 and there is nothing more to prove either. For $F_4(a_3)$, the nonempty $(L, L \cap B, \mathfrak{g}(2), U, N)$'s are described concretely in De Concini et al. [1988][section 4.2]. In the light of Lemma 6.1.5, they are clearly all paved by affines. Therefore, the only orbit that needs to be dealt with is $F_4(a_2)$. We start the computation by finding a good representative of this orbit.

We give the Dynkin diagram of F_4 the Bourbaki labeling.



Adding the lowest root $\alpha_0 = -(2\alpha_1 + 3\alpha_2 + 4\alpha_3 + 2\alpha_4)$, we have the extended Dynkin diagram of F_4 .



From Bala & Carter [1976][p. 417], we obtain the weighted Dynkin diagram corresponding to $F_4(a_2)$.



We expect a good representative N of $F_4(a_2)$ to satisfy the following three requirements:

 N can be embedded into an sl₂-triple {N, H, Y} so that H ∈ t and γ(H) ≥ 0 for every positive root γ ∈ Φ⁺. As a consequence, the associated parabolic subgroup P of N contains the preselected Borel subgroup B.

- (2) Let g = ⊕_{i∈Z} g(i) be the weight space decomposition of g via the sl₂-triple {N, H, Y}. We need to have g(0) = t ⊕ span_C{E_{α1}, E_{−α1}, E_{α3}, E_{−α3}} and g(2) = span_C{E_{α2}, E_{α4}, E_{α1+α2}, E_{α2+α3}, E_{α3+α4}, E_{α1+α2+α3}, E_{α2+2α3}, E_{α1+α2+2α3}}. This makes sure that the weighted Dynkin diagram associated to N is indeed the one given above.
- (3) $N \in \mathfrak{g}(2)$. This is always a consequence of (1).

The idea of finding such an N comes from Theorem 6.1.3. In particular, the first table in Sommers [1998][p. 557] tells us that a representative of $F_4(a_2)$ can be a regular nilpotent element of a pseudo-Levi subalgebra of type $A_1 + C_3$. From the eight roots belonging to $\mathfrak{g}(2)$, we pick 4 and rename them as $\beta_0 = \alpha_1 + \alpha_2 + 2\alpha_3$, $\beta_2 = \alpha_1 + \alpha_2$, $\beta_3 = \alpha_3 + \alpha_4$ and $\beta_4 = \alpha_2 + \alpha_3$. We can draw a diagram by treating these 4 roots as nodes and connecting β_i and β_j by $\langle \beta_i, \beta_j \rangle \langle \beta_j, \beta_i \rangle$ bonds $(i, j \in \{0, 2, 3, 4\})$, with arrows pointing from long roots to short roots. The resulting diagram happens to be the same as the Dynkin diagram of type $A_1 + C_3$.



Let Ψ denote the additively closed subrootsystem of Φ generated by $\{\beta_0, \beta_2, \beta_3, \beta_4\}$. We claim that Ψ is root system of type $A_1 + C_3$ and $\mathfrak{g}' = \mathfrak{t} \oplus \bigoplus_{\alpha \in \Psi} \mathfrak{g}_{\alpha}$ is a pseudo-Levi subalgebra of the same type. To see this, note that there is only one G-conjugacy class of pseudo-Levi subalgebras of type $A_1 + C_3$, whose "standard" Dynkin diagram is obtained from the extended Dynkin diagram of F_4 by removing the node α_1 (the Borel-de Siebenthal theory).



The removed node α_1 is related to the rest by $\alpha_1 = (1/2)(-\alpha_0 - 3\alpha_2 - 4\alpha_3 - 2\alpha_4)$. Define β_1 to be the same linear combination of β_0 , β_2 , β_3 and β_4 : $\beta_1 = (1/2)(-\beta_0 - 3\beta_2 - 4\beta_3 - 2\beta_4) = -2\alpha_1 - 3\alpha_2 - 4\alpha_3 - 2\alpha_4 = \alpha_0$. Now that β_1 , β_2 , β_3 , β_4 are 4 distinct roots of Φ and the diagram formed by them is exactly the Dynkin diagram of F_4 , $\{\beta_1, \beta_2, \beta_4, \beta_4\}$ must be another set of simple roots of Φ with β_0 being the corresponding lowest root.



Since Ψ is additively generated by $\{\beta_0, \beta_2, \beta_3, \beta_4\}$ (the new set of nodes with β_1 removed), it must be a subrootsystem of Φ of type $A_1 + C_3$. Hence $\mathfrak{g}' = \mathfrak{t} \oplus \bigoplus_{\alpha \in \Psi} \mathfrak{g}_{\alpha}$ is a pseudo-Levi subalgebra of the same type. Let $N = E_{\beta_0} + E_{\beta_2} + E_{\beta_3} + E_{\beta_4} = E_{\alpha_1 + \alpha_2 + 2\alpha_3} + E_{\alpha_1 + \alpha_2} + E_{\alpha_3 + \alpha_4} + E_{\alpha_2 + \alpha_3}$. By Lemma 6.1.4, N is a regular nilpotent element of \mathfrak{g}' and there exists a semisimple element $H \in \mathfrak{t}$ and a nilpotent element $Y \in \mathfrak{g}'$ so that $\{N, H, Y\}$ forms an \mathfrak{sl}_2 -triple. As a consequence, $\beta_i(H) = 2$ for i = 0, 2, 3, 4. Solving the linear system of equations,

$$\begin{cases} \beta_0(H) = \alpha_1(H) + \alpha_2(H) + 2\alpha_3(H) = 2\\ \beta_2(H) = \alpha_1(H) + \alpha_2(H) = 2\\ \beta_3(H) = \alpha_3(H) + \alpha_4(H) = 2\\ \beta_4(H) = \alpha_2(H) + \alpha_3(H) = 2 \end{cases}$$

we get $\alpha_1(H) = 0$, $\alpha_2(H) = 2$, $\alpha_3(H) = 0$ and $\alpha_4(H) = 2$. This means that the weighted Dynkin diagram associated to N is the one we started with. Therefore, $N = E_{\alpha_1+\alpha_2+2\alpha_3} + E_{\alpha_1+\alpha_2} + E_{\alpha_3+\alpha_4} + E_{\alpha_2+\alpha_3}$ is indeed a representative of $F_4(a_2)$ and does satisfy all 3 requirements mentioned earlier.

Let P be the associated parabolic of N and $P = LU_P$ be the Levi decomposition. We compute the nonempty $(L, L \cap B, \mathfrak{g}(2), U, N)$'s and show that they are all paved by affines.

In this case, $L = \langle T, X_{\alpha_1}, X_{-\alpha_1}, X_{\alpha_3}, X_{-\alpha_3} \rangle$ and $L \cap B = \langle T, X_{\alpha_1}, X_{\alpha_3} \rangle$, where the angle brackets stand for group generation. As a consequence, $L/L \cap B \cong$ $\mathbb{P}^1 \times \mathbb{P}^1$. By Lemma 2.7.1, for any $(L, L \cap B, \mathfrak{g}(2), U, N)$ to be nonempty, U can have codimension at most 2 in $\mathfrak{g}(2)$. When codim U is 0 or 2, the corresponding $(L, L \cap B, \mathfrak{g}(2), U, N)$ is respectively $\mathbb{P}^1 \times \mathbb{P}^1$ or a finite set of points, hence paved by affines. The only nontrivial case is when codim U = 1. There are only two such $(L \cap B)$ -stable subspace U of $\mathfrak{g}(2)$:

$$U = \bigoplus_{\alpha \in \Phi(U)} \mathfrak{g}_{\alpha}, \quad \Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_2\}, \text{ or}$$

$$U = \bigoplus_{\alpha \in \Phi(U)} \mathfrak{g}_{\alpha}, \quad \Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_4\},$$

where $\Phi(U)$ and $\Phi(\mathfrak{g}(2))$ denote the sets of roots belonging to U and $\mathfrak{g}(2)$ respectively. Recall that $\Phi(\mathfrak{g}(2)) = \{\alpha_2, \alpha_4, \alpha_1 + \alpha_2, \alpha_2 + \alpha_3, \alpha_3 + \alpha_4, \alpha_1 + \alpha_2 + \alpha_3, \alpha_2 + 2\alpha_3, \alpha_1 + \alpha_2 + 2\alpha_3\}$, hence we can only remove α_2 or α_4 in order for U to be an $(L \cap B)$ -stable subspace of codimension 1. • the case of $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_2\}$

Let s_1 and s_3 be the simple reflections associated to α_1 and α_3 respectively. Let $x_{\alpha_1} : \mathbb{C} \longrightarrow X_{\alpha_1}$ and $x_{\alpha_3} : \mathbb{C} \longrightarrow X_{\alpha_3}$ be the group isomorphisms mentioned in section 6.1. Let $\mathbb{C} \times \mathbb{C}$ denote the unique 2-cell of $L/L \cap B \cong \mathbb{P}^1 \times \mathbb{P}^1$, and we can present it as the following set:

$$\mathbb{C} \times \mathbb{C} = \{ x_{\alpha_1}(z_1) \dot{s}_1 x_{\alpha_3}(z_3) \dot{s}_3(L \cap B) \in L/L \cap B \mid z_1, z_3 \in \mathbb{C} \}.$$

Here $x_{\alpha_1}(z_1)\dot{s}_1x_{\alpha_3}(z_3)\dot{s}_3(L \cap B)$ is considered a left $(L \cap B)$ -coset, hence a point of the flag variety $L/L \cap B$ (for details of this presentation, see Equation 2.1 and Lemma 4.2.1 (2)).

Consider the intersection of $X_U = (L, L \cap B, \mathfrak{g}(2), U, N)$ with the 2-cell $\mathbb{C} \times \mathbb{C}$ of $L/L \cap B$. By definition,

$$X_U \cap (\mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_3) \in \mathbb{C}^2 \mid \dot{s}_3 \cdot x_{\alpha_3}(-z_3) \cdot \dot{s}_1 \cdot x_{\alpha_1}(-z_1) \cdot N \in U \}.$$

By Lemma 4.1.1 and Lemma 4.1.3, we know that

$$\dot{s}_3 \cdot x_{\alpha_3}(-z_3) \cdot \dot{s}_1 \cdot x_{\alpha_1}(-z_1) \cdot N = \sum_{\gamma \in \Phi(\mathfrak{g}(2))} f_\gamma(z_1, z_3) E_\gamma, \text{ where } f_\gamma \in \mathbb{C}[z_1, z_3].$$

Since $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_2\}$, in order for $\dot{s}_3 \cdot x_{\alpha_3}(-z_3) \cdot \dot{s}_1 \cdot x_{\alpha_1}(-z_1) \cdot N$ to be in U, it is necessary and sufficient that $f_{\alpha_2}(z_1, z_3) = 0$. Using the same two lemmas and computing carefully with the representative $N = E_{\alpha_1+\alpha_2+2\alpha_3} + E_{\alpha_1+\alpha_2} + E_{\alpha_3+\alpha_4} + C_{\alpha_3+\alpha_4}$ $E_{\alpha_2+\alpha_3}$, we get that

$$f_{\alpha_2}(z_1, z_3) = az_3^2 + bz_1z_3 + 1,$$

where a and b are some nonzero constants. Therefore,

$$X_U \cap (\mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_3) \in \mathbb{C}^2 \mid az_3^2 + bz_1z_3 + 1 = 0 \}.$$

There is an isomorphism between \mathbb{C}^{\times} and $X_U \cap (\mathbb{C} \times \mathbb{C})$:

$$\mathbb{C}^{\times} \longrightarrow X_U \cap (\mathbb{C} \times \mathbb{C})$$

$$z \longmapsto \left(-\frac{a}{b}z - \frac{1}{b}z^{-1}, z\right)$$

Note that $\overline{X_U \cap (\mathbb{C} \times \mathbb{C})}$ is a connected component of X_U . By Lemma 2.7.1 and the isomorphism above, $\overline{X_U \cap (\mathbb{C} \times \mathbb{C})}$ is a smooth projective rational curve, that is, \mathbb{P}^1 . As a result, X_U is either \mathbb{P}^1 or a disjoint union thereof, hence paved by affines.

• the case of $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_4\}$

Let $s_1, s_3, x_{\alpha_1}, x_{\alpha_3}, X_{\alpha_1}$ and X_{α_3} be the same as above. Let $\mathbb{C} \times \{\infty\}$ denote the 1-cell $X_{\alpha_1}\dot{s}_1(L \cap B)$ of $L/L \cap B \cong \mathbb{P}^1 \times \mathbb{P}^1$, which we present as:

$$\mathbb{C} \times \{\infty\} = \{x_{\alpha_1}(z_1)\dot{s}_1(L \cap B) \in L/L \cap B \mid z_1 \in \mathbb{C}\}.$$

Consider the intersection $X_U \cap (\mathbb{C} \times \{\infty\}) \cong \{z_1 \in \mathbb{C} \mid \dot{s}_1 \cdot x_{\alpha_1}(-z_1) \cdot N \in U\}$. Using

a similar method as above, it is easy to show that

$$\dot{s}_1 \cdot x_{\alpha_1}(-z_1) \cdot N = \sum_{\gamma \in \Phi(\mathfrak{g}(2))} f_{\gamma}(z_1) E_{\gamma} \text{ and } f_{\alpha_4}(z_1) = 0.$$

As a result, $X_U \cap (\mathbb{C} \times \{\infty\}) = \mathbb{C} \times \{\infty\}$ and X_U is still either \mathbb{P}^1 or a disjoint union thereof, hence paved by affines.

We have finished the case of F_4 .

6.3 The case of E_6

We prove Proposition 6.0.1 when G is of type E_6 . In this case, the increased dimension of $L/L \cap B$ makes the computation more complicated, but the idea is exactly the same. Therefore, we omit the details of those arguments that have exact counterparts in the case of F_4 .

 E_6 has 3 distinguished nilpotent orbits: E_6 , $E_6(a_1)$ and $E_6(a_3)$. The flag varieties $L/L \cap B$ for the orbits E_6 and $E_6(a_1)$ are \mathbb{P}^0 and \mathbb{P}^1 respectively, so there is nothing to prove. We only need to deal with $E_6(a_3)$. Similar to type F_4 , we start by finding a good representative of the orbit $E_6(a_3)$.

We give the Dynkin diagram of E_6 the following nonstandard labeling (neither Bourbaki nor GAP).


Adding the lowest root $\alpha_0 = -(\alpha_1 + 2\alpha_2 + 3\alpha_3 + 2\alpha_4 + \alpha_5 + 2\alpha_6)$, we have the extended Dynkin diagram of E_6 .



From Bala & Carter [1976][p. 417], we obtain the weighted Dynkin diagram corresponding to $E_6(a_3)$.



The reason for choosing the nonstandard labeling is the notational symmetry that odd-numbered simple roots α_1 , α_3 and α_5 are of weight 2 and even-numbered simple roots α_2 , α_4 and α_6 are of weight 0 in the weighted Dynkin diagram above.

We expect a good representative N of $E_6(a_3)$ to satisfy the following three requirements:

- (1) N can be embedded into an \mathfrak{sl}_2 -triple $\{N, H, Y\}$ so that $H \in \mathfrak{t}$ and $\gamma(H) \ge 0$ for every positive root $\alpha \in \Phi$.
- (2) Let $\mathfrak{g} = \bigoplus_{i \in \mathbb{Z}} \mathfrak{g}(i)$ be the weight space decomposition of \mathfrak{g} via the \mathfrak{sl}_2 -triple $\{N, H, Y\}$. We need to have $\mathfrak{g}(0) = \mathfrak{t} \oplus \operatorname{span}_{\mathbb{C}} \{E_{\alpha_2}, E_{-\alpha_2}, E_{\alpha_4}, E_{-\alpha_4}, E_{\alpha_6}, E_{-\alpha_6}\}$ and $\mathfrak{g}(2) = \operatorname{span}_{\mathbb{C}} \{E_{\alpha_1}, E_{\alpha_3}, E_{\alpha_5}, E_{\alpha_1+\alpha_2}, E_{\alpha_2+\alpha_3}, E_{\alpha_3+\alpha_4}, E_{\alpha_3+\alpha_6}, E_{\alpha_4+\alpha_5}, E_{\alpha_2+\alpha_3+\alpha_4}, E_{\alpha_2+\alpha_3+\alpha_6}, E_{\alpha_3+\alpha_4+\alpha_6}, E_{\alpha_2+\alpha_3+\alpha_4+\alpha_6}\}.$

(3) $N \in \mathfrak{g}(2)$.

The second table in Sommers [1998][p. 557] tells us that a representative of $E_6(a_3)$ can be a regular nilpotent element of a pseudo-Levi subalgebra of type $A_5 + A_1$, whose "standard" Dynkin diagram can be obtained from the extended Dynkin diagram of E_6 by removing the node α_2 .



From the twelve roots belonging to $\mathfrak{g}(2)$, we pick 6 and rename them as $\beta_0 = \alpha_2 + \alpha_3$, $\beta_6 = \alpha_4 + \alpha_5$, $\beta_3 = \alpha_3 + \alpha_6$, $\beta_4 = \alpha_1 + \alpha_2$, $\beta_5 = \alpha_3 + \alpha_4$ and $\beta_1 = \alpha_2 + \alpha_3 + \alpha_4 + \alpha_6$. Draw a diagram by treating the 6 roots as nodes and connecting β_i and β_j by $\langle \beta_i, \beta_j \rangle \langle \beta_j, \beta_i \rangle$ bonds $(i, j \in \{0, 1, 3, 4, 5, 6\})$, we get exactly the Dynkin diagram of type $A_5 + A_1$.



Let $N = E_{\alpha_2+\alpha_3} + E_{\alpha_4+\alpha_5} + E_{\alpha_3+\alpha_6} + E_{\alpha_1+\alpha_2} + E_{\alpha_3+\alpha_4} + E_{\alpha_2+\alpha_3+\alpha_4+\alpha_6}$. Arguing in exactly the same way as for type F_4 , we can show that N is a representative of $E_6(a_3)$ that satisfies all 3 requirements mentioned earlier.

Let P be the associated parabolic of N and $P = LU_P$ be the Levi decomposition. We compute all the $(L, L \cap B, \mathfrak{g}(2), U, N)$'s that are possibly nonempty for dimension reason and show that they are paved by affines.

In this case, $L = \langle T, X_{\alpha_2}, X_{-\alpha_2}, X_{\alpha_4}, X_{-\alpha_4}, X_{\alpha_6}, X_{-\alpha_6} \rangle$ and $L \cap B = \langle T, X_{\alpha_2}, X_{\alpha_4}, X_{\alpha_6} \rangle$. $X_{\alpha_6} \rangle$. As a consequence, $L/L \cap B \cong \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1$. Let s_2 , s_4 and s_6 be the simple reflections associated to α_2 , α_4 and α_6 respectively. Let $x_{\alpha_2} : \mathbb{C} \longrightarrow X_{\alpha_2}$, $x_{\alpha_4} : \mathbb{C} \longrightarrow X_{\alpha_4}$ and $x_{\alpha_6} : \mathbb{C} \longrightarrow X_{\alpha_6}$ be the corresponding group isomorphisms. We present all 8 cells of $L/L \cap B \cong \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1$ set-theoretically in Table 6.1.

By Lemma 2.7.1, for any $X_U = (L, L \cap B, \mathfrak{g}(2), U, N)$ to be possibly nonempty, U can have codimension at most 3 in $\mathfrak{g}(2)$. When codim U is 0 or 3, the corresponding X_U is respectively $\mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1$ or a finite set of points, hence paved by affines. The nontrivial cases are codim U = 1, 2. There are altogether 11 such $(L \cap B)$ -stable subspaces U of $\mathfrak{g}(2)$. They are divided into 6 groups and listed in Table 6.2. The computation of X_U is almost the same within each group.

We compute one example from each group with details and merely list the results for the rest. We will intersect X_U with as many cells as necessary and give sufficiently concrete descriptions of the intersections, from which we deduce that X_U is paved by affines. The various intersections will be displayed in tables of the same shape as Table 6.3, which shows the location of each cell in the table. The equations needed for computation are listed in Appendix B.

	1
notation of cell	presentation of cell
$\mathbb{C}\times\mathbb{C}\times\mathbb{C}$	$\{ x_{\alpha_2}(z_1)\dot{s}_2x_{\alpha_4}(z_2)\dot{s}_4x_{\alpha_6}(z_3)\dot{s}_6(L\cap B) \mid z_1, z_2, z_3 \in \mathbb{C} \}$
$\mathbb{C}\times\mathbb{C}\times\{\infty\}$	$\{ x_{\alpha_2}(z_1)\dot{s}_2x_{\alpha_4}(z_2)\dot{s}_4(L\cap B) \mid z_1, z_2 \in \mathbb{C} \}$
$\mathbb{C} \times \{\infty\} \times \mathbb{C}$	$\{ x_{\alpha_2}(z_1) \dot{s}_2 x_{\alpha_6}(z_3) \dot{s}_6(L \cap B) \mid z_1, z_3 \in \mathbb{C} \}$
$\{\infty\} \times \mathbb{C} \times \mathbb{C}$	$\{ x_{\alpha_4}(z_2) \dot{s}_4 x_{\alpha_6}(z_3) \dot{s}_6(L \cap B) \mid z_2, z_3 \in \mathbb{C} \}$
$\mathbb{C}\times\{\infty\}\times\{\infty\}$	$\{ x_{\alpha_2}(z_1)\dot{s}_2(L\cap B) \mid z_1 \in \mathbb{C} \}$
$\{\infty\}\times\mathbb{C}\times\{\infty\}$	$\{ x_{\alpha_4}(z_2)\dot{s}_4(L\cap B) \mid z_2 \in \mathbb{C} \}$
$ \{\infty\}\times\{\infty\}\times\mathbb{C}$	$\{ x_{\alpha_6}(z_3)\dot{s}_6(L\cap B) \mid z_3 \in \mathbb{C} \}$
$\{\infty\} \times \{\infty\} \times \{\infty\}$	$\{\dot{e}(L\cap B)\}$

Table 6.1: Cells of $L/L \cap B$

	10010	0.1. 1 m 0 0 01 00 a m 0 0 m				
group	$\operatorname{codim} U$	$\Phi(U)$				
1st	1	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_3\}$				
2nd	1	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_1\}$	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_5\}$			
3rd	2	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_3\}$	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_5\}$			
4th	2	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_5\}$				
5th	2	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_1 + \alpha_2\}$	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_5, \alpha_4 + \alpha_5\}$			
6th	2	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_2 + \alpha_3\}$	$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_4\}$			
0011		$\Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_6\}$				

Table 6.2: The U's of codimension 1 and 2

Table 6.3: The location of cells

dimension of cell	location of each cell in the table					
3	$\mathbb{C} imes \mathbb{C} imes \mathbb{C}$					
2	$\mathbb{C} imes \mathbb{C} imes \{\infty\}$	$\mathbb{C} imes \{\infty\} imes \mathbb{C}$	$\{\infty\} imes \mathbb{C} imes \mathbb{C}$			
1	$\mathbb{C}\times\{\infty\}\times\{\infty\}$	$\{\infty\} \times \mathbb{C} \times \{\infty\}$	$\{\infty\} \times \{\infty\} \times \mathbb{C}$			
0		$\overline{\{\infty\} \times \{\infty\} \times \{\infty\}}$	-			

6.3.1 The 1st group

We compute the only example where $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3\}.$

Intersect X_U with the 3-cell $\mathbb{C} \times \mathbb{C} \times \mathbb{C}$. By definition of the quintuple and set-theoretic presentation of the cell, we know that

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N \in U \}$$

Recall that $\dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N = \sum_{\gamma \in \Phi(\mathfrak{g}(2))} f_{\gamma}(z_1, z_2, z_3) E_{\gamma}$, where $f_{\gamma}(z_1, z_2, z_3) \in \mathbb{C}[z_1, z_2, z_3]$. Since $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3\}$, in order for $\dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N$ to be in U, we only need $f_{\alpha_3}(z_1, z_2, z_3) = 0$. According to Equation B.1, $f_{\alpha_3}(z_1, z_2, z_3) = 1 + az_1z_2 + bz_1z_3 + cz_2z_3$, where a, b and c are some nonzero constants. Therefore,

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid 1 + az_1 z_2 + bz_1 z_3 + cz_2 z_3 = 0 \}$$

and it is a smooth quadratic hypersurface of \mathbb{C}^3 . Such a hypersurface is known to be birationally equivalent to \mathbb{C}^2 via a stereographic projection, hence X_U must be a smooth projective rational surface. By Lemma 6.1.5, X_U is paved by affines.

6.3.2 The 2nd group

We demonstrate the example where $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_1\}.$

The intersection of X_U with each cell is given in Table 6.4. We explain the computation with more details. We know that

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_2, z_3) \in \mathbb{C}^2 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot N \in U \}.$$

In order for $\dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot N$ to be in U, we only need the coefficient $f_{\alpha_1}(z_2, z_3)$ of E_{α_1} to be 0. According to Equation B.4, $f_{\alpha_1}(z_2, z_3) = 0$. Therefore, $X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C})$ is the entire cell. The other intersections are determined in exactly the same way, and we deduce that $X_U \cong \{\infty\} \times \mathbb{P}^1 \times \mathbb{P}^1$, which is clearly paved by affines.

When $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_5\}$, the intersections are given in Table 6.5, and we deduce that $X_U \cong \mathbb{P}^1 \times \{\infty\} \times \mathbb{P}^1$.

Table 6.4 :	$\Phi(U) = \Phi$	$\mathfrak{P}(\mathfrak{g}(2)) \setminus \{\alpha_1\}$	}		
dimension of cells	intersection of X_U with cells				
3		Ø			
2	Ø	Ø	entire cell		
1	Ø	entire cell	entire cell		
0		entire cell			

 $\mathbf{A}(\mathbf{U}) = \mathbf{A}(\mathbf{O}) \setminus \mathbf{O}$

Table 6.5: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_5\}$

dimension of cells	intersection of X_U with cells					
3	Ø					
2	Ø	Ø				
1	$ entire cell \qquad \emptyset \qquad entire \\ \bullet \qquad \bullet \qquad \bullet \qquad \bullet \\ \bullet \qquad \bullet \qquad \bullet \qquad \bullet \\ \bullet \qquad \bullet \qquad$					
0	entire cell					

6.3.3The 3rd group

We demonstrate the example where $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_3\}.$

The intersections are given in Table 6.6. To compute $X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}),$ note that

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_2, z_3) \in \mathbb{C}^2 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot N \in U \}$$

and we need $f_{\alpha_1} = f_{\alpha_3} = 0$. According to Equation B.4, $f_{\alpha_1}(z_2, z_3) = 0$ and $f_{\alpha_3}(z_2, z_3) = az_3 + bz_2$, where a and b are nonzero. Therefore,

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_2, z_3) \in \mathbb{C}^2 \mid az_3 + bz_2 = 0 \}$$

and it is clearly isomorphic to \mathbb{C} . As a result, $X_U \cong \mathbb{P}^1$ and it is paved by affines.

When $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_5\}$, the intersections are given in Table 6.7 and we have $X_U \cong \mathbb{P}^1$ as well.

Table 6.6: Φ ($(U) = \Phi(\mathfrak{g})$	$\mathfrak{g}(2)) \setminus \{\alpha_1\}$	$1, \alpha_3\}$		
dimension of cells	intersection of X_U with cells				
3	Ø				
2	Ø	Ø	\mathbb{C}		
1	Ø	Ø	Ø		
0		entire ce	11		

Table 6.7: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_5\}$ dimension of cellsintersection of X_U with cells3 \emptyset 2 \emptyset \mathbb{C} 1 \emptyset \emptyset 0entire cell

6.3.4 The 4th group

We compute the only example where $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_5\}.$

The intersections are given in Table 6.8. To compute $X_U \cap (\{\infty\} \times \{\infty\} \times \mathbb{C}),$

note that

$$X_U \cap (\{\infty\} \times \{\infty\} \times \mathbb{C}) \cong \{ z_3 \in \mathbb{C} \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot N \in U \}$$

and we need $f_{\alpha_1} = f_{\alpha_5} = 0$. According to Equation B.7, $f_{\alpha_1}(z_3) = f_{\alpha_5}(z_3) = 0$, so $X_U \cap (\{\infty\} \times \{\infty\} \times \mathbb{C})$ is the entire cell and $X_U \cong \mathbb{P}^1$.

$\frac{1}{4} \left(\frac{1}{2} \right) = \frac{1}{4} \left(\frac{1}{2} \right) \left(\frac{1}{4} \right) \left(\frac{1}{4}$						
dimension of cells	intersection of X_U with cells					
3	Ø					
2	Ø	Ø	Ø			
1	Ø	Ø	entire cell			
0		entire cell	l			

Table 6.8: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_5\}$

6.3.5 The 5th group

When $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_1, \alpha_1 + \alpha_2\}$, the intersection of X_U with every cell is the empty set. This is because every equation from Equation B.1 to Equation B.8 has either E_{α_1} or $E_{\alpha_1+\alpha_2}$ as a summand (note that $N = E_{\alpha_2+\alpha_3} + E_{\alpha_4+\alpha_5} + E_{\alpha_3+\alpha_6} + E_{\alpha_1+\alpha_2} + E_{\alpha_3+\alpha_4} + E_{\alpha_2+\alpha_3+\alpha_4+\alpha_6}$, so it has $E_{\alpha_1+\alpha_2}$ as a summand as well). Hence $X_U = \emptyset$ and there is nothing to prove.

When $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_5, \alpha_4 + \alpha_5\}, X_U = \emptyset$ by the same argument.

6.3.6 The 6th group

We demonstrate the example where $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_2 + \alpha_3\}.$

The intersections are given in Table 6.9. To compute $X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C})$, note that

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N \in U \}$$

and we need $f_{\alpha_3} = f_{\alpha_2+\alpha_3} = 0$. According to Equation B.1, $f_{\alpha_3}(z_1, z_2, z_3) = 1 + az_1z_2 + bz_1z_3 + cz_2z_3$ and $f_{\alpha_2+\alpha_3}(z_1, z_2, z_3) = dz_3 + ez_2$, where *a*, *b*, *c*, *d*, *e* are all nonzero. Therefore,

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid 1 + az_1 z_2 + bz_1 z_3 + cz_2 z_3 = 0, dz_3 + ez_2 = 0 \}$$

Table 6.9: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_2 + \alpha_3\}$					
dimension of cells	intersection of X_U with cells				
3	\mathbb{C}^{\times} or $\mathbb{C} \amalg \mathbb{C}$				
2	\emptyset \emptyset 2 points				
1	Ø	Ø	Ø		
0		Ø			

Combining the two equations to eliminate z_3 , we get

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2) \in \mathbb{C}^2 \mid d + (ad - be)z_1z_2 - cez_2^2 = 0 \}.$$

Now it is clear that

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \begin{cases} \mathbb{C}^{\times} & \text{if } ad - be \neq 0 \\ \mathbb{C} \amalg \mathbb{C} & \text{if } ad - be = 0 \end{cases}$$

To compute $X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C})$, note that

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_2, z_3) \in \mathbb{C}^2 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot N \in U \}$$

and we need $f_{\alpha_3} = f_{\alpha_2+\alpha_3} = 0$ as well. According to Equation B.4, $f_{\alpha_3}(z_2, z_3) = az_3 + bz_2$ and $f_{\alpha_2+\alpha_3}(z_2, z_3) = 1 + cz_2z_3$, where a, b, c are nonzero. Hence

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_2, z_3) \in \mathbb{C}^2 \mid az_3 + bz_2 = 0, 1 + cz_2 z_3 = 0 \}$$
$$= \{ (\sqrt{a/(bc)}, -\sqrt{b/(ac)}), (-\sqrt{a/(bc)}, \sqrt{b/(ac)}) \}$$

Combining the intersections of X_U with the two cells, we see that X_U is either \mathbb{P}^1 or $\mathbb{P}^1 \amalg \mathbb{P}^1$, hence paved by affines.

Table 6.10: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_4\}$						
dimension of cells	intersection of X_U with cells					
3	\mathbb{C}^{\times} or $\mathbb{C} \amalg \mathbb{C}$					
2	\emptyset 2 points \emptyset					
1	Ø Ø Ø					
0	Ø					

Table 6.11: $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_6\}$ dimension of cellsintersection of X_U with cells3 \mathbb{C}^{\times} or $\mathbb{C} \amalg \mathbb{C}$ 22 points \emptyset 1 \emptyset \emptyset 0 \emptyset

When $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_4\}$ or $\Phi(U) = \Phi(\mathfrak{g}(2)) \setminus \{\alpha_3, \alpha_3 + \alpha_6\}$, the intersections are given in Table 6.10 and Table 6.11 respectively. By a similar argument, they are both either \mathbb{P}^1 or $\mathbb{P}^1 \amalg \mathbb{P}^1$. We have now finished the proof for the case of E_6 .

Appendix A: Betti Numbers of $Hess(M, x_J)$

We compute $\dim_{\mathbb{C}} H^*(\text{Hess}(M, x_J))$ for those regular Hessenberg varieties involved in section 5.3.

Let G be a connected algebraic group over \mathbb{C} of type G_2 . We use the same setups as in section 4.1. Let M be a Hessenberg subspace of \mathfrak{g} and J be a subset of the set of simple roots $\Delta = \{\alpha, \beta\}$. There always exists a semisimple element $s_J \in \mathfrak{g}$ such that $C_{\mathfrak{g}}(s_J)$ is a Levi subalgebra of \mathfrak{g} whose Weyl group is W_J . Let $n_J \in C_{\mathfrak{g}}(s_J)$ be a regular nilpotent element and define $x_J = s_J + n_J$. Then x_J is a regular element of \mathfrak{g} and $\operatorname{Hess}(M, x_J)$ is a regular Hessenberg variety. For simplicity of notation, let L denote the Levi subgroup of G with Lie algebra $\mathfrak{l} = C_{\mathfrak{g}}(s_J)$. As a result, $W_L = W_J$. By Lemma 2.5.1, each $w \in W$ can be written uniquely as w = yv with $y \in W_L$ and $v \in W^L$, where $W^L = \{v \in W \mid \Phi_v \subset \Phi(\mathfrak{u}_P)\}$. Define $M_v = \mathfrak{l} \cap \dot{v} \cdot M$. The following theorem is a consequence of Precup [2013][Theorem 4.10, Corollary 5.8].

Theorem (Precup). The regular Hessenberg variety $\text{Hess}(M, x_J)$ is paved by affines. Moreover:

- (1) Every nonempty intersection $X_w \cap \text{Hess}(M, x_J)$ is an affine space.
- (2) $X_w \cap \text{Hess}(M, x_J)$ is nonempty if and only if $J \subset y(\Phi(M_v))$.

(3) When $X_w \cap \operatorname{Hess}(M, x_J) \neq \emptyset$,

$$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J) = |\Phi_y \cap y(\Phi^-(M_v))| + |y(\Phi_v) \cap w(\Phi^-(M))|.$$

Clearly, the theorem above gives us a way of computing $\dim_{\mathbb{C}} H^*(\text{Hess}(M, x_J))$ by inspecting the intersection $X_w \cap \text{Hess}(M, x_J)$ for each $w \in W$. The inspections are carried out for all the $\text{Hess}(M, x_J)$'s involved in section 5.3, and the results are summarized in the following tables. A blank entry in the table means the corresponding intersection $X_w \cap \text{Hess}(M, x_J)$ is empty.

Table A.1: $I = I_{\beta+\alpha}, M = I^{\perp}, J = \{\alpha, \beta\}, W_J = W$

$w \in W$	e	r^{-1}	r^{-2}	r^{-3}	r^{-4}	r^{-5}
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	0			2		
$w \in W$	t	tr^{-1}	tr^{-2}	tr^{-3}	tr^{-4}	tr^{-5}
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	1	1				

Table A.2: $I = I_{\beta+\alpha}, M = I^{\perp}, J = \{\beta\}, W_J = \langle t \rangle$							
$w \in W^L$	e	tr^{-1}	tr^{-2}	tr^{-3}	r^{-4}	r^{-5}	
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	0	1	1	1	1	1	
$w \in tW^L$	t	r^{-1}	r^{-2}	r^{-3}	tr^{-4}	tr^{-5}	
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	1			2			

Table A.3: $I = I_{\alpha}, M = I^{\perp}, J = \{\alpha\}, W_J = \langle s \rangle$						
$w \in W^L$	e	t	sr^2	sr^3	r^4	r^5
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	0	1	1	1	0	0
$w \in sW^L$	s	r	r^2	r^3	sr^4	sr^5
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$						

	u)							
$w \in W^L$	e	tr^{-1}	tr^{-2}	tr^{-3}	r^{-4}	r^{-5}		
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	0	0	0	0	1	1		
$w \in tW^L$	t	r^{-1}	r^{-2}	r^{-3}	tr^{-4}	tr^{-5}		
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	1			1				

Table A.4: $I = I_{\alpha}, M = I^{\perp}, J = \{\beta\}, W_J = \langle t \rangle$

Table A.5: $I = I_{\beta}, M = I^{\perp}, J = \{\alpha\}, W_J = \langle s \rangle$ $w \in W^L$ $e \mid t \mid sr^2 \mid sr^3 \mid r^4 \mid r$ r^5 $\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$ 0 0 0 0 1 1 $w \in sW^L$ r^2 r^3 sr^4 sr^5 sr $\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$ 1 1

Table A.6: $I = I_{\beta}, M = I^{\perp}, J = \{\beta\}, W_J = \langle t \rangle$									
$w \in W^L$	e	tr^{-1}	tr^{-2}	tr^{-3}	r^{-4}	r^{-5}			
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$	0	1	1	1	0	0			
$w \in tW^L$	t	r^{-1}	r^{-2}	r^{-3}	tr^{-4}	tr^{-5}			
$\dim_{\mathbb{C}} X_w \cap \operatorname{Hess}(M, x_J)$									

Appendix B: Equations for Type E_6

This appendix contains all the equations necessary for the proof of Proposition 6.0.1 for type E_6 . The wildcard symbol * represents a random nonzero number, whose exact value is not needed for our purpose.

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_1, z_2, z_3) \in \mathbb{C}^3 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N \in U \}$$

$$\dot{s}_{6} \cdot x_{\alpha_{6}}(-z_{3}) \cdot \dot{s}_{4} \cdot x_{\alpha_{4}}(-z_{2}) \cdot \dot{s}_{2} \cdot x_{\alpha_{2}}(-z_{1}) \cdot N$$

$$= (*z_{1} + *z_{2})E_{\alpha_{3}+\alpha_{6}} + (1 + *z_{1}z_{2} + *z_{1}z_{3} + *z_{2}z_{3})E_{\alpha_{3}} + E_{\alpha_{3}+\alpha_{4}+\alpha_{6}}$$

$$+ (*z_{3} + *z_{1})E_{\alpha_{3}+\alpha_{4}} + E_{\alpha_{5}} + E_{\alpha_{1}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{6}}$$

$$+ (*z_{3} + *z_{2})E_{\alpha_{2}+\alpha_{3}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{4}}$$
(B.1)

$$X_U \cap (\mathbb{C} \times \mathbb{C} \times \{\infty\}) \cong \{ (z_1, z_2) \in \mathbb{C}^2 \mid \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N \in U \}$$

$$\dot{s}_{4} \cdot x_{\alpha_{4}}(-z_{2}) \cdot \dot{s}_{2} \cdot x_{\alpha_{2}}(-z_{1}) \cdot N$$

$$= (*z_{1} + *z_{2})E_{\alpha_{3}} + E_{\alpha_{3}+\alpha_{4}} + E_{\alpha_{5}} + E_{\alpha_{1}} + E_{\alpha_{2}+\alpha_{3}}$$

$$+ (1 + *z_{1}z_{2})E_{\alpha_{3}+\alpha_{6}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{2}E_{\alpha_{2}+\alpha_{3}+\alpha_{6}} + *z_{1}E_{\alpha_{3}+\alpha_{4}+\alpha_{6}}$$
(B.2)

$$X_U \cap (\mathbb{C} \times \{\infty\} \times \mathbb{C}) \cong \{ (z_1, z_3) \in \mathbb{C}^2 \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot \dot{s}_2 \cdot x_{\alpha_2}(-z_1) \cdot N \in U \}$$

$$\dot{s}_{6} \cdot x_{\alpha_{6}}(-z_{3}) \cdot \dot{s}_{2} \cdot x_{\alpha_{2}}(-z_{1}) \cdot N$$

$$= E_{\alpha_{3}+\alpha_{6}} + (*z_{3}+*z_{1})E_{\alpha_{3}} + E_{\alpha_{4}+\alpha_{5}} + E_{\alpha_{2}+\alpha_{3}} + E_{\alpha_{1}}$$

$$(B.3)$$

$$+ E_{\alpha_{2}+\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{3}E_{\alpha_{2}+\alpha_{3}+\alpha_{4}} + (1+*z_{1}z_{3})E_{\alpha_{3}+\alpha_{4}} + *z_{1}E_{\alpha_{3}+\alpha_{4}+\alpha_{6}}$$

$$X_{U} \cap (\{\infty\} \times \mathbb{C} \times \mathbb{C}) \cong \{ (z_{2}, z_{3}) \in \mathbb{C}^{2} \mid \dot{s}_{6} \cdot x_{\alpha_{6}}(-z_{3}) \cdot \dot{s}_{4} \cdot x_{\alpha_{4}}(-z_{2}) \cdot N \in U \}$$

$$\dot{s}_{6} \cdot x_{\alpha_{6}}(-z_{3}) \cdot \dot{s}_{4} \cdot x_{\alpha_{4}}(-z_{2}) \cdot N$$

$$= E_{\alpha_{2}+\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{3}E_{\alpha_{2}+\alpha_{3}+\alpha_{4}} + *z_{2}E_{\alpha_{2}+\alpha_{3}+\alpha_{6}} + (1+*z_{2}z_{3})E_{\alpha_{2}+\alpha_{3}}$$

$$(B.4)$$

$$+ E_{\alpha_{3}+\alpha_{6}} + (*z_{3}+*z_{2})E_{\alpha_{3}} + E_{\alpha_{1}+\alpha_{2}} + E_{\alpha_{5}} + E_{\alpha_{3}+\alpha_{4}}$$

$$X_{U} \cap (\mathbb{C} \times \{\infty\} \times \{\infty\}) \cong \{ z_{1} \in \mathbb{C} \mid \dot{s}_{2} \cdot x_{\alpha_{2}}(-z_{1}) \cdot N \in U \}$$

$$\dot{s}_{2} \cdot x_{\alpha_{2}}(-z_{1}) \cdot N$$

$$= E_{\alpha_{3}} + E_{\alpha_{4}+\alpha_{5}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{6}} + E_{\alpha_{1}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{4}}$$

$$+ E_{\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{1}E_{\alpha_{3}+\alpha_{6}} + *z_{1}E_{\alpha_{3}+\alpha_{4}}$$
(B.5)

$$X_U \cap (\{\infty\} \times \mathbb{C} \times \{\infty\}) \cong \{ z_2 \in \mathbb{C} \mid \dot{s}_4 \cdot x_{\alpha_4}(-z_2) \cdot N \in U \}$$

$$\dot{s}_{4} \cdot x_{\alpha_{4}}(-z_{2}) \cdot N$$

= $E_{\alpha_{2}+\alpha_{3}+\alpha_{4}} + *z_{2}E_{\alpha_{2}+\alpha_{3}} + E_{\alpha_{3}} + E_{\alpha_{1}+\alpha_{2}} + E_{\alpha_{5}}$
+ $E_{\alpha_{2}+\alpha_{3}+\alpha_{6}} + E_{\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{2}E_{\alpha_{3}+\alpha_{6}}$ (B.6)

$$X_U \cap (\{\infty\} \times \{\infty\} \times \mathbb{C}) \cong \{ z_3 \in \mathbb{C} \mid \dot{s}_6 \cdot x_{\alpha_6}(-z_3) \cdot N \in U \}$$

$$\dot{s}_{6} \cdot x_{\alpha_{6}}(-z_{3}) \cdot N$$

$$= E_{\alpha_{2}+\alpha_{3}+\alpha_{6}} + *z_{3}E_{\alpha_{2}+\alpha_{3}} + E_{\alpha_{3}+\alpha_{4}+\alpha_{6}} + *z_{3}E_{\alpha_{3}+\alpha_{4}}$$

$$(B.7)$$

$$+ E_{\alpha_{1}+\alpha_{2}} + E_{\alpha_{4}+\alpha_{5}} + E_{\alpha_{3}} + E_{\alpha_{2}+\alpha_{3}+\alpha_{4}}$$

$$X_U \cap (\{\infty\} \times \{\infty\} \times \{\infty\}) = \begin{cases} \{\infty\} \times \{\infty\} \times \{\infty\} & \text{if } N \in U \\ \emptyset & \text{if } N \notin U \end{cases}$$
(B.8)

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