Cyclone Technology: An Overview*

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Abstract

The current network, which is based on managing resources on demand and accepting uncontrolled communication request, often leads to problems such as congestion and other queueing bottlenecks. The extent of congestion and queues depends on the variability in customer arrival times, services needed, and the resource allocation mechanism used by system components. The queue sizes, which results in congestion, can be reduced only by controlling the variability in customer arrival times, and this is best done by making explicit use of time. Cyclone technology uses the information based on times of events explicitly, including the design of systems. Cyclone provides the coordination of resources through dynamic, time-based resource management leading to a network that is capable of providing end-to-end low latency communications free of losses, jitter, and congestions.

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1 Introduction

Networks have been designed to process packets at nodes taking into account the packet header information. Clearly this information is not available until packets arrive at a node. As a consequence, the processing of a packet including scheduling its transmission on an outgoing link can be carried out only after a packet has arrived. In a connection-oriented environment, a connection is usually established for a well-defined use, and the traffic and its timing information is either readily available or easily derived. However, in the current networks, no attempt is made to utilize the timing information. The key idea in a Cyclone network is to use the timing information explicitly in managing all resources and actions throughout the network.

A basic operation of computer communication is to move a packet from a location **A** to another location **B**. The packet to be moved is stored in a buffer at **A** and is to be stored in a buffer at **B**. A device or a link, once started, carries out the move operation autonomously taking a fixed amount of time **t**. Note that **t** depends on the packet size, **s**, and the link speed. When a link carries out its operation with no interference, the time **t** is fixed, once **s** is fixed. Note that the move operation can be initiated in a number of ways. Typically, a node inspects the header of a packet, which contains information such as the destination address, to determine the link by which the packet is to move. The transmission, then, is activated when the link is free. However, when establishing the connection in a connection-oriented environment, the user usually knows how the connection is to be used and when the packets are to be sent. Based on the availability of such information about the connection, it is feasible to schedule the move of packets on a link. In this case, the link is activated based on its ***schedule*** or ***calendar***, which shows the time instances that it has to move the packets. The calendar of a link shows the buffer information as well when there are multiple buffers from which the link possibly takes packets. All store and forward operations are carried out in Cyclone technology using a time-based calendar, which is created when a connection is established. As a consequence, Cyclone connections can deliver loss free, jitter free, contention free, and in order data end-to-end.

We believe that the Cyclone technology offers the capability to the applications, which is not available from the current technologies, namely providing end-to-end guarantees for the time instants when each packet of the message is delivered to the applications.

In this paper, we present an overview of Cyclone technology describing its components and its basic modes of operations. We first define terminology followed by the description of Cyclone components in Section 2. In Section 3, data move and connection establishment operations are explained. We describe implementation issues in Section 4. Section 5 and Section 6 describe clock synchronization and scheduling approaches used in Cyclone, respectively. In Section 7, we present an example of handling a connection request. Several other issues are described in section 8. Our assessment of Cyclone is found in Section 9, and the comparison to other work is described in Section 10. We conclude this paper with the current status of Cyclone technology.

2 Architecture[12,13]

A Cyclone network provides a connection-oriented environment that accepts connection requests with a *temporal profile* specifying the time instants at which the sender sends data. In a Cyclone network, all components of the network operate in a deterministic manner according to a defined schedule based on temporal profiles provided by senders, thus, assuring a temporally determinate delivery of data end-to-end. Nodes are connected via links allowing an arbitrary topology for the

Cyclone network. A unit called Temporal Regulator (TR) provides the interface to hosts and external networks, therefore, forming a boundary of Cyclone Network. While the basic concept of Cyclone technology is very general and can be used with a variety of component technologies, we present the basic idea through one such design in this paper.

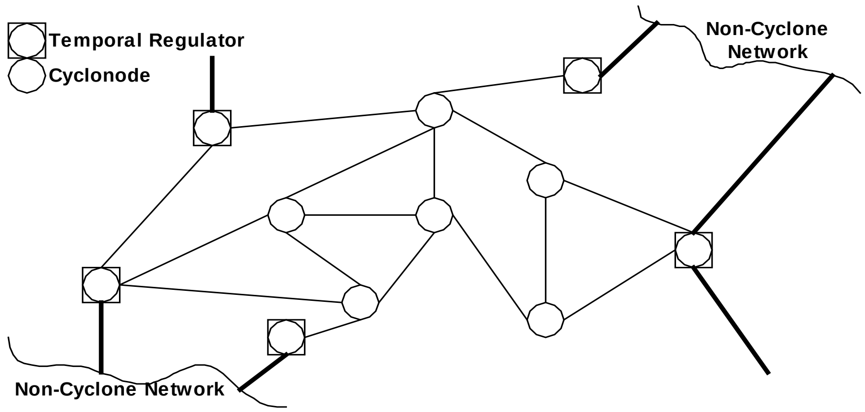

Figure 1 Cyclone Network

A message in this network is sent as a sequence of ***chunks***, each of which is transmitted in order. A chunk is a number of bytes that is fixed for the entire network. A ***control chunk*** is used to differentiate a chunk that carries a message that does not belong to any connection. A chunk that carries a message to request a connection is an example of a control chunk. The store-and-forward operation uses buffers at a node. A buffer is organized as a slotted buffer so that a chunk can be stored in a ***slot***. In a Cyclone network, a slot is a space-time description consisting of a ***chunk buffer*** and a ***time-tag***. We use a ***logical buffer*** that is of infinite size in this design description first, and then map it onto a physical buffer of finite size. Clearly, time-tags monotonically increase for the slots of a logical buffer.

Cyclone network is composed of links, ***CycloNodes***, and ***Temporal Regulators***. A link is a point-to-point unidirectional data path that connects two CycloNodes/Temporal Regulators. A link has a logical buffer at each end, a ***send-buffer*** and a ***receive-buffer***. There is a time tag for each slot, and the time tags for two adjacent slots differ by the chunk processing time of the link. For any slot in the send-buffer, there is a slot in the receive-buffer, and the time tags for the two corresponding slots differ by the link latency. Moving contents of the send-buffer to the receive-buffer is the only operation at a link. A link continuously moves one chunk at a time in a pipelined manner. Therefore, an empty slot in the send-buffer results in an empty slot in the receive-buffer.

In Cyclone, a ***CycloNode***, which has a set of incoming and outgoing links and a controller, carries out the functions of a switch/router, but in a temporally determinate manner. An outgoing link is organized in a way that it reads data from its send-buffer and stores the data in the receive-buffer, which is at the CycloNode at the other end of the link. Thus, the receive-buffers of incoming links and the send-buffers of outgoing links are visible at a node. At a CycloNode, chunks from the receive-buffers are moved to the send-buffers according to a calendar, a time-based schedule. This move operation must take place after the time-tag of the slot in the receive-buffer, but before the time-tag of the slot in the send-buffer.

Operations at a CycloNode, including switching of chunks, are carried out according to the time at its local clock. In order to maintain the required degree of temporal determinacy, it is important that the clocks in Cyclone network remain in synchrony with respect to each other. For this discussion, we assume that all clocks are synchronized and describe later how the required degree of clock synchronization can be achieved.

In addition, a CycloNode is responsible for managing connections, maintaining calendars, and routing. The controller at a CycloNode performs these operations. All communications among CycloNodes and/or Temporal Regulators are via control chunks. All control chunks are transferred to the controller, which processes them further. Note that all control chunks go across a link from one CycloNode to the next one, and not end-to-end.

A ***Temporal Regulator*** is a CycloNode with an additional interface, which is used to connect it to a host. All communications with any non-Cyclone network component are via this interface. A Cyclone connection is between two Temporal Regulators and operates in a temporally determinate manner. The host, however, may not supply the data with such a temporal determinacy. Therefore, a Temporal Regulator must provide mechanisms for tolerating the temporal variability observed in its host interface while maintaining temporal determinacy in its Cyclone interface. It initiates a Cyclone connection in response to the request received from the host. When it is at the receiving end of a connection, it assures that the host is ready to receive data for this connection before accepting the connection request. The source Temporal Regulator uses buffers to store data from the host until it transfers them to the Cyclone connection according to the temporal profile of the connection. The inverse operation takes place at the destination Temporal Regulator.

A Temporal Regulator provides a ***control chunk buffer***, which receives all control messages from the host such as connection request, terminate request, etc. Slots in a control chunk buffer are unscheduled; in other words, the controller examines the contents of chunks in this buffer for further action. A separate ***connection data chunk buffer*** is allocated for each connection when a connection is established. As a part of connection establishment processing, slots in a connection data chunk buffer are scheduled for outgoing transmission on a selected outgoing link or for receiving incoming data.

3 Operations

Let us consider how a chunk goes from a source Temporal Regulator to a sink Temporal Regulator at the other end of a connection. Note that when the connection is established, appropriate entries are made in the calendars at all intermediate CycloNodes for all chunks of the connection.

3.1 Data Movement

The data movement takes place across a link one chunk at a time. A link starts to move a chunk in a slot in its send-buffer with the current time-tag and places it in a slot in the receive-buffer with the corresponding time-tag. At a CycloNode, a chunk is moved from a slot in the receive-buffer to a slot in the send-buffer for an outgoing link at a time specified by the calendar. Note that this time must be after the time-tag of the slot in the receive-buffer and before the time-tag of the slot in the send-buffer. *As no header has to be processed during the move operation at the CycloNode, no headers are required for chunks*. In this way, a chunk is moved from a source Temporal Regulator to a sink Temporal Regulator for a connection.

Unlike data chunks, which go across the Cyclone network from a source Temporal Regulator to a sink Temporal Regulator, control chunks go from the controller at one CycloNode across a link to the controller at the other CycloNode. Their movement across a link is similar to that of data chunk and uses slots reserved at regular intervals or any unused slots.

3.2 Connection Establishment

A Cyclone connection is established between two Temporal Regulators with a defined temporal profile. The temporal profile for a connection request specifies all time instants when chunks would be ready for transmission. A source Temporal Regulator constructs a control chunk for this connection request and forwards it to a CycloNode selected according the routing table in its controller.

The controller at each intermediate CycloNode processes the request. First it examines the routing table to determine the outgoing link to be used. It then examines the temporal profile of the request and the current calendar of the node. If the request can be accommodated, it modifies the calendar by creating ***reserved*** entries in the calendar for this connection, and adjusts the temporal profile of the current request to conform to the reservations made. It then constructs a control chunk and forwards it to the next CycloNode through the outgoing link that is selected for this connection. In this way, the connection request traverses Cyclone network and reaches the sink Temporal Regulator.

Once the connection request reaches the sink Temporal Regulator, a confirmation message indicating the acceptance of the connection is sent back toward the source Temporal Regulator after the sink Temporal Regulator confirms that the host is ready to receive data for this connection. The confirmation message is sent along the same path that the request traversed to reach the destination. All CycloNodes on the path then change the calendar entries from ***reserved*** to ***confirmed*** state.

Any CycloNode can reject a connection request if it finds that the outgoing link cannot meet the request. A notification is sent on the upstream toward the source Temporal Regulator if any of intermediate CycloNodes rejects the connection request during this phase. All CycloNodes receiving this notification release resources that are reserved for this connection.

4 Implementation Issues

We have described the concept of a Cyclone network using time, which increases continuously, and logical buffers of infinite size. In a practical implementation, we define a period $\mathbf{P}$ that is common for the whole network. Let us consider a link $\mathbf{i}$, which operates at a link speed, $\mathbf{L_i}$. To move a chunk of size, $\mathbf{C}$ bytes, this link takes $\mathbf{D_i}$ seconds. As a consequence, the time tags of consecutive slots associated with this link differ by $\mathbf{D_i}$. In the period $\mathbf{P}$, the number of time slots, $\mathbf{N_i}$ is equal to $\mathbf{P/D_i}$. A physical buffer associated with this link has $\mathbf{N_i}$ slots, and we emulate the concept of an infinite buffer by circularly assigning the time tag to the slot of a physical buffer (Figure 2). One of these slots is reserved for sending control chunks, which can also be sent in any unused slot.

In the discussion above, we described the operations using two buffers for each link, which requires a buffer copy operation for each chunk. We can eliminate the copy operation by not having a send-buffer. Instead we have a sequence of pointers which point to receive-buffer slots and time tags. At the time specified by the time tag, the link starts the transfer of the chunk pointed to by the pointer reading it directly from the receive-buffer. By using dual-ported memory for the receive-buffers and having appropriate data paths between the outgoing links and the receive-buffers, we can carry out these operations with no conflicts.

In this mode of operation, we note that we need to construct a calendar for each outgoing link independently. This makes the Cyclone design highly scalable, as the complexity of constructing the calendar does not depend on the number of links connected to a node.

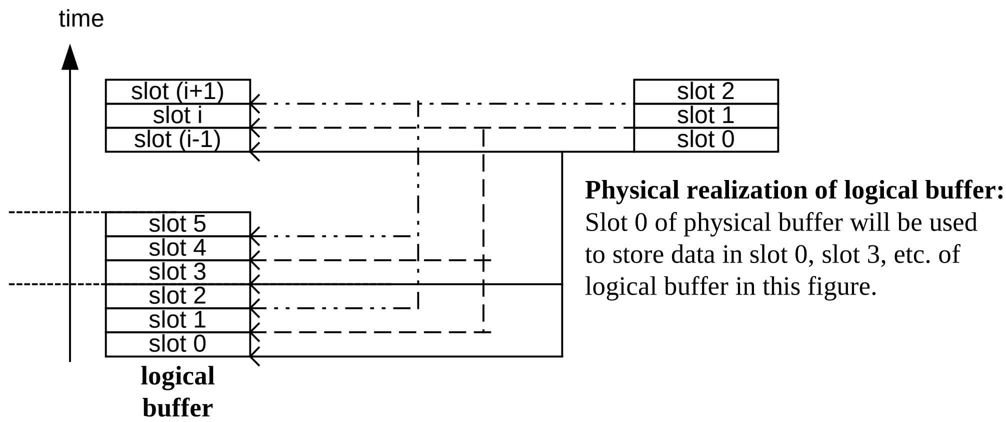

Figure 2: Buffer Model

5 Clock Synchronization

For any node, its own clock is the only mechanism for obtaining the knowledge of time and carrying out operations according to its calendar. These operations, however, have to maintain a fixed timing relationship with operations carried out at other nodes. Therefore, it is essential that the clocks in a Cyclone network be synchronized for their rates as well as phases. While the clocks do not have to maintain exactly the same time, they can not drift apart. As all practical clocks do show some jitter, and have varying rates, a specialized clock synchronization approach is used in Cyclone that synchronizes the clock rates and minimizes the jitter. The knowledge about the maximum permissible jitter is taken into account in scheduling.

We note that the timing on a link is controlled by the sending CycloNode and is visible to the receiving CycloNode in terms of the times when a period starts and when a slot starts. Based on this information, we have developed a synchronization algorithm [12], which maintains a high degree of synchronization among clocks, and gives a tight bound on the clock jitter. While the details of the clock synchronization approach are not included here, the results indicate that an accuracy of the order of a few parts in a million can be easily maintained when each node is using quartz clocks with known variability of a few hundred parts in a million.

Our design takes the phase variability into account by maintaining a small delay between the finish of a period and the start of the following period, which is adjusted to maintain high degree of synchrony. Even with a conservative estimate on the bound of phase variability this delay causes very little (less than .1%) loss of time or bandwidth.

6 Scheduling

As described in Section 2, data must be moved to a send-buffer only after it is placed in a receive-buffer for correct operations. Limited buffer space in the physical implementation imposes additional requirements. Recall that a link moves data continuously from one end to the other. When there is infinite buffer space, data reaching the end of a link is always written into a new slot.