

An Experiment to Assess the Cost-Benefits of Code Inspections in Large Scale Software Development

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Abstract

We conducted a long-term experiment to compare the costs and benefits of several different software inspection methods. These methods were applied by professional developers to a commercial software product they were creating. Because the laboratory for this experiment was a live development effort, we took special care to minimize cost and risk to the project, while maximizing our ability to gather useful data.

This article has several goals: (1) to describe the experiment's design and show how we used simulation techniques to optimize it, (2) to present our results and discuss their implications for both software practitioners and researchers, and (3) to discuss several new questions raised by our findings.

For each inspection we randomly assigned 3 independent variables: (1) the number of reviewers on each inspection team (1, 2 or 4), (2) the number of teams inspecting the code unit (1 or 2), and (3) the requirement that defects be repaired between the first and second team's inspections. The reviewers for each inspection were randomly selected without replacement from a pool of 11 experienced software developers. The dependent variables for each inspection included inspection interval (elapsed time), total effort, and the defect detection rate.

Our results are based on the observation of 88 inspections and challenge certain long-held beliefs about the most cost-effective ways to conduct inspections and raise some questions about the benefits of recently proposed methods.

1 Introduction

For almost twenty years, software inspections have been promoted as a cost-effective way to improve software quality. Although the benefits of inspections have been well studied, their costs are often justified by simply observing that the longer a defect remains in a system, the more expensive it is to repair, and therefore the future cost of fixing defects is greater than the present cost of finding them. However, this argument is simplistic – for example, it doesn't consider the powerfully negative effect inspections have on schedule.

We have observed that a typical release of AT&T's 5ESS[®] switch [16] ($\approx .5$ M lines of added and changed code per release on a base of 5M lines) can require roughly 1500 inspections, each with four, five or even

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more participants. Besides the obvious labor costs, holding such a large number of meetings can also cause delays which may significantly lengthen the development interval (calendar time to completion).¹ Since long development intervals risk substantial economic penalties, this hidden cost must be considered.

We hypothesized that different inspection approaches create different tradeoffs between minimum interval, minimum effort and maximum effectiveness. But until now there have been no empirical studies to evaluate these tradeoffs. We conducted such a study, and our results indicate that the choice of approach significantly affects the cost-effectiveness of the inspection.

Below, we review the relevant research literature, describe the various inspection approaches we examined, and present our experimental design, analysis, and conclusions.

1.1 Inspection Process Summary and Literature Review

To eliminate defects, many organizations use an iterative, three-step inspection procedure: Preparation, Collection, Repair [12]. First, a team of reviewers each reads the artifact separately, detecting as many defects as possible. Next, these newly discovered defects are collected, usually at a team meeting. They are then sent to the artifact's author for repair. Under some conditions the entire process may be repeated one or more times.

Many articles have been written about inspections. Most, however, are case studies describing their successful use [9, 10, 23, 20, 27, 14, 2]. Few critically analyze inspections or rigorously evaluate alternative inspection approaches. We believe that additional critical studies are necessary because the cost-effectiveness of inspections may well depend on such variables as team size, number of inspection sessions, and the ratio of individual contributions versus group efforts.

Team Size: Inspections are usually carried out by a team of four to six reviewers. Buck [3] provides data (from an uncontrolled experiment) that showed no difference in the effectiveness of three, four, and five-person teams. However, no studies have measured the effect of team size on inspection interval.

Single-Session vs. Multiple-Session Inspections: Traditionally, inspections are carried out in a single session. Additional sessions occur only if the original artifact or the inspection itself is believed to be seriously

¹As developer's calendars fill up, it becomes increasingly difficult to schedule meetings. This pushes meeting dates farther and farther into the future, increasing the development interval. [1]

flawed. But some authors have argued that multiple session inspections might be more effective.

Tsai et al. [21] developed the N-fold inspection process, in which N teams each carry out independent inspections of the entire artifact. The results of each inspection are collated by a single moderator, who removes duplicate defect reports. N-fold inspections will find more defects than regular inspections as long as the teams don't completely duplicate each other's work. However, they are far more expensive than a single team inspection.

Parnas and Weiss' active design reviews (ADR) [17] and Knight and Myers' phased inspections (PI) [15] are also multiple-session inspection procedures. Each inspection is divided into several mini-inspections or "phases". ADR phases are independent, while PI phases are executed sequentially and all known defects are repaired after each phase. Usually each phase is carried out by one or more reviewers concentrating on a single type of defect.

The proponents of multiple-session inspections believe they will be much more effective than single-session inspections, but they have not shown this empirically, nor have they considered its effect on inspection interval.

Group-centered vs. Individual-centered Inspections: It is widely believed that most defects are first identified during the collection meeting as a result of group interaction [8]. Consequently, most research has focused on streamlining the collection meeting by determining who should attend, what roles they should play, how long the meeting should last, etc.

On the other hand, several recent studies have concluded that most defects are actually found by individuals prior to the collection meeting. Humphrey [11] claims that the percentage of defects first discovered at the collection meeting ("meeting gain rate") averages about 25%. In an industrial case study of 50 design inspections, Votta [25] found far lower meeting gain rates (about 5%). Porter et al. [19] conducted a controlled experiment in which graduate students in computer science inspected several requirements specifications. Their results show meeting gain rates consistent with Votta's. They also show that these gains are offset by "meeting losses" (defects first discovered during preparation but never reported at the collection meeting). Again, since this issue clearly affects both the research and practice of inspections, additional studies are needed.

Defect Detection Methods. Preparation, the first step of the inspection process, is accomplished through the application of defect detection methods. These methods are composed of defect detection techniques, individual reviewer responsibilities, and a policy for coordinating responsibilities among the review team.

Defect detection techniques range in prescriptiveness from intuitive, nonsystematic procedures (such as ad

hoc or checklist techniques) to explicit and highly systematic procedures (such as correctness proofs).

A reviewer's individual responsibility may be general, to identify as many defects as possible, or specific, to focus on a limited set of issues (such as ensuring appropriate use of hardware interfaces, identifying untestable requirements, or checking conformity to coding standards).

Individual responsibilities may or may not be coordinated among the review team members. When they are not coordinated, all reviewers have identical responsibilities. In contrast, the reviewers in coordinated teams have distinct responsibilities.

The most frequently used detection methods (Ad Hoc and Checklist) rely on nonsystematic techniques. Reviewer responsibilities are general and identical. Multiple-session inspection approaches normally require reviewers to carry out specific and distinct responsibilities. One reason these approaches are rarely used may be that many practitioners consider it too risky to remove the redundancy of general and identical responsibilities and to focus reviewers on narrow sets of issues that may or may not be present. Clearly, the advantages and disadvantages of alternative defect detection methods need to be understood before new methods can be safely applied.

1.2 Hypotheses

Inspection approaches are usually evaluated according to the number of defects they find. As a result, some information has been collected about the effectiveness of different approaches, but very little about their costs. We believe that cost is as important as effectiveness, and we hypothesize that different approaches have significantly different tradeoffs between development interval, development effort, and detection effectiveness. Specifically, we hypothesize that

- inspections with large teams have longer inspection intervals, but find no more defects than smaller teams;
- multiple-session inspections are more effective than single-session inspections, but significantly increase inspection interval.
- multiple-session inspections with sequential sessions (sessions happen in a specific order and all defects found at the i^{th} session must be repaired before the $i + 1^{st}$ session begins) have a longer interval, but find more defects than multiple-session inspections with parallel sessions (sessions can happen in any order and

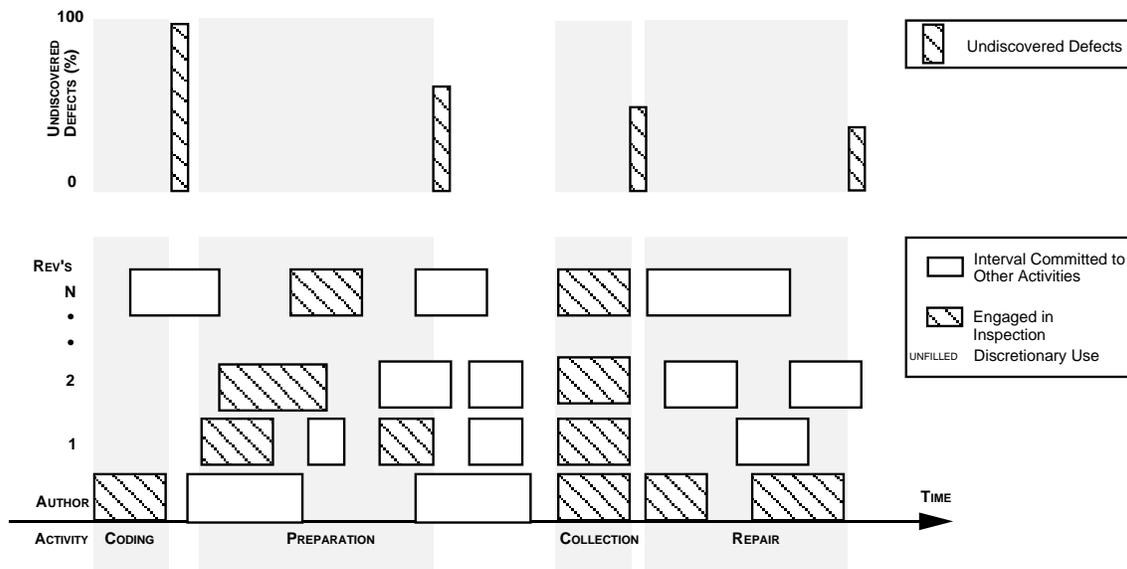


Figure 1: This figure depicts how inspection participants use time during the inspection process. The figure's lower panel summarizes the inspection's time usage. Specifically, it shows the inspection's participants (an author and several reviewers), the activities they perform (coding, preparation, collection, repair, and other), the subinterval devoted to each activity (denoted by the shaded areas), and the total inspection interval (end of coding to completion of repair). It also shows that in a software development organization, inspections must compete with other processes for limited time and resources. The upper portion of the figure shows when and to what extent inspections remove defects from the code.

defects are not repaired in between sessions).

2 The Experiment

To evaluate these hypotheses we designed and conducted a controlled experiment. Our purpose was to compare the tradeoffs between minimum interval, minimum effort, and maximum effectiveness of several inspection approaches.

2.1 Experimental Setting

We ran this experiment at AT&T on a project that was developing a compiler and environment to support developers of the AT&T 5ESS[®] telephone switching system. The finished system contains over 45K new lines of C++ code, plus 8K which was reused from a prototype.

Our inspector pool consisted of 11 experienced developers, each of which had received inspection training in the last 5 years. The experiment ran for 18 months (June, 1994 to December 1995), during which the team

performed 88 code inspections.

The first code units were inspected from July, 1994 to September, 1994, at which time the first integration build delivered the compiler's front end. After this there were few inspections as the development team tested and modified the front end and continued designing the back end. By Jan 1995, the back end code became available and there was a steady of inspections throughout 1995.

2.2 Operational Model

To test our hypotheses we needed to measure the effort, interval and effectiveness of every inspection. To do this we constructed two models; one for calculating inspection interval and effort, and another for estimating the number of defects in a code unit. These models are depicted in Figure 1.

2.2.1 Modeling the Inspection Interval

The inspection process begins when a code unit is ready for inspection and ends when the author finishes repairing the defects found in the code. The elapsed time between these events is called the inspection interval.

The length of this interval depends on the time spent working (preparing, attending collection meetings, and repairing defects) and the time spent waiting (time during which the inspection does not progress due to process dependencies, higher priority work, scheduling conflicts, etc).

In order to measure inspection interval and its various subintervals, we devised an inspection time model based on visible inspection events [26]. Whenever one of these events occurred it was timestamped and the event's participants were recorded. (In most cases this information was manually recorded on the forms described in Section 2.4.1.) These events occurred, for example, when code was ready for inspection, or when a reviewer started or finished his or her preparation. This information was entered into a database, and inspection intervals were reconstructed by performing queries against the database.

Inspection effort was calculated by summing the appropriate subintervals.

2.2.2 Modeling the Defect Detection Ratio

One important measure of an inspection's effectiveness is its defect detection ratio – the number of defects found during the inspection divided by the total number of defects in the code. Because we never know exactly how

many defects an artifact contains, it was impossible to make this measurement directly, and therefore we were forced to approximate it.

The estimation procedure needed be (a) as accurate as possible and (b) available throughout the study because we were experimenting with a live project and needed to identify and eliminate dangerously ineffective approaches as soon as possible.

We found no single approximation that met both criteria. Therefore we used three methods.

- **Observed detection ratio:** We assumed that total defect density is constant for all code units and that we could compare the number of defects found per KNCSL. This was always available, but may be very inaccurate.
- **Partial estimation of detection ratio:** We used capture-recapture methods to estimate pre-inspection defect content. This estimation can be performed when there are at least two reviewers and they discover some defects in common. Under these conditions this method is more accurate than the observed detection ratio and is available immediately after every inspection. Since capture-recapture techniques make that strong statistical assumptions, we tested our data to see whether or not this technique would be appropriate. We found that this method was inappropriate for our study and therefore we did not use it in our analysis. For example, inspectors often found completely disjoint sets of defects. (We've included the method here for completeness only. See Appendix A for more details.)
- **Complete estimation of detection ratio:** We can track the code through testing and field deployment, recording new defects as they are found. This is the most accurate method, but is not available until well after the project is completed. We are currently instrumenting the development process to capture this data, but it will not be available for some time.

2.3 Experimental Design

2.3.1 Variables

The experiment manipulated 3 independent variables:

1. the number of reviewers per team (1, 2, or 4 reviewers, in addition to the author),
2. the number of inspection sessions (1-session or 2-sessions),

	Number of Sessions		Totals
	1	2	
Reviewers		With Repair	No Repair
1	$\frac{1}{9}$	$\frac{1}{9}$	$\frac{1}{9}$
2	$\frac{1}{9}$	$\frac{1}{9}$	$\frac{1}{9}$
4	$\frac{1}{3}$	0	0
Totals	$\frac{2}{9}$	$\frac{2}{9}$	1

Table 1: This table gives the proportion of inspections originally allocated to each treatment. These proportions changed during the experiment’s execution because several poorly performing treatments were discontinued.

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- the coordination between sessions (in 2-session inspections the author was either required to or prohibited from repairing known defects between sessions).

These variables reflect many (but not all) of the differences between Fagan inspections, N-Fold inspections, Active Design Reviews, and Phased Inspections. One very important difference that is **not** captured in our experiment is the choice of defect detection methods. The methods used in Active Design Reviews and Phased Inspections involve systematic techniques, with specific and distinct responsibilities, while Fagan and N-fold inspection normally use nonsystematic techniques with general and identical responsibilities.

The treatments are arrived at by selecting a value for each of the independent variables and are denoted [**1**, or **2**] sessions **X** [**1**, **2**, or **4**] persons [**N**o-repair, **R**epair], so, for example, the label 2sX1pN indicates a two-session, one-person, without-repair inspection. These distributions changed during the experiment because some of the poorly performing or excessively expensive treatments were discontinued.

For each inspection we measured 5 dependent variables:

- inspection interval,
- inspection effort,
- estimated defect detection ratio,
- the percentage of defects first identified at the collection meeting (meeting gain rate),
- the percentage of potential defects reported by an individual, that were determined not to be defects during the collection meeting (meeting suppression rate).

We also captured repair statistics for every defect (See Section 2.4.2). This information was used to discard certain defect reports from the analysis – i.e., those regarding defects that required no changes to fix them or

concerned coding style rather than incorrect functionality.

2.3.2 Design

This experiment used a $2^2 \times 3$ partial factorial design to compare the interval, effort, and effectiveness of inspections with different team sizes, number of inspection sessions, and coordination strategies. We chose a partial factorial design because some treatment combinations were considered too expensive (e.g., two-session-four-person inspections with and without repair).

2.3.3 Professional Developers as Subjects

We took special care to insure that the experimental design did not inadvertently influence subject behavior (professional developers and inspectors). Each study participant was given a simple "bill of rights", reminding them of their right to withdraw from the study at anytime with no recriminations from the researchers or his/her management [13]. Each participant acknowledged this right at the beginning of the experiment by signing a release form. No subject used this right during the experiment.

2.3.4 Discontinuing Ineffective Treatments

In our initial briefings with the development team, we were asked, "What happens if a treatment cost too much or takes too long?" They were concerned that the experiment could jeopardize the budget or schedule of the product.

We took this concern seriously and realized that if a treatment was jeopardizing the project's budget, schedule, or quality, we would have to discontinue the treatment. However, the professional developers also realized that they were gaining some valuable knowledge from the study. So our compromise was to discontinue any treatment after enough inspections had been done, and we could convince ourselves that nothing "unlucky" had happen. (See Appendix B for more details.)

This specific problem of knowing when to stop experimenting is important for software engineer researchers. Because experiments that use professional developers creating professional products can have very strong validity, but can put the participated project at risk. A similar problem confronts medical researchers when assessing the efficacy of drug treatments for diseases [13]. They solve the problem like we did through an agreement with their subjects in the study.

2.3.5 Threats to Internal Validity

Threats to internal validity are influences that can affect the dependent variable without the researcher's knowledge. We considered three such influences: (1) selection effects, (2) maturation effects, and (3) instrumentation effects.

Selection effects are due to natural variation in human performance. For example, if one-person inspections are done only by highly experienced people, then their greater than average skill can be mistaken for a difference in the effectiveness of the treatments. We limited this effect by randomly assigning team members for each inspection. This way individual differences were spread across all treatments.

Maturation effects result from the participants' skills improving with experience. Again we randomly assigned the treatment for each inspection to spread any performance improvements across all treatments.

Instrumentation effects are caused by the code to be inspected, by differences in the data collection forms, or by other experimental materials. In this study, one set of data collection forms was used for all treatments. Since we could not control code quality or code size, we randomly assigned the treatment for each inspection.

2.3.6 Threats to External Validity

Threats to external validity are conditions that limit our ability to generalize the results of our experiment to industrial practice. We considered three sources of such threats: (1) experimental scale, (2) subject generalizability, and (3) subject and artifact representativeness.

Experimental scale is a threat when the experimental setting or the materials are not representative of industrial practice. We avoided this threat by conducting the experiment on a live software project.

A threat to subject generalizability may exist when the subject population is not drawn from the industrial population. This is not a concern here because our subjects are software professionals.

Threats regarding subject and artifact representativeness arise when the subject and artifact population is not representative of the industrial population. This may endanger our study because our subjects are members of a development team, not a random sample of the entire development population and our artifacts are not representative of every type of software professional developers write.

2.3.7 Analysis Strategy

Our strategy for analyzing the experiment has three steps: resolution analysis, calibration, and hypothesis testing.

Resolution Analysis. An experiment’s resolution is the minimum difference in the effectiveness of two treatments that can be reliably detected.

We performed the resolution analysis using a Monte Carlo simulation. The simulation indicates that with as few as 5 observations per treatment the experiment can reliably detect a difference as small as .075 in the defect detection rate of any two treatments. The strongest influence on the experiment’s resolution is the standard deviation of the code units’ defect content – the smaller the standard deviation the finer the resolution. (See Appendix B for more details.)

Calibration. We continuously calibrated the experiment by monitoring the sample mean and variance of each treatment’s detection ratio and inspection interval, and the number of observed inspections. Based on this information and the resolution analysis we discontinued some treatments because their effectiveness was so low or their interval was so long that it put the project at risk. We also monitored the experiment to ensure that the distribution of treatments did not produce too few data points to identify statistically significant performance differences².

Hypothesis Testing. Once the data was collected we analyzed the combined effect of the independent variables on the dependent variables to evaluate our hypotheses. Once the significant explanatory variables were discovered and their magnitude estimated, we examined subsets of the data to study specific hypotheses.

2.4 Experimental Instrumentation

We designed several instruments for this experiment: preparation and meeting forms, author repair forms, and participant reference cards.

2.4.1 Data Collection Forms

We designed two data collection forms, one for preparation and another for the collection meeting.

²For example, if two treatments have little within-treatment variance and very different mean performance, then few data points are needed to statistically establish the difference. Otherwise, more observations are necessary.

The meeting form was filled in at the collection meeting. When completed, it gives the time during which the meeting was held, and a page number, a line number, and an ID for each defect.

The preparation form was filled in during both preparation and collection. During preparation, the reviewer recorded the times during which he or she reviewed, and the page and line number of each issue (“suspected” defect). During the collection meeting the team decided which of the reviewer’s issues were, in fact, real defects. At that time, real defects were recorded on the meeting form and given an ID. If a reviewer had discovered this defect during preparation then they record this ID on their preparation form.

2.4.2 Author Repair Forms

The author repair form captured information about each defect identified during the inspection. This information included Defect Disposition (no change required, repaired, deferred); Repair Effort ($\leq 1hr$, $\leq 4hr$, $\leq 8hr$, or $> 8hr$), Repair Locality (whether the repair was isolated to the inspected code unit), Repair Responsibility (whether the repair required other developers to change their code), Related Defect Flag (whether the repair triggered the detection of new defects), and Defect Characteristics (whether the defect required any change in the code, was changed to improve readability or to conform to coding standards, was changed to correct violations of requirements or design, or was changed to improve efficiency).

2.4.3 Participant Reference Cards

Each participant received a set of reference cards containing a concise description of the experimental procedures and the responsibilities of the authors and reviewers.

2.5 Conducting the Experiment

To support the experiment, Mr. Harvey Siy, a doctoral student working with Dr. Porter at the University of Maryland, joined the development team in the role of inspection quality engineer (IQE). The IQE was responsible for tracking the experiment’s progress, capturing and validating data, and observing all inspections. The IQE also attended the development team’s meetings, but had no development responsibilities.

When a code unit was ready for inspection, its author sent an inspection request to the IQE. The IQE then randomly assigned a treatment (based on the treatment distributions given in Table 1) and randomly drew the

review team from the reviewer pool.³ These names were then given to the author, who scheduled the collection meeting. Once the meeting was scheduled, the IQE put together the team's inspection packets.⁴

The inspection process used in this environment is similar to a Fagan inspection, but there are some differences. During preparation, reviewers analyze the code in order to find defects, not just to acquaint themselves with the code. During preparation reviewers have no specific technical roles (i.e., tester, or end-user) and have no checklists or other defect detection aids. All suspected defects are recorded on the preparation form. The experiment places no time limit on preparation, but a organizational limit of 300 LOC over a maximum of 2 hours is generally observed.

For the collection meeting one reviewer is selected to be the reader. This reviewer paraphrases the code. (Often this involves reading several lines of code at a time and emphasizing their function or purpose. During this activity, reviewers may bring up any issues found during preparation or discuss new issues. One reviewer acts as the the moderator. This person runs the meeting and makes sure all required changes are made. The code unit's author compiles the master list of all defects and no other reviewer has a predefined role.

The IQE attended every collection meeting to ensure that all the procedures were followed correctly. He also answered questions about how to fill out the forms and took extensive field notes. After the collection meeting he gave the preparation forms to the author, who then repaired the defects, filled out the author repair form, and returned all forms to the IQE. After the forms were returned, the IQE interviewed the author to validate any questionable data.

3 Data and Analysis

Four sets of data are important for this study: the team defect summaries, the individual defect summaries, the interval summaries, and the author repair summaries. This information is captured on the preparation, meeting, and repair forms.

The team defect summary forms show all the defects discovered by each team. This form is filled out by the author during the collection meeting and is used to assess the effectiveness of each treatment. It is also used to measure the added benefits of a second inspection session by comparing the meeting reports from both halves of

³We did not allow any single reviewer to be assigned to both teams in a two-session inspection.

⁴The inspection packet contains the code to be inspected, all required data collection forms and instructions, and a notice giving the time and location of the collection meeting.

two-session inspections with no repair.

The individual defect summary forms show whether or not a reviewer discovered a particular defect. This form is filled out during preparation to record all suspected defects. The data is gathered from the preparation form and is compiled during the collection meeting when reviewers cross-reference their suspected defects with those that are recorded on the meeting form. This information, together with the team summaries, is used to calculate the capture-recapture estimates and to measure the benefits of collection meetings.

The interval summaries describe the amount of calendar time that was needed to complete the inspection process. This information is used to compare the average inspection interval and the distribution of subintervals for each treatment.

The author repair summaries characterize all the defects and provide information about the effort required to repair them.

3.1 Data Reduction

Data reduction is the manipulation of data after its collection. We have reduced our data in order to (1) remove data that is not pertinent to our study, and to (2) adjust for systematic measurement errors.

3.1.1 Reducing the Defect Data

The preparation and meeting forms capture the set of issues that were raised during each inspection. The reduction we made was to remove duplicate reports from 2-session-without-repair inspections. This task is performed by the IQE and the code unit's author.

Another reduction was made because, in practice, many issues, even if they went unrepaired, would not lead to incorrect system behavior, and they are therefore of no interest to our analysis.

Although defect classifications are usually made during the collection meeting, we feel that authors understand the issues better after they have attempted to repair them, and therefore, can make more reliable classifications. consequently, we use information in the repair form and interviews with each author to classify the issues into one of three categories:

- False Positives (issues for which no changes were made),
- Soft Maintenance (issues for which changes were made only to improve readability or enforce coding stan-

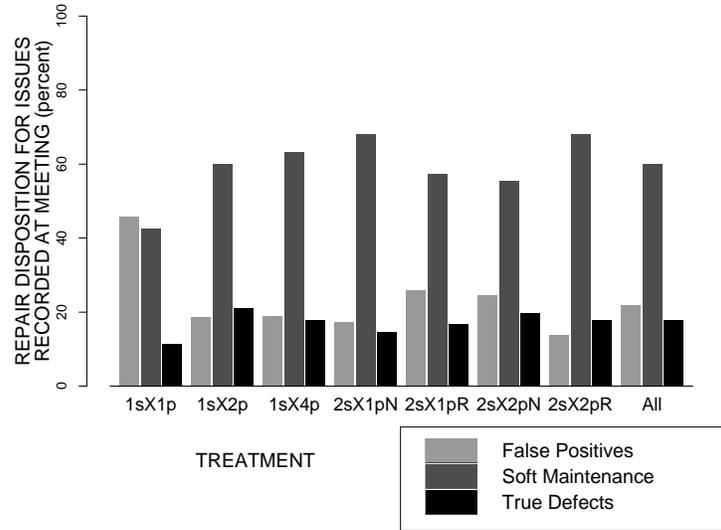


Figure 2: **Disposition of Issues Recorded at the Collection Meeting.** For each treatment, the barchart shows the percentage of the issues recorded at collection meetings that turn out to be false positives, soft maintenance, or true defects. Across all treatments, only 18% of the issues are true defects.

dards),

- True Defects (issues for which changes were made to fix requirements or design violations, or to improve system efficiency).

The distribution of defect classifications for each treatment appears in Figure 2. Across all inspections, 22% of the issues are False Positives, 60% involve Soft Maintenance, and 18% are True Defects. We consider only True Defects in our analysis of estimated defect detection ratio (a dependent variable).⁵

3.1.2 Reducing the Interval Data

The preparation, meeting, and repair forms show the dates on which important inspection events occur. This data is used to compute the inspection intervals.

We made two reductions to this data. First, we observed that some authors did not repair defects immediately following the collection meeting. Instead, they preferred to concentrate on other development activities, and fix the defects later, during slow work periods. To remove these cases from the analysis, we use only the pre-meeting interval (the calendar period between the submission of an inspection request and the completion of the collection

⁵We observed that most of the soft maintenance issues are caused by conflicts between different reviewers about the coding style or conventions used. Since, in and of themselves, these are not true defects some authors never reported them, others always did.

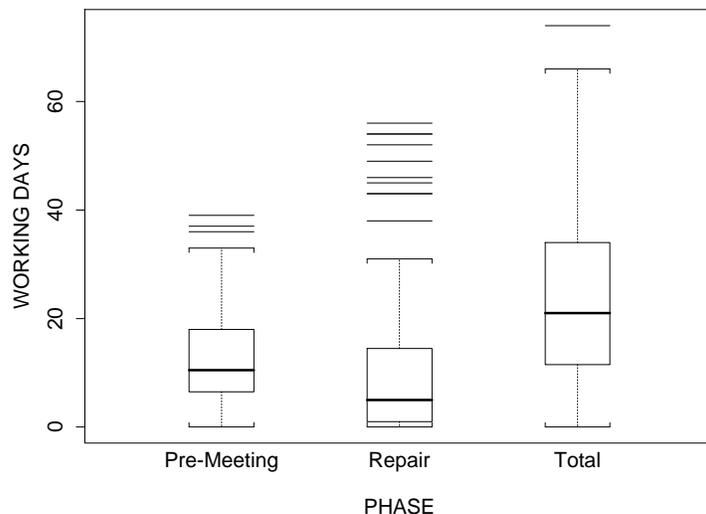


Figure 3: **Pre-meeting Inspection Interval.** These boxplots show all the interval data divided into two parts: time before the meeting and time after the meeting. The median inspection interval is 21 days, 50% of which is before the meeting.

meeting) as our initial measure of inspection interval.

When this reduction is made, two-session inspections have two inspection subintervals – one for each session. The interval for a two-session inspection is the longer of its two subintervals, since both of them begin at the same time.

Next, we removed all non-working days from the interval. Non-working days are defined as either (1) weekend days during which no inspection activities occur, or (2) days during which the author is on vacation and no reviewer performs any inspection activities. We use these reduced intervals as our measure of inspection interval.

Figure 3 is a boxplot⁶ showing the number of working days from the issuance of the inspection request to the collection meeting (Pre-Meeting) , from the collection meeting to the completion of repair (Repair), and the total (Total). The total inspection interval has a median of 21 working days, 10.5 before and 10.5 after the collection meeting.

3.2 Overview of Data

⁶In this paper we have made extensive use of boxplots to represent data distributions. Each data set is represented by a box whose height spans the central 50% of the data. The upper and lower ends of the box marks the upper and lower quartiles. The data's median is denoted by a bold line within the box. The dashed vertical lines attached to the box indicate the tails of the distribution; they extend to the standard range of the data (1.5 times the inter-quartile range). All other detached points are "outliers". [5]

Team Size	Number of Sessions		Totals	
	1	2		
	With Repair	No Repair		
1	7	5	18	30
2	26	4	15	45
4	13	0	0	13
Totals	46	9	33	88

Table 2: This table shows the number of inspections allocated to each treatment.

Table 2 shows the number of observations for each treatment. Figure 4 is a contrast plot showing the interval, effort, and effectiveness of all inspections and for every setting of each independent variable. This information is used to determine the amount of the variation in the dependent variables that is explained by each independent variable. We also show another variable, total number of reviewers (the number of reviewers per session multiplied by the number of sessions). This variable provides information about the relative influence of team size vs. number of sessions.

3.3 Defect Discovery by Inspection Phase

During preparation, reviewers analyze the code units to discover defects. After all reviewers are finished preparing, a collection meeting is held. These meetings are believed to serve at least two important functions: (1) suppressing unimportant or incorrect defect reports, and (2) finding new defects. In this section we analyze how defect discovery is distributed across the preparation and collection meeting activities.

Analysis of Preparation Reports. One input to the collection meeting is the list of defects found by each reviewer during his or her preparation. Figure 5 shows the percentage of defects reported by each reviewer that are eventually determined to be true defects. Across all 233 preparation reports, only 13% of all issues turn out to be true defects. We can find no clear relationship between the independent variables and preparation effectiveness.

Analysis of Suppression. It is generally assumed that collection meetings suppress unimportant or incorrect defect reports, and that without these meetings, authors would have to process many spurious reports during repair. As we deduce from the previous section an average of 87% of reviewer reports (100% - 13%) do not involve true defects.

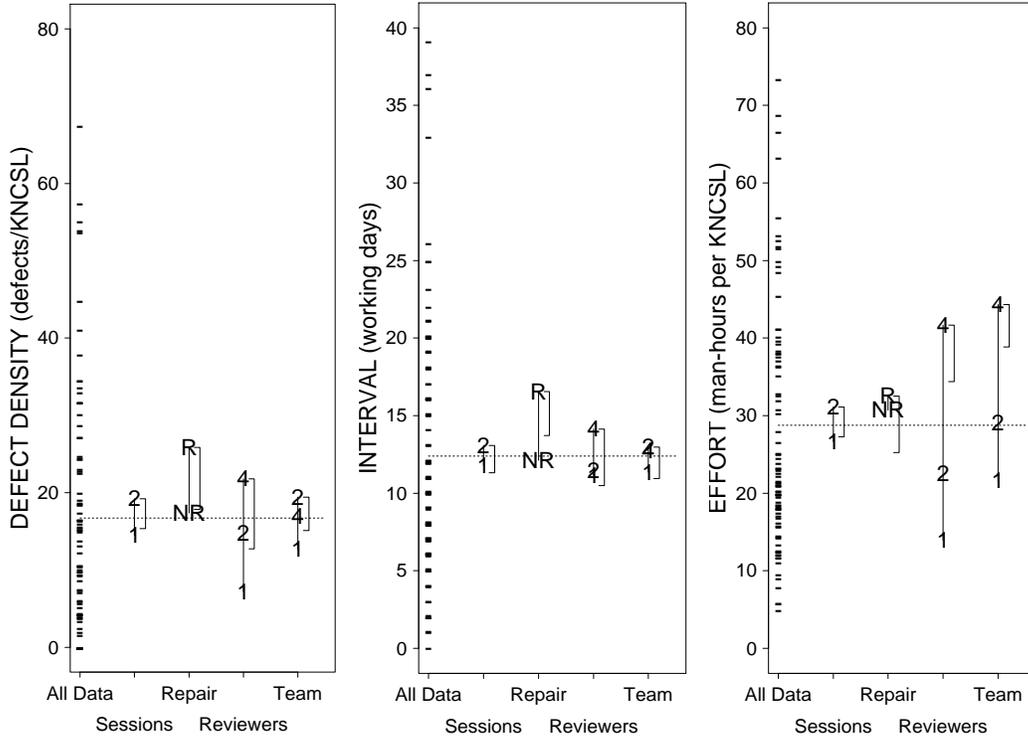


Figure 4: **Effectiveness, Interval, and Effort by Independent Variables.** The dashes in the far left column of the first plot show the defect detection rates for all inspections. The dotted horizontal line marks the average defect detection rate. The other four columns indicate factors that may influence this dependent variable. The plot demonstrates the ability of each factor to explain variations in the dependent variable. For the Repair factor, the vertical locations of the symbols "N" and "NR" are determined by averaging the defect detection rates for all code inspections using 2-sessions with repair and 2-sessions without-repair. The bracket at each factor represents one standard error of difference. If the actual difference is longer than the bracket, then that factor is statistically significant. The middle and right panels show similar information for inspection interval and effort.

Figure 6 shows the suppression rates for all 233 reviewer reports. Across all inspections about 26% of issues are suppressed. This appears to be independent of the treatment.

Analysis of Meeting Gains Another function of the collection meeting is to find new defects in addition to those discovered by the individual reviewers. Defects that are first discovered at the collection meeting are called meeting gains.

Figure 7 shows the meeting gain rates for all 131 collection meetings. Across all inspections, 30% of all defects discovered are meeting gains. The data suggests meeting gains are independent of treatment.

3.4 Analysis of Effort Data

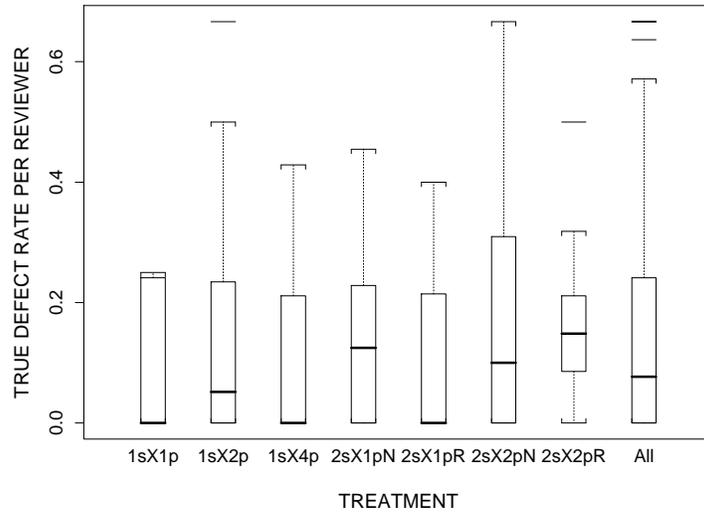


Figure 5: **True Defect Rate per Reviewer Preparation Report by Treatment.** This boxplot shows the rate at which defects found during preparation are eventually considered to be true defects. Across all treatments, only 13% of the reports turn out to be true defects.

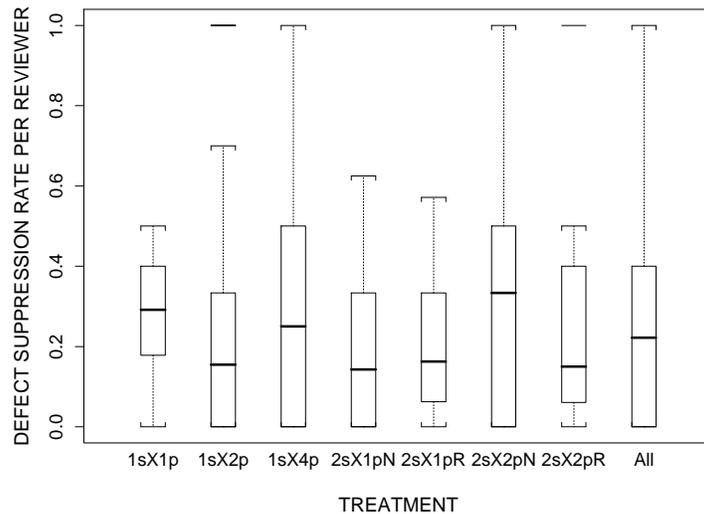


Figure 6: **Meeting Suppression Rate by Treatment.** These boxplots show the suppression rate for each reviewer by treatment. The suppression rate for a reviewer is the number of defects detected during preparation but not included in the collection meeting defect report, divided by the total number of defects recorded by the reviewer in his/her preparation. Across all inspections, 26% of the preparation reports are suppressed.

The common measure of inspection cost is total effort – the number of hours spent in preparation and meeting by each reviewer and author. Figure 8 shows the effort spent per KNCSL for each inspection by treatment and for all treatments. Across all treatments, the median effort is about 22 person-hours per KNCSL.

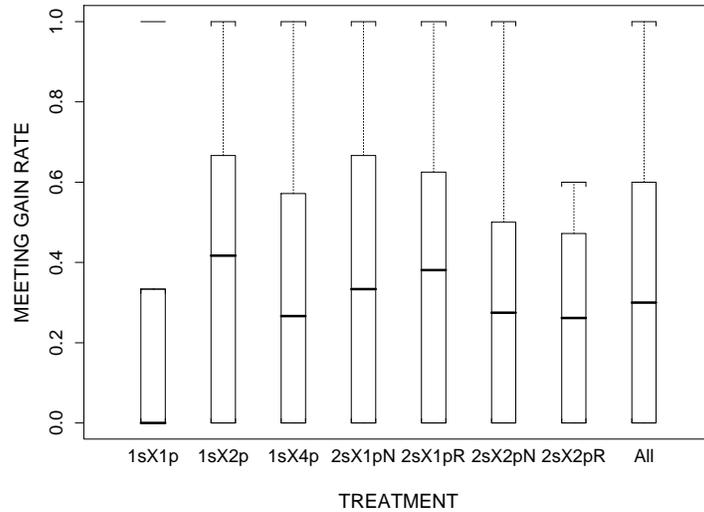


Figure 7: **Meeting Gain Rate by Treatment.** These boxplots shows the meeting gain rates for all inspections and for each treatment. The average rate was 30%.

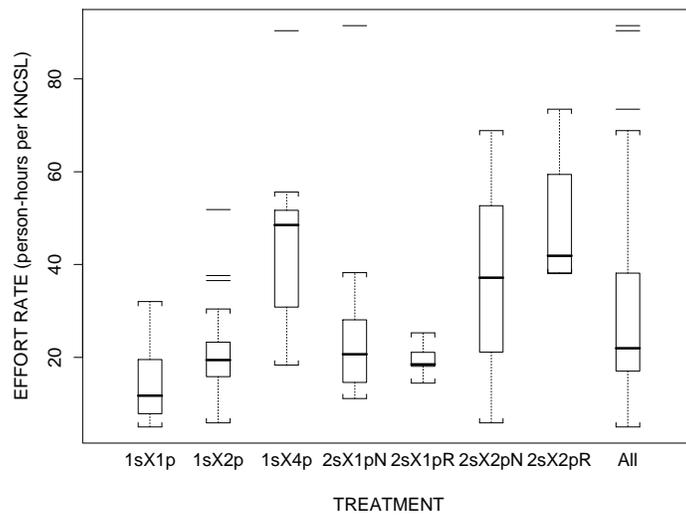


Figure 8: **Total Inspection Effort by Treatment.** This plot shows the total inspection effort per KNCSL for each treatment. Across all treatments, the median effort is 22 person-hours per KNCSL.

The data suggest that effort increases in direct proportion with the total number of reviewers while the number of sessions and the repair between sessions have no effect ⁷. That is, inspections involving 4 reviewers (1sX4p, 2sX2pN, and 2sX2pR) required significantly more effort than inspections involving 2 reviewers. Likewise,

⁷In this article, we consider two data distributions to be significantly different only if the Wilcoxon rank sum test rejects the null hypothesis that the observations are drawn from the same population with a confidence level $\geq .9$.

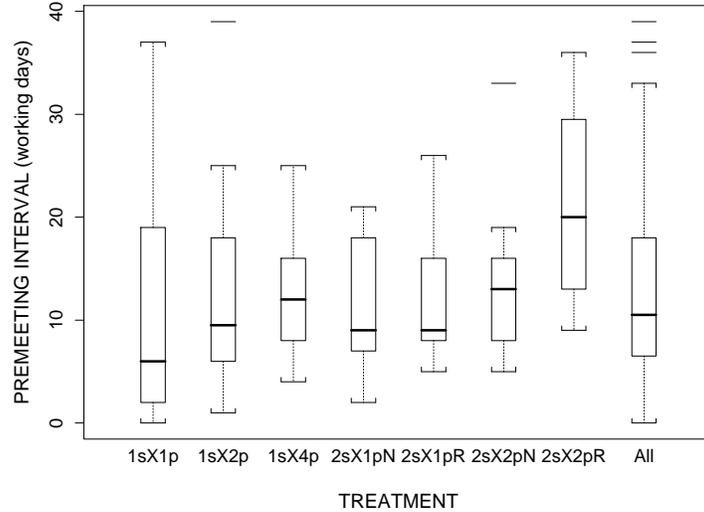


Figure 9: **Pre-meeting Interval by Treatment.** This plot shows the observed pre-meeting interval for each inspection treatment. Across all treatments, the median interval is 10.5 days.

inspections involving 2 reviewers (1sX2p, 2sX1pN, and 2sX1pR) required significantly more effort than inspections involving 1 reviewer.

3.5 Analysis of Interval Data

Inspection interval is another important, but often overlooked cost. Figure 9 shows the inspection interval (pre-meeting only) by treatment and for all treatments.

The cost of increasing team size is suggested by comparing 1-session inspections (1sX1p, 1sX2p, and 1sX4p). Since there is no difference between the intervals, team size alone did not affect interval.

The additional cost of multiple inspection sessions can be seen by comparing 1-session inspections with 2-session inspections (1sX2p and 1sX1p with 2sX2p and 2sX1p inspections). We find that 2sX1p inspections didn't take longer to conduct than 1sX1p inspections, but that 2sX2p inspections took longer to complete than 1sX2p inspections. (This effect is caused solely by the 2sX2pR treatment, since there was no difference between 1sX2p and 2sX2pN inspections.)

The cost of serializing two inspection sessions is suggested by comparing 2-session-with-repair inspections to 2-session-without-repair inspections (2sX2pN and 2sX1pN with 2sX2pR and 2sX1pR inspections). When the teams had only 1 reviewer we found no difference in interval, however, we did see a difference for 2-reviewer

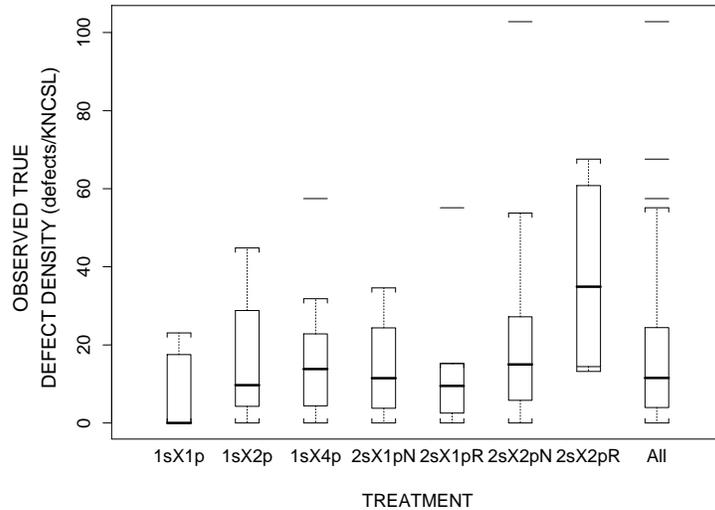


Figure 10: **Observed Defect Density by Treatment.** This plot shows the observed defect density for each inspection treatment. Across all inspections, the median defect detection rate was 12 defects per KNCSL.

teams. This indicates that requiring repair between sessions only increases interval as the team size grows.

Another interesting observation is that the median interval for the 2sX2pR treatment is extremely long (20 days), while all others have a median of only 10 days. Since this treatment took twice as long to complete than did the others we discontinued it early in the experiment. Consequently, we conducted only four of these inspections. Nevertheless, we are convinced that this finding warrants further study, because it suggests that relatively straightforward changes to a process can have dramatic, negative effects on interval.

3.6 Analysis of Effectiveness Data

The primary benefit of inspections is that they find defects. This benefit varied with different inspection treatments. Figure 10 shows the observed defect density for all inspections and for each treatment separately.

The effect of increasing team size is suggested by comparing the effectiveness of all 1-session inspections (1sX1p, 1sX2p, and 1sX4p inspections). There was no difference between 2- and 4-person inspections, but both performed better than 1-person inspections.

The effect of multiple sessions is suggested by comparing 1-session inspections with 2-session inspections. When team size is held constant (1sX2p vs. 2sX2p and 1sX1p vs. 2sX1p inspections), 2-session inspections were more effective than 1-session inspection only for 1-person teams. However, when total number of reviewers is

held constant (1sX2p vs. 2sX1p and 1sX4p vs. 2sX2p) there were no differences in effectiveness.

The effect of serializing multiple sessions is suggested by comparing 2-session-with-repair inspections to 2-session-without-repair inspections (2sX2pN and 2sX1pN with 2sX2pR and 2sX1pR inspections). The data show that repairing defects between multiple sessions didn't increase effectiveness when the team size was one, but did when the team size was two. This result should be viewed with caution, however, because there are only four 2sX2pR and five 2sX1pR inspections, respectively. Also, during the time in which the with-repair treatments were used they performed no differently than did without-repair treatments, and furthermore the overall mean dropped steadily as the experiment progressed possibly exaggerating the differences between the 2sX2pR and 2sX2pN treatments. (See Appendix C for more details.)

We draw several observations from this data: (1) increasing the number of reviewers did not necessarily lead to increased defect discovery, (2) splitting one large team into two smaller teams did not increase effectiveness, and (3) repairing defects in between 2-session inspections doesn't guarantee increased effectiveness.

4 Low Level Analysis

Several software inspection researchers have proposed changes to the structure of the process, hoping to improve its performance. For example, originally researchers claimed that large teams would bring a wide diversity of expertise to an inspection, and, therefore find more defects than would smaller teams. But later authors believed that smaller teams would be better because they would minimize the inefficiencies of large team meetings. Some authors argued further that multiple sessions with small teams would be more effective than a single session with a larger team because the small teams would be nearly as effective as large ones, wouldn't duplicate each other's effort and would have more effective collection meetings. defects. Finally, some authors told us that repairing defects in between multiple sessions would be more effective than two sessions without repair because repair would improve the ability of the second team to find defects.

Our initial analysis suggests, however, that many of these changes have little or no effect on observed defect density. For example,

- increasing team size doesn't always improve performance. ($1sX1p < 1sX2p$, but $1sX2p = 1sX4p$),
- creating two smaller teams isn't an effective way to reorganize a large group. ($2sX2p = 1sX4p$ and $2sX1p$

= 1sX2p), and

- repairing defects between sessions doesn't guarantee improved inspection performance. (2sX2pR = 2sX2pN⁸ and 2sX1pR = 2sX1pN).

One possible explanation is that the assumptions driving inspection process changes didn't hold in practice. (e.g., that repairing defects between multiple sessions didn't improve the ability of the second team to find defects.) Another possible explanation is that the treatments had unintended, negative side effects (i.e., the treatment improved some aspect of the inspection while degrading another).

To evaluate these potential explanations we examined the effect of each treatment on several inspection sub-activities.

4.1 Modeling Defect Detection in an Inspection Artifact

First, we have developed a model to measure defect discovery in each inspection subtask. The model, shown in Figure 11, assumes that the inspection artifact contains N undiscovered defects. Each reviewer, R_i , finds some number of defects, p_i , during preparation. Some number of these, *common*, may be found by more than one reviewers so the number of unique defects found in preparation, P , may be less than $\sum p_i$. Some number of additional defects, M , may be found at the meeting. During the meeting some of the defects found in preparation may be suppressed (determined not to be defects). These are called meeting losses.

Although we don't know how many true defects are suppressed, we will assume the number to be small and will, therefore, ignore meeting losses for now. Given this assumption, the number of defects found in one inspection, D , is just $P + M$ and the observed defect density is $\frac{D}{NCSL}$, where $NCSL$ is the number of noncommentary lines of code in the artifact.

Using this model and the data from our experiment we can calculate several statistics.

1. the average number of defects found by individual reviewers during preparation: \bar{p}_i ,
2. the number of unique preparation defects: P ,
3. the number of defects found by more than one reviewer during preparation: *common*,

⁸Comparing only the inspections that occurred while the 2sX2pR treatment was being used.

Defect ID	1	2	3	4	5	6	7	8	9	10	...	N	Number Found
R_1	✓		✓							✓	...		p_1
R_2		✓	✓		X			✓			...		p_2
R_3								✓			...	✓	p_3
⋮													⋮
R_n						✓				✓	...	✓	p_n
<i>Preparation</i>	✓	✓	✓			✓		✓		✓	...	✓	P
<i>Meeting</i>				✓			✓				...		M
<i>TotalDefects</i>	✓	✓	✓	✓		✓	✓	✓		✓	...	✓	$D = P + M$

Figure 11: **A Defect Detection Model.** During preparation, reviewer R_i finds p_i defects. Each ✓ mark in row R_i indicates one of these defects. Each X mark indicates a defect that was found by R_i , but was suppressed at the meeting. The row labeled *Preparation* contains one ✓ mark for each defect that found by at least one reviewer during preparation and the M defects found at the meeting are indicated by a ✓ mark in the row labeled *Meeting*. Finally, the row labelled *TotalDefects* contains a ✓ mark for each of the D defects that are known to the artifact’s author at the end of the inspection.

4. the overlap in preparation defects: $\frac{\text{common}}{P}$, and

5. meeting gains – M .

Our goal in this analysis is to determine whether treatments with similar inspection performances show significant differences in these lower-level activities. For example, if one treatment has higher preparation defect densities ($\frac{P}{NCSL}$) than another, but the same observed defect densities, then we’d expect to find worse performance in some other subtasks, (e.g., lower meeting gain densities ($\frac{M}{NCSL}$)).

4.2 Large Teams vs. Small Teams

As long as additional reviewers find some new defects and don’t negatively affect collection meeting performance, we would expect larger teams to find more defects than smaller teams, yet we found that 1sX2p inspections performed the same as 1sX4p inspections. Somewhere the supposed advantage of having more reviewers didn’t materialize, so we investigated how team size affected both preparation and meeting performance.

First, we investigated two aspects of preparation performance: individual preparation and amount of overlap in the defects found by the reviewers.

Figure12(b) shows the number of defects per NCSL found in preparation by reviewers in 1sX2p and 1sX4p inspections, $\frac{p_i}{NCSL}$. There was no difference between the two treatments.

Then we examined the amount of overlap in the reviewer’s defect reports. This is the number of defects found

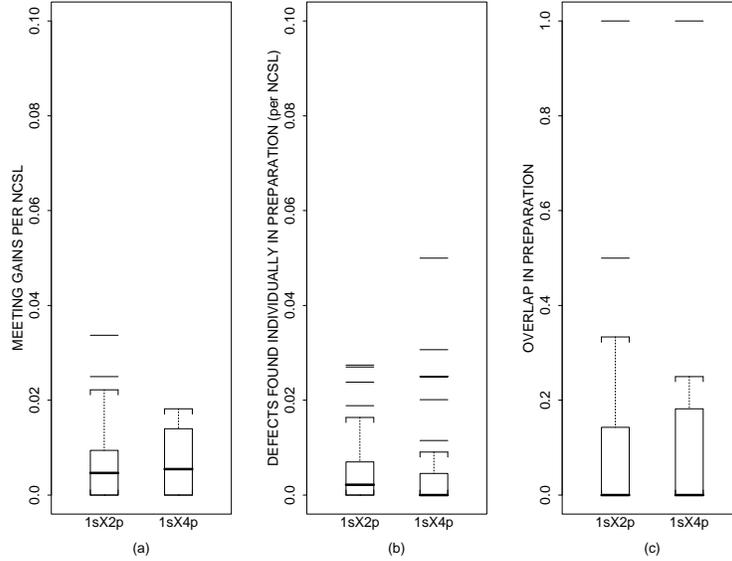


Figure 12: **Effect of Team Size on Inspection Subtasks.** (a) meeting gains, (b) mean individual preparation performance, and (c) overlap of defects found in preparation.

by more than one reviewer divided by the total number found in preparation, $\frac{\text{common}}{P}$. There was no difference in overlap between 1sX2p and 1sX4p inspections and both distributions had a median of 0. (See Figure 12(c)).

Next we examined two aspects of meeting performance: defect suppression and meeting gains. We found that defect suppression rates were higher for 1sX4p than for 1sX2p inspections. (See Figure 6).

Finally, Figure 12(a)) shows that there is no difference in the meeting gains per NCSL, $\frac{M}{NCSL}$, for 1sX2p and 1sX4p inspections.

One interpretation of these results is that larger teams don't improve inspection performance because meeting gains do not increase as the number of reviewers increases, and because larger teams may suppress a large number of (possibly true?) defects.

4.3 One Large Team vs. Two Small Teams

Another recommendation that has appeared in the literature is to substitute several small (1- or 2-person) teams for one larger team. This approach should be more effective if the combined defect detection of the smaller teams is greater than that of the single larger team, and if the small teams don't significantly duplicate each other's efforts.

Nevertheless we saw that 2sX2p (2sX1p) inspections did not perform better than 1sX4p (1sX2p) inspections.

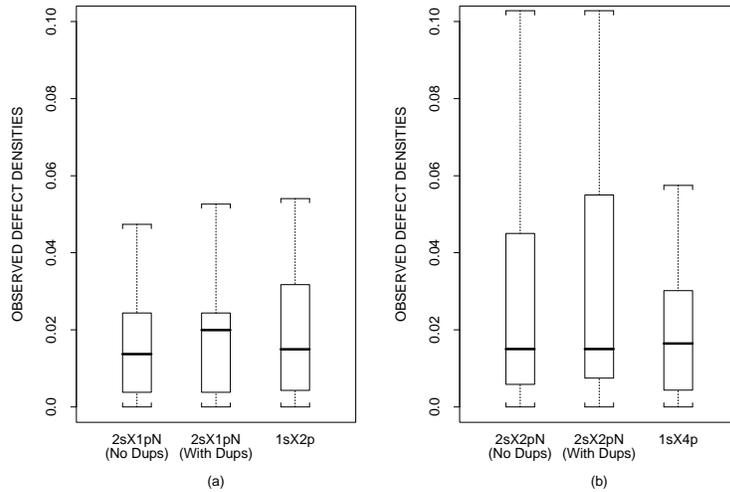


Figure 13: **The Effect of Splitting One Large Team.** This figure compares the distribution of observed defect densities of 2-session inspections before (Dups) and after (No Dups) accounting for overlap with that of 1-session inspections.

To investigate this result, we extended our defect discovery model to include inspections with 2 sessions.

To evaluate this explanation we compared the distribution of observed defect densities for 1-session inspections with the sum of the defect densities found in both sessions of the 2-session inspections (defects found by both teams are counted twice). We found that combined defect densities of 2sX1p (2sX2p) inspections are not greater than the defect densities of 1sX1p (1sX2p) inspections. We also found that there was effectively no overlap in the defects found by the two sessions (see Figure 13).

This data suggests that for our experimental setting overlap among reviewers is a rare occurrence, but that splitting teams did not improve performance because the two smaller teams found no more defects than the one larger team.

4.4 Repair vs. No Repair

Repairing defects between sessions of a multiple session inspection should result in greater defect detection than not repairing if (1) the teams in the with-repair inspections perform as well as the teams in the without-repair inspections, (2) there are significantly more defects than one team can find alone, and (3) the teams doing without-repair inspection find many of the same defects.

However, we saw that during the period in which with-repair inspections were conducted they did not perform

Defect ID	1	2	3	4	5	6	7	8	9	10	...	N	Number Found
R_{11}	✓		✓							✓	...		P_{11}
⋮													⋮
R_{1m}		✓	✓		X			✓			...		P_{1m}
<i>Preparation</i> ₁	✓	✓	✓					✓		✓	...		P_1
<i>Meeting</i> ₁				✓			✓				...		M_1
<i>Defects</i> ₁	✓	✓	✓	✓			✓	✓		✓	...		$D_1 = P_1 + M_1$
Defect ID	1	2	3	4	5	6	7	8	9	10	...	N	
R_{21}	-	-	-	-	✓		-	-		-	...	✓	p_{21}
⋮													⋮
R_{2m}	-	-	-	-		✓	-	-		-	...	✓	p_{2m}
<i>Preparation</i> ₂	-	-	-	-	✓	✓	-	-		-	...	✓	P_2
<i>Meeting</i> ₂	-	-	-	-			-	-	✓	-	...		M_2
<i>Defects</i> ₂	-	-	-	-	✓	✓	-	-	✓	-	...	✓	$D_2 = P_2 + M_2$
<i>Defects</i> ₁	✓	✓	✓	✓			✓	✓		✓	...		D_1
<i>Defects</i> ₂	-	-	-	-	✓	✓	-	-	✓	-	...	✓	D_2
<i>Total Defects</i>	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	...	✓	D

Figure 14: **Repairing in Between Sessions.** The - indicates defects that have been fixed and are no longer visible in the second session.

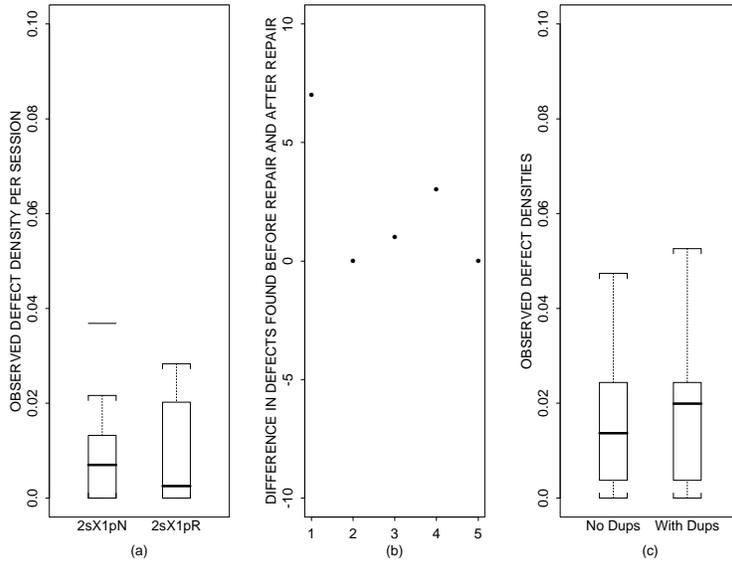


Figure 15: **Effect of Repairing In Between Sessions for 1-Reviewer Teams.** (a) comparing session performance with same team size, (b) drop-off in number of defects found, and (c) counting the duplicates for 2sX1pN inspections.

better than without-repair inspections. One or more of the assumptions may have been violated. To investigate this, we extended our inspection model to account for two sessions, with and without repair after the first session (See Figure 14).

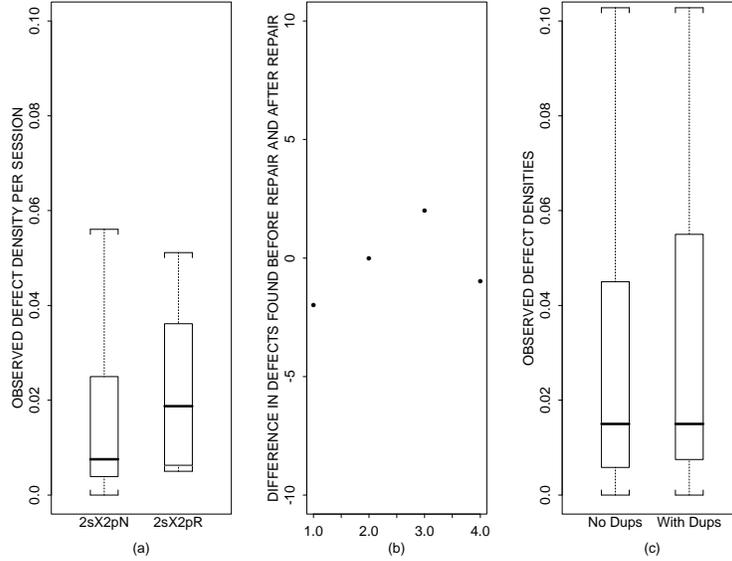


Figure 16: **Effect of Repairing In Between Sessions for 2-Reviewer Teams.** (a) comparing session performance with same team size, (b) drop-off in number of defects found, and (c) counting the duplicates for 2sX2pN inspections.

To test whether with-repair teams perform as well as without-repair teams we compared defect densities per session, D_1 and D_2 , of with-repair inspections with those of without-repair inspections. We found no differences in the performances (see Figures 15(a) and 16(a)), suggesting that the with-repair teams perform no differently than without-repair teams.

To test whether there are enough defects to warrant two inspection teams we compared the performance of with-repair teams inspecting the same unit. If the second team (inspecting after the repair) consistently found fewer defects than the first team, (i.e., $D_1 - D_2$ is significantly higher than 0), then the first team may have found most of the defects that can be found with current inspection techniques. If not, this suggests that there are more than enough defects to be found by two teams, and that on the average, one team is as good as the other. We found some drop-off defect density for the second team of 2sX1pR inspections (see Figure 15(b)), but none for the second team of 2sX2pR inspections (see Figure 16(b)).

To test whether overlap has a significant influence on without-repair inspections we first calculated the number of defects identified by the first team that were subsequently rediscovered by the second team. If we assume that an equal number of new defects would have been found had repair been done prior to the second inspection, then an approximation for the total number of defects that would have been found by the two sessions would be $D_1 + D_2$. We found that this approximate defect density was not different than defect density of the actual

without-repair inspections (see Figures 15(c) and 16(c)).

These results are based on a very small number of observations and should be viewed with considerable caution. Tentatively, it suggests that multiple sessions inspections will improve performance only when there is an excess of defects to be found, and that repairing defects in between multiple sessions may not improve the performance of a second inspection team.

5 Conclusions

We have run an 18-month experiment in which we applied different software inspection methods to all the code units produced during a professional software development. We assessed the methods by randomly assigning different team sizes, numbers of inspection sessions, author repair activities, and reviewers to each code unit.

Our results challenge certain long-held beliefs about the most cost-effective ways to conduct inspections and raise some questions about the feasibility of recently proposed methods.

In particular, two of our major findings are that:

- Although a significant amount of software inspection research has focused on making structural changes (team size, number of sessions, etc.) to the process, these changes had little or no effect in our experiment. Consequently, we believe that significant improvements to the inspection process will depend on the development of new defect detection techniques.
- The 2sX2pR treatment had an interval twice that of the other treatments. Although we were able to gather only four observations, the magnitude of this difference surprises us. Furthermore, it highlights the fact that although researchers frequently argue for changes to software development processes, we have no reliable methods for predicting the effect of these changes on development interval.

In the following Section we summarize our specific results and discuss their implications from points of view of both practitioners and researchers.

Individual Preparation. Our data indicate that about one-half of the issues reported during preparation turn out to be false positives, Approximately 35–40% pertain to nonfunctional style and maintenance issues. Finally, only 13% concern defects that will compromise the functionality of the delivered system.

For practitioners this suggests that a good deal of effort is currently being expended on issues that might better be handled by automated tools or standards.

For researchers this suggests that developing better defect detection techniques may be much more important than any of the organizational issues discussed in this article [19].

Meeting Gains. Only 30% of defects were meeting gains. One implication of this result is that it may be worthwhile to explore meeting-less inspections. For example, 2sX2pN inspections are about 33% more effective than 1sX4p inspections. Without a collection meeting 2sX2pN inspections would still be more effective, but might require less total effort and have a shorter interval.

These meeting gain rates are higher than those reported by Votta [25] (5%). Since meetings without meeting gains are a large, unnecessary expense, it's important for researchers to better understand this issue. Also, it is extremely important that contradictory findings be examined and resolved. Some possible explanations for this are (1) Votta's study focused on design inspections rather than code inspections, (2) the average team size for a design inspection is considerably larger than for code inspections (so more defects are found in preparation), or (3) design reviewers may prepare much more thoroughly since design defects are likely to be more damaging than code defects. We are currently conducting another experiment to help resolve these discrepancies.

Team Size. We found no difference in the interval or effectiveness of inspections of 2-, or 4-person teams. The effectiveness of 1-reviewer teams was poorer than both of the others.

For practitioners this suggests that reducing the default number of reviewers from 4 to 2 may significantly reduce effort without increasing interval or reducing effectiveness.

The implications of this result for researchers is unclear. We need to develop a better understanding of why 4-reviewer teams weren't more effective than 2-reviewer teams. Maybe better inspection techniques would have found more defects, maybe the code was relatively bug-free, or maybe problems with group interaction become more pronounced as team size grows. We will explore this issue further by tracking the system as it is tested and deployed in the field.

Multiple Sessions. We found that two, 2-person teams weren't more effective than 1, 2-person team. We found that two, 2-person (1-person) teams were not more effective than one, 4-person (2-person) team. We also

found that 2-session inspections without repair have the same interval as 1-session inspections.

In practice this indicates that 2-session inspections aren't worth their extra effort.

These results are significant for researchers as well. Multiple session methods such as active design reviews (ADR) and phased inspections (PI) rely on the assumption that several one person teams using specially developed defect detection techniques can be more effective than a single large team without special techniques. Some of our experimental treatments mimic the ADR and PI methods (without special defect detection techniques). This suggests that any improvement offered by these techniques will not come just from the structural organization of the inspection, but will depend heavily on the development of defect detection techniques.

Serializing Multiple Sessions. We found that repairing defects in between multiple sessions had no effect on defect detection rate, but in some cases increased interval dramatically.

In practice, we see no reason to repair defects between multiple sessions. Furthermore, some of the developers in our study felt that the 2-session-with-repair treatments caused the greatest disruption in their schedule. For example, they had to explicitly schedule their repairs although they would normally have used repair to fill slow work periods.

This result raises several research questions as well. In particular, why did one treatment have such a long interval? And why weren't we able to predict this effect?

This result also provides some information about the recently proposed phased inspection method. This method requires small teams each specially defect detection techniques to perform several inspections in serial, repairing defects between each session. Our data shows no improvement due solely to the presence of repair. Consequently, without special defect detection techniques the approach is unlikely to be effective.

6 Future Work

Our continuing work will focus on deepening our analysis in several areas. Some of the questions we will be addressing include:

- How much variation in the observed performance did our experimental design successfully control?
- How much variation in the observed performance can be explained by natural variation in factors outside our control like inspector skill, code quality and author skill?

- What factors outside of our experimental control affected inspection interval? For example, the number of inspections in which each reviewer was already participating, proximity to project deadlines, etc.

Finally, we feel it is important that others attempt to replicate our work, and we are preparing materials to facilitate this. Although we have rigorously defined our experiment and tried to remove the external threats to validity, it is only through replication that we can be sure all of them have been addressed.

Acknowledgments

We would like to recognize the efforts of the experimental participants – an excellent job is being done by all. Our special thanks to Nancy Staudenmayer for her many helpful comments on the experimental design. Our thanks to Dave Weiss and Mary Zajac who did much to ensure we had all the necessary resources and to Clive Loader and Scott VanderWiel for their valuable technical comments. Finally, Art Caso’s editing is greatly appreciated.

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A Capture-Recapture Methods

Capture-recapture (CRC) methods are sampling, resampling schemes for estimating the size of a population [18] – in our case the total number of defects in the artifact (which we denote by N). The idea is to compare the defect reports of several reviewers. Assuming reviewers are independent and that defects have identical detection probabilities, if several reviewers find many of the same defects then we conclude that most of the defects have been found. On the other hand, if every reviewer finds many defects which were not found by the other reviewers, we conclude that many undiscovered defects remain. Capture-recapture methods translate these intuitive ideas into statistical estimation procedures.

From the preparation, collection meeting, and author repair we gather enough information to support a large number of CRC methods [6]. Our choice of a specific capture-recapture method will depend on how well our specific application conforms to the assumptions underlying several available methods.

Three assumptions are made when deriving the simplest estimators: (A) reviewer performances are statistically independent, (B) all reviewers are equally effective at finding defects, and (C) all defects have the same probability of being found.

If assumption (A) is violated, it will not be possible to derive a reliable estimator. Assumption (A) may be violated because of collusion (reviewers working together, causing N to be underestimated) and/or specialization (reviewers looking for disjoint sets of defects, causing N to be overestimated). We will use a statistical test constructed by Steve Eick et al. [7] to establish whether or not assumption (A) holds for our data.

If assumption (B) holds, we can use a jackknife estimator for N . This allows us to ignore assumption (C), since it does not enter into the estimator’s derivation. The jackknife estimator for N of order k ($k \leq m$) has the form

$$\hat{N} = \max\{0, a_1 f_1 + \dots + a_k f_k\} + n \tag{1}$$

where m is the number of reviewers, n is the total number of defects found by all reviewers during their preparation, and f_j denotes the number of defects discovered by exactly j reviewers ($j = 0, \dots, m$). The constants a_1, \dots, a_k depend on m and k . Full details as well as a method for selecting k are given in Burnham and Overton [4].

If assumption (B) is violated, but assumption (C) holds, we can compute a maximum likelihood estimation,

\hat{N} , for N . This will be the value of X that maximizes the following equation:

$$\mathcal{L}_c(X) = \ln \binom{X}{n} + \sum_{j=1}^m n_j \ln(n_j) + \sum_{j=1}^m (X - n_j) \ln(X - n_j) - Xm \ln(X) \quad (2)$$

where n_j is the number of defects found by the j^{th} reviewer in his or her preparation.

When neither assumption (B) nor assumption (C) hold, then an estimator cannot always be derived. However, Scott Vander Wiel et al. [24] found that if the defects can be partitioned into a small number of groups, where the defects in each group have similar detection probabilities, then Equation 2 can be applied to each group separately and the results added together to calculate an estimate for N .

An analysis of our data indicates that assumption (A) holds, but assumptions (B) and (C) do not. However, the data can be partitioned as suggested by Vander Wiel. Therefore, we will use Equation 2 to estimate the size of each subpopulation and combine them to estimate the total population.

B Resolution Analysis

The simulation involves just two treatments, T_a and T_b , whose defect detection probabilities are p_a and p_b .

The simulation comprises three distinct steps:

1. **Creation of code units.** We create a number of code units with known size and defect density. The defect density is randomly drawn from a normal distribution with mean μ and standard deviation σ . The number of defects in the code, N , is just the defect density multiplied by the code size.
2. **Application of treatments.** We apply treatments T_a and T_b to different groups of code units. Each group contains sets of 5, 10, and 15 code units. The number of defects found, n_a , by applying T_a to a code unit containing N defects, is determined by a random draw from a Binomial distribution with parameters N and p_a (p_b when applying treatment T_b finds n_b defects).
3. **Comparison of results.** We use the Wilcoxon rank sum test [22] to determine the probability that the n_a 's are drawn from the same population as the n_b 's.⁹

This process is repeated a hundred times for each experimental setting. Even though the two treatments have different detection probabilities, under some conditions the test may fail to recognize the difference. Running the simulation in a wide variety of experimental settings helps us to determine when and how confidently we can say that two treatments are different.

We created 600 experimental settings consisting of 25 different combinations of means (53,67,80,93,107) and standard deviations (3,7,13,27,40) to generate defect densities, and 24 different pairs of p_a (.2, .4, .6, .8) and p_b ($p_b = p_a + .0, .025, .05, .075, .1, .15$).

Figure 17 shows some (108 out of 600 settings) of the simulation results. The x-axis shows the true difference between p_a and p_b and the y-axis shows the probability that the null hypothesis ($p_a = p_b$) will be rejected. Each combination of a symbol and a line segment represents the outcomes of 100 simulation runs of one experimental setting. The symbol indicates the median, and the line segment through the symbol spans the .25 through the .75 quantiles.

We define the experimental resolution as the value when more than 50% of the 100 outcomes have a significance

⁹Although the Wilcoxon rank sum test is not as powerful as a t distribution test, the Wilcoxon rank sum test does not require the n_a 's and n_b 's to be normally distributed – an assumption that is difficult to test with small samples of data.

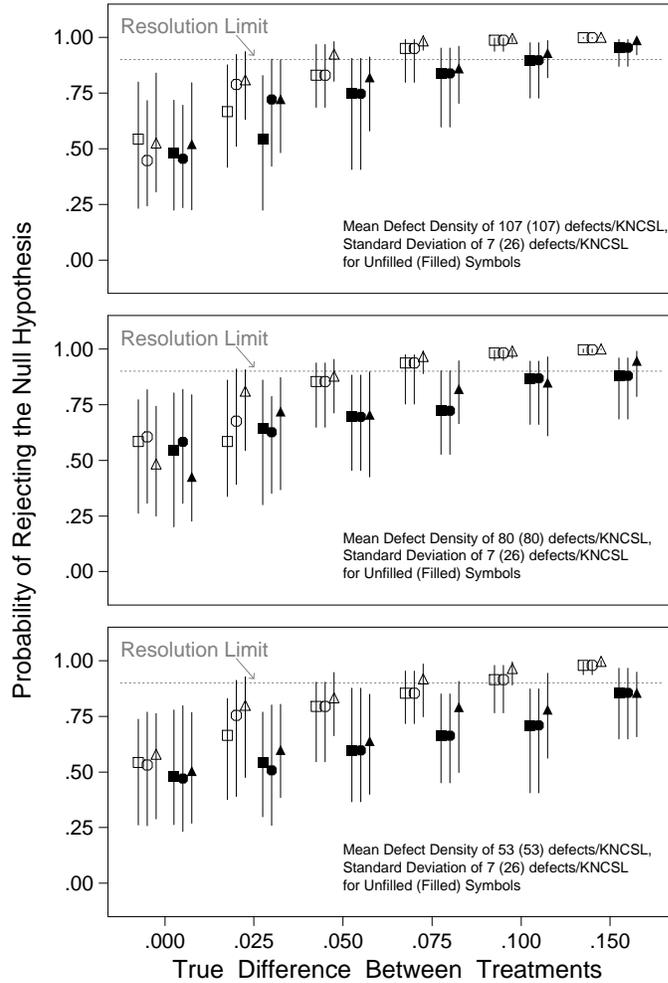


Figure 17: **Resolution of the Experiment.** This plot shows the results of applying treatments T_a and T_b to sets of 5, 10, or 15 code units (marked by the square, circle, and triangle). Each simulated unit has 300 NCSL and a mean defect density of 53, 80, or 107 defects per 1000 NCSL, with a standard deviation of 7 or 26 defects per 1000 NCSL. p_a is set to .6. The x-axis shows the true difference between p_a and p_b and the y-axis shows the probability that the null hypothesis (i.e., that all the treatments have the same effectiveness) will be rejected. Each combination of a symbol and a line segment represents the outcome of 100 simulation runs for one experimental setting. The symbol indicates the median and the line segment runs from the lower to the upper quartile. Symbols plotted above the dotted horizontal line in each panel indicate experimental situations where true differences in treatment effectiveness can be reliably detected. The simulation results indicate a resolution as fine as .05. The resolution does not become substantially finer as the number of observations increases; however, it does become finer as the standard deviation decreases.

greater than .9 (the symbol in Figure 17 lies *above* the resolution line), and the next smaller true difference value has the symbol with less than 50% of the 100 outcomes greater than .9 (the symbol in Figure 17 lies *below* the resolution line).

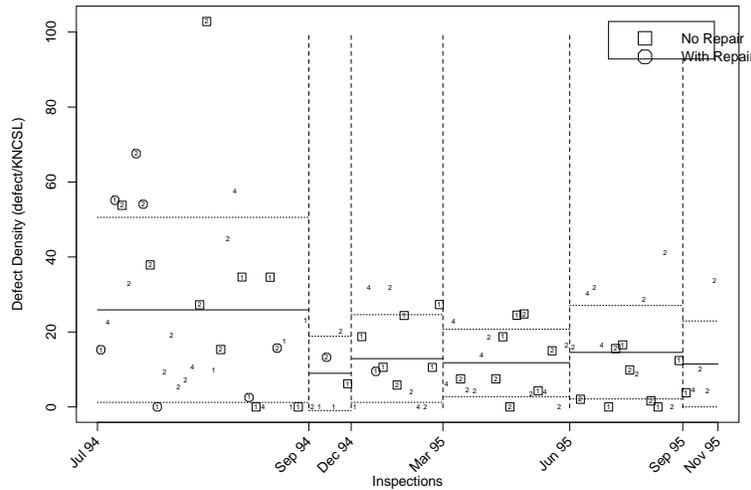


Figure 18: **Inspection Performance Over Time.** This is a time series plot showing the trends in observed defect densities of inspections as time passed. The vertical lines partition the plot into quarters. Within each quarter, the solid horizontal line marks the mean of that quarter’s distribution. The dashed lines mark one standard deviation above and below the mean. The treatment used by the inspection is encoded in the plotting symbol. The plotted numbers represent the team size of the inspection. The open ones are 1-session inspections, the circled ones are 2-session inspections with repair and the square ones are 2-session inspections with no repair.

C Inspection Performance over Time

C.1 Chronological Overview

Initially, the experiment involved seven treatments. At the beginning of 1995, we evaluated the existing results and discussed them with the project’s management. Although we would have preferred to gather more data, it would have been risky for the project to continue performing expensive or ineffective treatments. Therefore, we discontinued three treatments: 1sX1p, 2sX1pR, and 2sX2pR.

The 1sX1p treatment was the least effective, while the two with-repair treatments (2sX1pR and 2sX2pR) were no more effective than the without-repair treatments. In addition, the 2sX2pR treatment was, by far, the most expensive treatment in terms of interval. Figure 18 confirms that the last instances of these discontinued treatments were held in the first quarter of 1995.

Our primary concern is that discontinuing treatments may compromise the experiment’s internal validity (i.e., factors that affected all treatments early in the experiment, will affect only the remaining treatments later in the experiment). Consequently, we must be careful when we compare treatments that were discontinued with those

that were not.

Figures 18 and `refinttimeseq` show inspection effectiveness and interval over time, with observations sorted according to the time at which the code unit became available for inspection.

C.2 Analysis of Inspection Performance Over Time

The data presented in Figure 18 suggests that there are two distinct performance distributions. That is, that the first quarter (July - September, 1994) – during which about one-third of the inspections occurred – has a significantly higher mean and variance than the remaining quarters (October, 1994 – December, 1995).

One reason for this may be that the end of the first quarter coincides with the system’s first integration build. Our records show that with the compiler’s front end in place, the developers were able to do more thorough unit testing for the back end code than they did for front end code itself.

Other factors may be that the reviewers had become more familiar with the programming language as the project progressed, that the requirements for the front-end (language definition, parsing, and intermediate code generation) was more prone to misinterpretation than the final code generation and optimization

In particular, this suggests to us that had we continued using the `2sX2pR` treatment its effectiveness would have dropped in a manner consistent with the other treatments.

C.3 Analysis of Inspection Interval Over Time

Figure 20 is a time series plot showing inspection interval as project progressed. We see that the mean inspection interval did not vary significantly throughout the project, although there is a gradual increase as the project nears completion.

Although there were only four `2sX2pR` inspections, the stability of the interval for the other treatments suggests that had we continued the treatment, its interval would not have changed significantly.

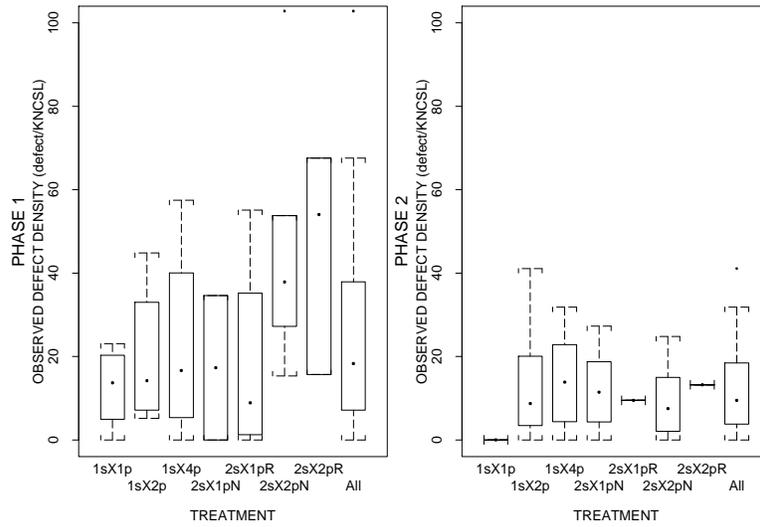


Figure 19: **Observed Defect Density by Treatment and Phase.** These two plots show the observed defect density for each inspection treatment during the first and second phase of the project. Across all inspections, the median observed defect density was 18 defects per KNCSL for the first phase and 10 defects per KNCSL for the second phase.

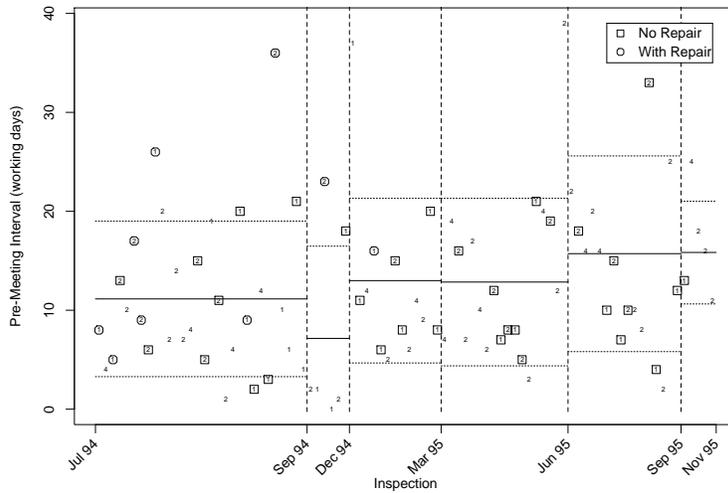


Figure 20: **Inspection Intervals Over Time.** This is a time series plot showing the trends in inspection intervals as time passed.