



Balancing Fairness and Profit in Rideshare

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Background

Dispatch policies are algorithms that match drivers with riders for rideshare companies

Dispatch policies use Markov Decision Policies, which model matching riders and drivers as actions that change the "state" of the rideshare system

State Space: Rider and Driver Locations

Action Space: All combinations of riders, drivers
Dispatch policies determine action that maximizes objective function

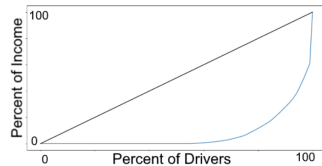


There are many combinations of drivers and riders, so dispatch policies need to quickly sort through the combinations and find the best ones
Image taken from Xu et al. paper in KDD 2018

Fairness in Rideshare

Dispatch policies typically optimize for profit, which causes inequality for both drivers and riders

Driver Inequality: Unequal pay amongst drivers
Quantify using a Lorenz Curve

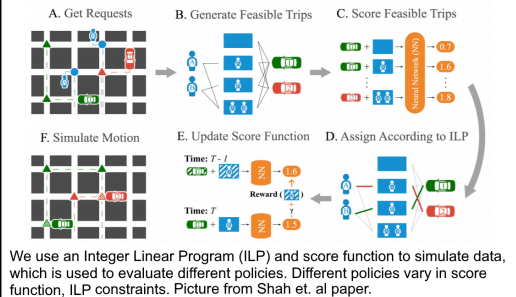


The closer the curve is to a straight line, the more even the income distro is.

Passenger Inequality: Passengers from certain areas get picked up less

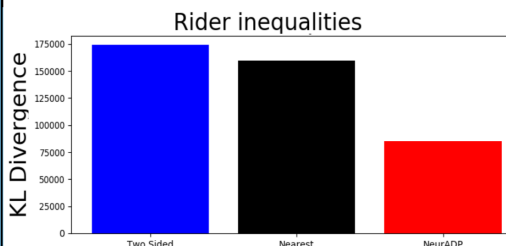
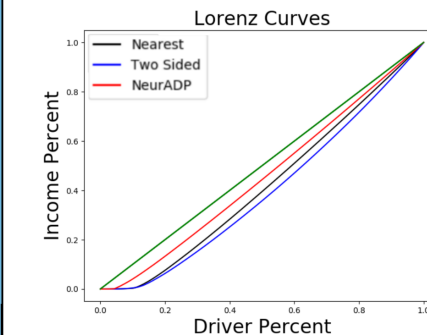
Quantify using difference in distribution between which drivers request rides, and which get picked up

Rideshare Simulator

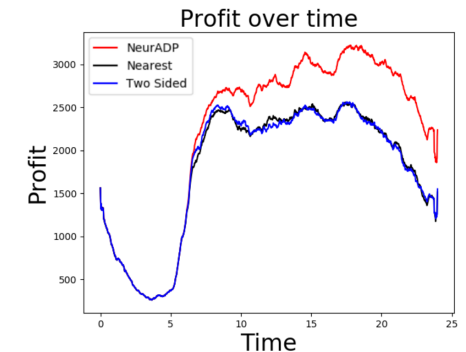


Experiments

Run preliminary experiments comparing existing dispatch policies on fairness and profit



Experiments



We see the NeurADP policy performs best in profit and inequality, While two sided performs worst in all three

Future Directions

We have baseline performance from policies
So we know what to compare our policies to

Next step is to find policies that outperform in fairness using different objective functions, such as entropy

Another method is to enforce fairness constraints when matching in the ILP

References

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